AMD Generic Encapsulated Software Architecture (AGESA™) Interface Specification for Arch2008
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# AGESA™ Software Fundamentals

## Chapter 1 Introduction

<table>
<thead>
<tr>
<th>Section</th>
<th>Title</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.1</td>
<td>Goals</td>
</tr>
<tr>
<td>1.2</td>
<td>Audience</td>
</tr>
<tr>
<td>1.3</td>
<td>Related Documents</td>
</tr>
<tr>
<td>1.4</td>
<td>Terminology</td>
</tr>
</tbody>
</table>

## Chapter 2 Logistical Matters

<table>
<thead>
<tr>
<th>Section</th>
<th>Title</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.1</td>
<td>Version Numbering</td>
</tr>
<tr>
<td>2.2</td>
<td>Release Package</td>
</tr>
<tr>
<td>2.3</td>
<td>File Naming Convention</td>
</tr>
<tr>
<td>2.4</td>
<td>File headers</td>
</tr>
<tr>
<td>2.5</td>
<td>Procedure Naming Convention</td>
</tr>
<tr>
<td>2.6</td>
<td>Internal Documentation</td>
</tr>
<tr>
<td>2.6.1</td>
<td>Installing the Doxygen and Dot Tools</td>
</tr>
<tr>
<td>2.6.2</td>
<td>Building the HTML files</td>
</tr>
</tbody>
</table>

## Chapter 3 Design Concepts

<table>
<thead>
<tr>
<th>Section</th>
<th>Title</th>
</tr>
</thead>
<tbody>
<tr>
<td>3.1</td>
<td>Interface Design Theory</td>
</tr>
<tr>
<td>3.1.1</td>
<td>Required versus Optional Parameters</td>
</tr>
<tr>
<td>3.1.2</td>
<td>Call Mechanics</td>
</tr>
<tr>
<td>3.1.3</td>
<td>Error Reporting</td>
</tr>
<tr>
<td>3.2</td>
<td>Build Design Theory</td>
</tr>
<tr>
<td>3.2.1</td>
<td>Control Files</td>
</tr>
<tr>
<td>3.2.2</td>
<td>Build Styles</td>
</tr>
<tr>
<td>3.3</td>
<td>Binary Image Design</td>
</tr>
<tr>
<td>3.3.1</td>
<td>Binary Block Structure</td>
</tr>
<tr>
<td>3.3.2</td>
<td>Execution Environment Expectations</td>
</tr>
<tr>
<td>3.3.3</td>
<td>Standard Header</td>
</tr>
<tr>
<td>3.4</td>
<td>Binary Image Implementation</td>
</tr>
<tr>
<td>3.4.1</td>
<td>Binary Header</td>
</tr>
<tr>
<td>3.4.2</td>
<td>Module Header</td>
</tr>
</tbody>
</table>
3.5 Integrated Debug Services ......................................................... 37

Chapter 4 Operational Overview ................................................... 38

4.1 AGESA™ Core Software ......................................................... 38
4.2 Operational Warnings .............................................................. 41
4.3 Reported Errors ................................................................. 41
  4.3.1 Returned Status Codes ....................................................... 41
  4.3.2 Error Logging ................................................................. 42
Porting Guide for Binary Module

Chapter 5  Binary Module Porting ................................................................. 43
  5.1  Overview ....................................................................................... 43
  5.2  Terms and Definitions ................................................................. 43
  5.3  Theory of Operation ................................................................. 43
    5.3.1  Calling an AGESA™ Software Procedure ......................... 44
    5.3.2  Call-Out Operation ............................................................. 45

Chapter 6  The Binary Module API ...................................................... 47
  6.1  Making Calls to Core Entry Points ........................................... 47
    AmdAgesaDispatcher ................................................................. 48
  6.2  Handling Core Call-Out Procedures ......................................... 49
    Host BIOS Router Procedure .................................................. 50
Porting Guide for UEFI

Chapter 7  UEFI Porting .......................................................... 52
  7.1  Overview ................................................................. 52
  7.2  Tool Set .................................................................. 53
  7.3  Configuration Options ............................................ 53
    7.3.1  Build Time Options ........................................... 53
    7.3.2  Run Time Options ............................................... 53
  7.4  Build Environment Installation ................................ 54

Chapter 8  The SEC Phase ..................................................... 55

Chapter 9  The PEI Drivers .................................................... 56
  9.1  AmdProcessorInitPeim ............................................. 57
      AmdInitResetPPI ...................................................... 58
      AmdInitEarlyPPI .................................................... 59
      AmdInitPostPPI ........................................................ 60
      AmdMemoryInfoHob ............................................... 61
  9.2  AmdInitPostPeim ...................................................... 63
      MemoryInitPPI ........................................................ 64
  9.3  AmdResetManager .................................................... 65

Chapter 10 The DXE Driver ................................................. 66
  AagesaDxeProtocol ...................................................... 67
  AmdGpuVgaControlDxe ................................................. 68

Chapter 11  UEFI Porting Check List ........................................ 69
  11.1  Example Files ........................................................ 69
  11.2  Build Control Files ............................................... 69
  11.3  Environment Variables ........................................... 70
  11.4  UEFI Check List ..................................................... 70
API Specification

Chapter 12 Introduction ................................................................. 71
  12.1 Platform solutions .......................................................... 71
  12.2 Build Methods ............................................................... 71
  12.3 Build Customization ....................................................... 71

Chapter 13 Service Procedures ..................................................... 73
  13.1 Stack Procedures ............................................................. 73
    AMD_RESET_ENABLEMENT .................................................. 74
    AMD_CAR_SUPPORT (Deprecated) .......................................... 75
    AMD_ENABLE_UEFI_STACK ................................................ 76
    AMD_DISABLE_UEFI_STACK .............................................. 79
  13.2 General Service Procedures ............................................. 81
    AmdCreateStruct .......................................................... 81
    AmdGet2DDataEye .......................................................... 84
    AmdGetApicId ............................................................. 86
    AmdGetAvailableExeCacheSize ......................................... 88
    AmdGetPciAddress ....................................................... 89
    AmdIdentifyCore .......................................................... 91
    AmdIdentifyDimm ........................................................ 93
    AmdAddMmioMapping ..................................................... 95
    AmdReadEventLog ....................................................... 97
    AmdReleaseStruct ........................................................ 99

Chapter 14 Entry Point Procedures .............................................. 100
  14.1 Recovery Branch Functions ............................................. 100
    AmdInitReset ............................................................. 101
  14.2 Boot Branch Functions ................................................... 105
    AmdInitEarly ............................................................. 105
    AmdInitPost ............................................................. 115
    AmdInitEnv .............................................................. 128
    AmdInitMid .............................................................. 135
    AmdInitLate ............................................................. 137
    AmdInitRtb .............................................................. 141
  14.3 Resume Branch Procedures .............................................. 144
    AmdInitResume .......................................................... 144
    AmdS3LateRestore ..................................................... 146
    AmdS3FinalRestore ..................................................... 148
Chapter 15  Call-Out Procedures ................................................................. 150

15.1 Required Call-Out Procedures ...................................................... 150
   AgesaAllocateBuffer ................................................................. 151
   AgesaDeallocateBuffer ............................................................ 153
   AgesaDoReset ........................................................................... 155
   AgesaLocateBuffer .................................................................... 157
   AgesaReadSpd ........................................................................... 159
   AgesaRunFcnOnAp .................................................................... 161
   AgesaRunFcnOnAllAps ............................................................... 161
   AmdLateRunApTask ................................................................... 163
   AgesaPcieSlotResetControl ......................................................... 164
   AgesaWaitForAllApsFinished ....................................................... 166
   AgesaIdleAnAp .......................................................................... 167

15.2 Optional Call-Out Procedures ...................................................... 168
   AgesaGetIdsData ........................................................................ 168
   AgesaHeapRebase ....................................................................... 170
   AgesaHookBeforeDramInit ......................................................... 172
   AgesaHookBeforeDQSTraining .................................................... 173
   AgesaExternal2dTrainVrefChange .............................................. 174
   AgesaHookBeforeExitSelfRefresh ............................................. 175
   AgesaGetVbiosImage .................................................................. 176
   AgesaFchOemCallout .................................................................. 177
   AgesaExternalVoltageAdjust ....................................................... 178
   AgesaGnbOemCallout .................................................................. 180

Chapter 16  Customizing Platforms ..................................................... 181

16.1 Build Options ............................................................................. 181

16.2 Build Configuration Elements .................................................... 186
   16.2.1 Platform Descriptive Elements ......................................... 187
      16.2.1.1 Voltage Regulation Module Elements ...................... 187
   16.2.2 System Descriptive Elements ............................................ 189
   16.2.3 Software Table Elements .................................................. 190
   16.2.4 Processor and General Elements ....................................... 191
   16.2.5 Memory Elements ............................................................ 196
      16.2.5.1 Memory Configuration Elements ......................... 196
      16.2.5.2 Memory Operations Elements ............................... 202
   16.2.6 Thermal and Power Control Elements .............................. 208
   16.2.7 HD Audio Elements .......................................................... 209
      16.2.7.1 Analog HD Audio .................................................. 209
16.2.7.2 Digital HD Audio .................................................................210
16.2.8 Graphics and PCIe® Elements ........................................211
16.2.9 FCH Elements .................................................................217

16.3 Customizing the Environment — Library Functions ......................222
   LibAmdCpuIdRead ...............................................................223
   LibAmdIoRead .................................................................224
   LibAmdIoWrite .................................................................224
   LibAmdLocateImage ...........................................................225
   LibAmdMemCopy ...............................................................226
   LibAmdMemFill .................................................................226
   LibAmdMemRead ...............................................................227
   LibAmdMemWrite .............................................................227
   LibAmdMsrRead ...............................................................228
   LibAmdMsrWrite ..............................................................228
   LibAmdPciRead ...............................................................229
   LibAmdPciWrite ..............................................................229
Integrated Debug Services (IDS)

Chapter 17  
17.1 Goals .............................................231  
17.2 Capabilities ...................................231  
17.3 Host Environment ...............................232  
17.4 Installation and Configuration ...............233  

Chapter 18  
18.1 IDS Macro .....................................235  
AGESA_TESTPOINT ..................................236  
STOP_HERE ........................................237  
ASSERT ...........................................238  
IDS_ERROR_TRAP ..................................239  
IDS_OPTION_HOOK ................................240  
IDS_SKIP_HOOK ...................................241  
IDS_HDT_CONSOLE ................................242  
CONSOLE .........................................243  
IDS_HDT_CONSOLE_INIT .........................244  
IDS_HDT_CONSOLE_EXIT .........................245  
IDS_PERF_TIMESTAMP ............................246  
IDS_PERF_ANALYSE ................................247  
IDS_EXCEPTION_TRAP ..............................248  

Chapter 19  
19.1 IDS Build Switches ............................249  
19.2 UI Interface Controls .........................250  
19.2.1 Configuration Controls .................250  
19.2.1.1 Processor Core Controls ............250  
19.2.1.2 Memory Cache & ECC Controls ......252  
19.2.2 HDT Tracing Controls ....................255  
19.2.3 Performance Analysis Controls ........255  
19.3 Build Switch Hierarchy .....................255  

Chapter 20  
20.1 Check List ....................................257  
20.2 Example ......................................257  
20.3 Debugging Using IDS .......................258  

Chapter 21  
HDT Console .......................................260
21.1 Starting an HDT Console debug session .................................................260
21.2 Available Scripts ...............................................................................261
Appendices

Appendix A  Family Specific Details .........................................................263
A.1 Family 15h Models 30h-3Fh .....................................................263
   A.1.1 Call Entries & parameters .................................................263
A.2 Family 15h Models 60h-6Fh .....................................................264
   A.2.1 Call Entries & parameters .................................................264
   A.2.2 Configuration elements ..................................................268
      A.2.2.1 Memory Elements ......................................................268
      A.2.2.2 Thermal and Power Control Elements ......................271
      A.2.2.3 HD Audio Elements ...............................................273
      A.2.2.4 Graphics and PCIe® Elements .......................................274
         A.2.2.4.1 High Speed HDMI Controls ...................................275
A.3 Family 16h, Models 30h - 3Fh ..................................................276
   A.3.1 Call Entries & parameters .................................................276
   A.3.2 Configuration elements ..................................................276
      A.3.2.1 Thermal and Power Control Elements ......................276
         A.3.2.1.1 Elements for DcTDP_V2.0 .............................278
      A.3.2.2 Graphics and PCIe® Elements .......................................280
Appendix B  Tools .............................................................................282
B.1 BINUTIL2 .................................................................................282
Appendix C  Logged Error Messages ......................................................283
C.1 AGESA_SUCCESS Class ............................................................283
C.2 AGESA_BOUNDS_CHK Class .....................................................284
C.3 AGESA_ALERT Class ...............................................................285
C.4 AGESA_WARNING Class ...........................................................285
C.5 AGESA_ERROR Class ...............................................................288
C.6 AGESA_CRITICAL Class ...........................................................294
C.7 AGESA_FATAL Class ...............................................................294
Appendix D  Memory Details ...............................................................297
D.1 Modifying or Correcting SPD values .............................................297
D.2 Specialized Platform Files .........................................................297
MemAGetPsCfgRHy2 ................................................. 298
MemAGetPsCfgRHy3 ................................................. 298

D.3 Advanced DQS Training ........................................... 300

D.4 On-Line Spares ................................................. 300

D.5 Platform Specific Override ................................... 300

D.5.1 Expert Overrides .............................................. 300

MOTHER_BOARD LAYERS ............................................. 301
MEMCLK_DIS_MAP .................................................. 302
ON_DIMM_THERMAL_CONTROL ..................................... 304
CKE_TRI_MAP ..................................................... 305
ODT_TRI_MAP ..................................................... 306
CS_TRI_MAP ..................................................... 307
NUMBER_OF_DIMMS_SUPPORTED ................................... 308
NUMBER_OF_SOLDERED_DOWN_DIMMS_SUPPORTED .................. 309
NUMBER_OF_CHIP_SELECTS_SUPPORTED ............................ 310
NUMBER_OF_CHANNELS_SUPPORTED ................................ 311
OVERRIDE_DDR_BUS_SPEED ......................................... 312
DRAM_TECHNOLOGY ................................................. 313
WRITE_LEVELING_SEED ............................................. 314
HW_RXEN_SEED ................................................... 315
NO_LRDIMM_CS67_ROUTING ......................................... 316
SOLDERED_DOWN_SODIMM_TYPE .................................... 317
MIN_RD_WR_DATAEYE_WIDTH ....................................... 318
CPU_FAMILY_TO_OVERRIDE ......................................... 319

D.5.2 Conditional Overrides ........................................ 320

D.5.2.1 Condition and Test Macros ................................. 320
CONDITION_AND .................................................. 321
COND_LOC ..................................................... 322
COND_SPD ..................................................... 323

D.5.2.2 Conditional Action Macros ................................. 323
ACTION_ODT ..................................................... 324
ACTION_ADDRTMG ................................................ 325
ACTION_ODCCTRL ................................................ 326
ACTION_SLEWRATE ............................................... 327
ACTION_SPEEDLIMIT ............................................. 328

D.5.3 Table Overrides ................................................ 328

D.5.3.1 Configuration Macros ..................................... 328
TBLDRV_CONFIG_TO_OVERRIDE .................................... 329
TBLDRV_SPEEDLIMIT_CONFIG_TO_OVERRIDE ..................... 331
TBLDRV_RC2IBT_CONFIG_TO_OVERRIDE ............................ 332

D.5.3.2 Override Macros ............................................ 334
Appendix E  Graphics Northbridge Details ................................................. 348

E.1  PCIe® Port Descriptor List ....................................................... 348
E.2  DDI Link Descriptor List ......................................................... 352
E.3  PCIe® Engine Data ................................................................. 354
E.4  IOMMU Exclusion Range Descriptor ......................................... 355
E.5  ACPI ASL Library ................................................................. 355
    E.5.1  Optional ACPI Callout Method ........................................ 362
    E.5.2  AWAK and APTS Methods .............................................. 363
List of Figures

Figure 2.1: Package Directory Structure ....................................................... 24
Figure 3.2: Interface Call Flow ................................................................. 28
Figure 3.3: Build Design Diagram ............................................................... 30
Figure 3.4: Binary Image Layout ................................................................. 32
Figure 4.5: General Boot Time Line ............................................................ 38
Figure 4.6: AGESA Boot Time Call Points .................................................... 40
Figure 5.7: Funneling Overview ................................................................. 44
Figure 5.8: Making a ROM image Call ......................................................... 45
Figure 5.9: Handling a Call-Out ................................................................. 46
Figure 8.1: Overview of AMD SEC components .......................................... 55
Figure 9.1: Overview of AMD PEI module interactions .................................. 56
Figure 10.1: Overview of AMD DXE driver interaction ................................... 66
Figure 17.2: IDS overview ........................................................................ 233
Revision History

Note: The latest version of the document is intended to describe the interface as it is implemented for the currently shipping processor(s). Previous generations of the spec will best describe the interface for previous generations of processors.

<table>
<thead>
<tr>
<th>Date</th>
<th>Revision</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
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<td></td>
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<td>DCR462687: Support for custom VDDIO</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• added “CustomVddioSupport” on page 267,</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• added “BLDCFG_CUSTOM_VDDIO_VOLTAGE” on page 270</td>
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<tr>
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<td>DCR462761: Add Memory Fatal Error Code</td>
</tr>
<tr>
<td></td>
<td></td>
<td>MEM_ERROR_VDDPVDDR_UNSUPPORTED</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• updated “AGESA_ERROR Class” on page 288</td>
</tr>
<tr>
<td></td>
<td></td>
<td>DCR439310: New Agesa call out functions</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• added “AllAPs” on page 162,</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• added “AgesaRunFcnOnAllAps” on page 161,</td>
</tr>
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<td></td>
<td>DCR450871: Add - BLDCFG_MEMORY_ENABLE_BANK_SWAP_ONLY</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• added “EnableBankSwapOnly” on page 266,</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• added “BLDCFG_MEMORY_ENABLE_BANK_SWAP_ONLY” on page 268</td>
</tr>
</tbody>
</table>
### DCR462007 AGESA GNB interface changes
- added “PkgPwrLimitAC” on page 265,
- added “BLDCFG_PPT_LIMIT_AC” on page 271,
- added “PkgPwrLimitDC” on page 265,
- added “BLDCFG_PPT_LIMIT_DC” on page 271
- added “BLDCFG_VRM_GFX_CURRENT_LIMIT” on page 187,
- added “BLDCFG_VRM_GFX_LOW_POWER_THRESHOLD” on page 187,
- added “BLDCFG_VRM_GFX_SLEW_RATE” on page 188,
- added “BLDCFG_VRM_GFX_HIGH_SPEED_ENABLE” on page 188,
- added “BLDCFG_VRM_GFX_MAXIMUM_CURRENT_LIMIT” on page 188,
- added “BLDCFG_VRM_GFX_SVI_OCP_LEVEL” on page 189,
- updated “BLDCFG_BATTERY_BOOST_TUNE” on page 272,
- added “BLDCFG_STAPM_SCALAR” on page 272,
- added “BLDCFG_STAPM_TIME_CONSTANT” on page 272,
- updated “BLDCFG_BATTERY_BOOST_TUNE” on page 272,
- added “BLDCFG_SYSTEM_CONFIGURATION” on page 273,
- Added “Dynamic Power and Thermal Configuration Interface - Function C” on page 361,
- updated “PCIe® Port Descriptor List” on page 348,
- added “BLDCFG_DP_FIXED_VOLT_SWING” on page 216,
- added “BLDCFG_EDP_V1_4_VS_MODE” on page 274
- Moved controls to family specific appendix:
  - BLDCFG_DOCKED_TDP_HEADROOM
  - BLDCFG_TDP_AC_DOCKED
  - BLDCFG_TDP_DC_DOCKED
  - BLDCFG_TDP_AC_UNDOCKED
  - BLDCFG_TDP_DC_UNDOCKED
  - BLDCFG_STAPM_EN_AC_DOCKED
  - BLDCFG_STAPM_EN_DC_DOCKED
  - BLDCFG_STAPM_EN_AC_UNDOCKED
  - BLDCFG_STAPM_EN_DC_UNDOCKED
  - BLDCFG_STAPM_POWER_AC_DOCKED
  - BLDCFG_STAPM_POWER_DC_DOCKED
  - BLDCFG_STAPM_POWER_AC_UNDOCKED
  - BLDCFG_STAPM_POWER_DC_UNDOCKED
  - BLDCFG_LVDS_MISC_VSYNC_ACTIVE_LOW
  - BLDCFG_LVDS_MISC_HSYNC_ACTIVE_LOW
  - BLDCFG_NUM_GFX_CORES_ENABLED

### DCR460803 Add BLDCFG_GNB_AZ_SSID
### DCR457447 Add BLDCFG_CODEC_VERB_TABLE
- added parameters to “\} PLATFORM_CONFIGURATION;\}” on page 106,
- added “BLDCFG_CODEC_VERB_TABLE” on page 273,
- added “BLDCFG_GNB_AZ_SSID” on page 274
<table>
<thead>
<tr>
<th>Date</th>
<th>Version</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>July 2014</td>
<td>v3.00</td>
<td>Initial public release. Updated for the Family 16h Model 30-3Fh processor and Family 15h Model 30-3Fh processor.</td>
</tr>
</tbody>
</table>

- **R453240**: Add BLDCFG_THERMCTL_LIMIT and drop BLDCFG_HTC_TEMPERATURE_LIMIT
  - added “BLDCFG_THERMCTL_LIMIT” on page 271
  - “ThermCtlLimit” on page 264
  - Moved HTC & LHTC controls to family specific appendix:
    - “BLDCFG_HTC_TEMPERATURE_LIMIT” on page 277
    - “BLDCFG_LHTC_TEMPERATURE_LIMIT” on page 277

- **DCR444573**: Arch2008: Add interface option for users to specific Memory Power Policy
  - Added “MemoryPowerPolicy” on page 264
  - “BLDCFG_MEMORY_POWER_POLICY_MODE” on page 268

- **DCR435568**: Deprecate BLDCFG_BATTERY_BOOST_EN
  - Moved option to Family specific appendix:
    “BLDCFG_BATTERY_BOOST_EN” on page 276

- **DCR452365**: [Arch2008] DCR for AmdMemoryInfoHob
  - Added “AmdMemoryInfoHob” on page 61

- **DCR447127**: New BLDCFG definitions for LVDS Miscellaneous controls
  - Modified “LvdsMiscControl” on page 131
  - Added “BLDCFG_LVDS_BIT_DEPTH” on page 215 and “BLDCFG_LVDS_PARAM_OVERWRITE_EN” on page 215

- **DCR446310**: Build options for AGESA_TESTPOINT controls.
  - Added “IDS_DEBUG_PORT_SIZE_IN_BYTES - sets the size of the IO cycle write for the testpoint. Options are:” on page 258,
  - “IDS_DEBUG_TP_PERFIX - Sets the value of a prefix set of bytes to be used in the upper bytes of the IO write to identify the source of the code.” on page 258

- Updated the Related Documents section
- Removed text previously marked as deprecated.
Chapter 1 Introduction

The AMD Generic Encapsulated Software Architecture (AGESA™) software is a BIOS procedure library designed to aid AMD customers to quickly implement AMD technology into their products. This document covers the interface definition for the procedure library and provides some guidelines on how to use the library in the customer’s environment. The library is designed to support multiple AMD products. This chapter explains the goals of the AGESA™ software.

1.1 Goals

The goal of this document is to provide a user-level description of the procedures and abilities of the AGESA™ software library.

1.2 Audience

This document is directed to the host environment wrapper implementer. It defines procedure call interfaces, specifies a recommended wrapper implementation and describes options that the wrapper implementer may choose to use. Some knowledge of BIOS programming practices is required.

1.3 Related Documents

Following is a list of related AMD documents:
• BIOS and Kernel Developer's Guides (BKDG)
  – BIOS and Kernel Developer's Guide for AMD Family 14h Models 00h-0Fh Processors, order# 43170
  – BIOS and Kernel Developer's Guide for AMD Family 15h Models 10h-1Fh Processors, order# 42300
  – BIOS and Kernel Developer's Guide for AMD Family 16h Models 00h-0Fh Processors, order# 48751
  – BIOS and Kernel Developer's Guide for AMD Family 16h Models 30h-3Fh Processors, order# 52740
  – BIOS and Kernel Developer's Guide for AMD Family 15h Models 30h-3Fh Processors, order# 49125
  – BIOS and Kernel Developer's Guide for AMD Family 15h Models 60h-6Fh Processors, order# 50742
• Revision Guides
  – Revision Guide for AMD Family 14h Models 00h-0Fh Processors, order# 47534
  – Revision Guide for AMD Family 15h Models 10h-1Fh Processors, order# 48931
  – Revision Guide for AMD Family 16h Models 00h-0Fh Processors, order# 51810
  – Revision Guide for AMD Family 16h Models 30h-3Fh Processors, order# 53072
  – Revision Guide for AMD Family 15h Models 30h-3Fh Processors, order# 51603
  – Revision Guide for AMD Family 15h Models 60h-6Fh Processors, order# 53564
• CPUID Specification, order# 25481
• Processor Design Guides
• Processor Functional Data Sheet

Related industry standards documents:
• DDR3 SDRAM Standard (JESD79-3F), July 2012.
• Advanced Configuration and Power Interface Specification, (ACPI) revision 5.0
• System Management BIOS (SMBIOS) Reference Specification, DMTF DSP0134, Version 2.8.0
• MultiProcessor Specification (MP Spec), Intel corp., version 1.4
• C Coding Standards Specification, UEFI consortium, USWG, v0.3

1.4 Terminology

The following definitions, acronyms and terms are used in this specification:
<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>Host Environment</td>
<td>The main body of code responsible for power-up sequencing and initialization of the platform. This can be one of many code bases in today’s technical markets.</td>
</tr>
<tr>
<td>Link</td>
<td>A HyperTransport™ technology connection between two devices.</td>
</tr>
<tr>
<td>MCT</td>
<td>Name used to refer to the memory controller and the memory controller initialization code.</td>
</tr>
<tr>
<td>Node</td>
<td>Refers to a processor or other device actively participating in the HyperTransport link coherent fabric.</td>
</tr>
<tr>
<td>Socket</td>
<td>Physical connector on the motherboard into which a processor can be installed. Sockets are numbered relative to the system or motherboard and are software-identified by the SA[2:0] pins.</td>
</tr>
<tr>
<td>Processor</td>
<td>AMD silicon product which fits into a socket and may contain one or more die.</td>
</tr>
<tr>
<td>Die</td>
<td>With the advent of Multi-Chip-Modules (MCM), a single processor may contain more than one silicon wafer die. Each die may contain one or more cores. Die are numbered relative to the processor.</td>
</tr>
<tr>
<td>Core</td>
<td>A term used to refer to the portion of a central processing unit which executes computational programs. Software sees each core as a separate entity even though two or more cores may physically reside in the same processor, or in the same die. Cores are numbered relative to the processor regardless of the die on which they may be physically located.</td>
</tr>
<tr>
<td>System address</td>
<td>Physical 40-bit address (without translations).</td>
</tr>
<tr>
<td>Wrapper</td>
<td>The layer of code used to isolate the AGESA™ software code from the host architecture code.</td>
</tr>
<tr>
<td>MP - Multi-Processor</td>
<td>This refers to a programming environment in which multiple processor cores are executing code simultaneously. In such an environment, special programming practices must be used to communicate between processor cores and to synchronize their operations.</td>
</tr>
<tr>
<td>or Multi-Processing</td>
<td></td>
</tr>
<tr>
<td>BSP - Boot Strap Processor</td>
<td>In an MP environment this is the master processor core. This core controls what operations are allocated to the other cores.</td>
</tr>
<tr>
<td>AP - Application Processor</td>
<td>In an MP environment this is a slave processor core that performs operations as directed by the BSP. Once the operation is complete, the core stops execution and waits for its next instructions from the BSP.</td>
</tr>
<tr>
<td>&lt;Plat&gt;Options</td>
<td>This is a general term convention to indicate an item that is specific to a Platform Solution. For example, when applied to a file, “&lt;Plat&gt;Options.c” would be interpreted as a file having the name “MaranelloOptions.c”</td>
</tr>
<tr>
<td>BKDG</td>
<td>A short hand reference to the BIOS and Kernel Developer's Guides (BKDG)</td>
</tr>
</tbody>
</table>
Chapter 2  Logistical Matters

2.1  Version Numbering

The AGESA™ software uses a three-level version numbering scheme: X.Y.Z. This interface specification is updated along with the code and the specification version tracks with the code version except that the specification only uses a two-level version numbering scheme, X.Y, where:

**X** - Major version number
A major version number of 0 indicates a prototype status. The first production ready version has a major version number of 1, then increments for further changes. This number increments when a major new feature or feature set is added.

**Y** - Minor version number
This number is incremented when a minor change occurs in the interface specification. Example of a minor change is the addition of a new function or feature.

**Z** - Code update number
This number is incremented for each software release. Changes at this level indicate no change has occurred in the interface. Code changes are bug fixes only. Note that this number may be more than one digit long.

Incrementing a version sub-number causes all lower-level sub-numbers to revert to 0. The product name is not part of the version numbering, but it can be used to designate the full title. Take “AGESA MarG34PI V1.2.3” for example: the “AGESA MarG34PI” is the product title and the “V1.2.3” is the version number.

The version string is embedded into the code image and can be discovered by a program. The program searches the ROM image for the signature in the following structure. Once found, the program can start at the 3rd byte and use the rest of the structure as a null terminated ASCII string.

```c
// AMD_CODE_HEADER Signatures.
#define AGESA_CODE_SIGNATURE {'!', '!', 'A', 'G', 'E', 'S', 'A', ' '}
#define CIMXNB_CODE_SIGNATURE {'!', '!', 'C', 'I', 'M', 'X', 'N', 'B'}
#define CIMXSB_CODE_SIGNATURE {'!', '!', 'C', 'I', 'M', 'X', 'S', 'B'}

/// AGESA_CODE_SIGNATURE
typedef struct {
    IN CHAR8 Signature[8];   // code header Signature
    IN CHAR8 ComponentName[8]; // 8 character name of the code module
    IN CHAR8 Version[12];   // 12 character version string
    IN CHAR8 TerminatorNull; // = 0x00, null terminated string
    IN CHAR8 VerReserved[7]; // reserved space
} AMD_CODE_HEADER;
```
2.2 Release Package

The release package given to customers includes the following:

- AGESA™ software technology core files
- Binary block interfacing files
- Binary compilations (all options set ‘on’)
- Examples of user-generated files (wrapper)
- Documentation (release notes)
- UEFI interfacing files
- Build control files
- Specialized build tools

The files contained in the distribution are organized into a directory hierarchy similar to the one as shown in Figure 2.1 below:

Figure 2.1: Package Directory Structure
2.3 File Naming Convention

The AGESA™ software complies with the *C Coding Standards Specification, UEFI consortium, USWG, v0.3* which states the core “C” code files use the long file name format. This removes any need for a cryptic naming convention, the file names are descriptive.

2.4 File headers

Every source file contains a comment header describing the file function and purpose, as defined in the *C Coding Standards Specification, UEFI consortium, USWG, v0.3*. The following is an example comment header as used in the AGESA™ software files:

```c
/**
 * @file
 *
 * Text Title of file.
 *
 * Purpose of File Content.
 *
 * @xrefitem bom "File Content Label" "Release Content"
 * @e project:      AGESA
 * @e sub-project: Library
 * @e version: $Revision$       @e date:    $Date$
 *
```

This is immediately followed by the AMD copyright notice, which is not shown here. The revision number in the last line is the revision number of the individual file as recorded in the AMD source control system. This number has no relationship to the code block version number.

2.5 Procedure Naming Convention

All public procedures use a name prefix to assist the programmer in understanding his or her place and purpose. All call-in entry points to the AGESA™ software use a prefix: “Amd” (for example, AmdInitReset). All call-out procedures used to gather data or provide customizing opportunities use a prefix: “Agesa” (for example, AgesaReadSpd).
2.6 Internal Documentation

This document describes the user interface to which the implemented code must conform. For more detailed information about the internal design or how the sub-systems work, there is internal documentation shipped with the sources in the delivery package. This internal documentation is generated from the source files using the open source tools ‘Doxygen’ and ‘Dot’. The HTML output is quite impressive and includes linked function and structure definitions, include dependency trees, call trees and where used lists.

2.6.1 Installing the Doxygen and Dot Tools

Doxygen is an open source, source code documentation generator tool. Documentation, user guides and downloads can be found at:

http://www.stack.nl/~dimitri/doxygen/index.html

Doxygen uses the Dot graphics generation tool to make visual diagrams and graphs of the dependency and call trees. Documentation and downloads can be found at:

http://www.graphviz.org/

2.6.2 Building the HTML files

The AGESA™ software includes a Microsoft® Visual Studio SLN control file used for building the HTML internal documentation files. The build control file for the processor documentation can be found at \Proc\AgesaDoc.sln within the release package.

The documentation build can be run from the command line (see the inputs for the Legacy.Bat file) or it can be run interactively by opening MS Visual Studio with the proper environment variables established (same as needed for the code build), loading the AgesaDoc.sln file, then selecting the project ‘rebuild’ command. The HTML files will be placed in an Html sub-directory under the platform tip directory. An internet browser may be used to open mainpage.html in that folder.

For convenience, a single help file called arch2008.chm is placed at the same level as the html folder. This is the complete help output and may be used in place of the html folder content. A copy is provided within the release package.
Chapter 3  Design Concepts

3.1  Interface Design Theory

The goal for the interface is to remain a constant for several generations of processors. To accomplish this goal, the number of call entry points and the content of the interface are reduced as much as possible. The call entry points are based on the boot time line and represent time points in the boot process instead of specific technical functions. See “4.1 AGESA™ Core Software” on page 38 for more details.

3.1.1  Required versus Optional Parameters

The AGESA™ software vigorously seeks to automatically determine configuration parameters for the host system. However, there are limits of technology and practicality, which means that there are still some required parameters that the host environment must provide. These parameters are identified in the call definitions. Many other parameters are available to the host environment for tailoring the configuration, but these are optional and the host environment may modify those it chooses. If not modified, the default values determined by the AGESA™ software are used. The default settings are identified in the interface definitions.

3.1.2  Call Mechanics

To greatly simplify the host environment implementation of an AGESA™ software interface call, this architecture uses the concept of an “initializer” function. See Figure 3.2 on page 28. The initializer allocates space for the interface data structure and pre-fills the structure with default parameter settings. The host environment must then fill in any required parameters and may modify any additional parameters of interest. After the main function is called, the host environment checks error status, then releases the interface data structure.
A code example for this process is as follows:

```c
VOID
OemMyProcedure (UINT8 MyParam) {
    AGESA_STATUS MyStatus;
    CREATE_STRUCT_PARAMS LclConfigBlk;
    AMD_EARLY_PARAMS *MyPtr;

    /* Fill the local Config Block */
    LclConfigBlk.StdHeader.Func = AMD_CREATE_STRUC
    LclConfigBlk.StdHeader.ImageBase = 0xFFFE0000;
    LclConfigBlk.StdHeader.AltImageBase = 0x00000000;
    LclConfigBlk.StdHeader.PcieBasePtr = 0x00000000;
    LclConfigBlk.StdHeader.CallBackPtr = &OemMyCbDispatcher;
    LclConfigBlk.ParamStructName = AMD_EARLYINIT_PARAMS;
    LclConfigBlk.AllocMethod = PREMEM_HEAP;

    /* Call the AMD Initializer function */
    MyStatus = AmdBridge32(&LclConfigBlk);
    MyPtr = (AMD_EARLY_PARAMS *)LclConfigBlk.NewStruc;
}
```

Figure 3.2: Interface Call Flow
/* OEM has chance to change parameter struct content */
MyPtr->EarlyParams.RandomParameter = MY_OEM_VALUE;

/* Call the AGESA main entry point */
MyPtr->StdHeader.Func = AMD_EARLY_INIT;
MyStatus = AmdBridge32(MyPtr);
/* Check return status */
switch (MyStatus) {
    case AGESA_WARNING:
        printf("Warning msg");
        break;
    case AGESA_ERROR:
        /* handle error */
    }
/* Call to release the data structure */
LclConfigBlk.StdHeader.Func = AMD_RELEASE_STRUCT
MyStatus = AmdBridge32(&LclConfigBlk);
}

All interface structure definitions are provided in an include file.

### 3.1.3 Error Reporting

Two methods of error reporting are provided: return codes and error logs. The return codes are described in “4.3.1 Returned Status Codes” on page 41 and provide enough detail for most host environments. For more detailed error reporting, the error log system is provided (see section “4.3.2 Error Logging” on page 42 for more details).

### 3.2 Build Design Theory

All pertinent data needed to select build options and to describe the target platform is contained in one user file named “<Plat>Options.c”. See Figure 3.3 on page 30. This file contains a list of #define entries that are used to conditionally compile the AGESA™ software defaults tables. It is these defaults tables that are used by the “initializer” functions to pre-fill the procedure parameter data structures prior to the call to the main function as described in “3.1.2 Call Mechanics” on page 27.
The main technology code is compiled, without #defines and without the <Plat>Options.c file. The main technology code then becomes a code library for the platform build.

The defaults tables file is compiled separately, referencing the <Plat>Options.c file. It extensively evaluates and cross checks the user options listed and outputs a data object file containing parameter data default values and reference pointers to selected option procedures. When linked with the main technology code library, the reference points cause only the desired option procedures to be included into the build. The location of this output object file must be specified to the AGESA™ module build control files.

The <Plat>Options.c file is located in a platform-specific directory according to the host environment needs. The defaults tables output file is located in the same platform-specific directory. The host environment may choose to reference it from that location or may choose to copy or move it to another directory location.

### 3.2.1 Control Files

The AGESA™ software contains the ability to generate build control files for several code bases, including generic .mak files, UEFI descriptor files and some IBV specific files.

The control files are nested or layered to allow modular construction. The directories have a top-level control file that invokes control files from the other directories to assemble components needed for their interface.
3.2.2 Build Styles

Some of the control files are designed to create binary images that can be built separately from the host environment code and merged into the final ROM image. This creates the ability to have multiple build styles:

- **Direct to module dispatcher** — This style uses the separated binary image build, using a direct call to the module dispatcher entry point. The host environment must parse the binary header described in the next section to locate the module dispatcher entry point.

- **Full integration with host environment** — This style does not use the binary image but pulls the AGESA™ software sources into the host environment build tools. The host environment code, using this style, may make direct calls to the AGESA™ software published functions. This style is used by the UEFI drivers.

3.3 Binary Image Design

The binary image build style is used to isolate the AGESA support code from the host environment in a way that allows the two to be compiled separately then merged as binary blocks into a final BIOS ROM image.

3.3.1 Binary Block Structure

An AGESA™ software binary image is prefixed with a binary header that identifies the binary and points to the code modules contained within. There may be only one code module or several may be combined into one binary image to reduce build overhead costs. See “3.4 Binary Image Implementation” on page 35.
The host environment must first find the binary image in the memory space, then calculate the execution address of the dispatcher to transfer control to the desired AGESA™ software function.

### 3.3.2 Execution Environment Expectations

The image code expects to be ‘located’ at an address determined by the host environment. This means the relocation fix-up records are used to fix up the code references to addresses in the image. AMD provides a tool called BINUTIL2.EXE to perform this action. Options and usage of this tool are listed in “B.1 BINUTIL2” on page 282.

Prior to calling any AGESA™ software interface, the host environment must establish the following requirements:

- CPU is in 32-bit protected mode execution
- CS is a 32-bit code segment with Base/Limit – 0x00000000/0xffffffff
- DS/ES/SS are 32-bit data segments with Base/Limit – 0x00000000/0xffffffff
- If paging is enabled, then pages must be identity-mapped (pg. 1 to pg.1, pg. 2 to pg. 2, etc.)

This configuration is commonly known as ‘32-bit Flat Address’ mode.
3.3.3 Standard Header

An architectural header is defined at the front of every function’s configuration block. This standard header is filled by the host environment prior to calling through the entry point. This data is present in the configuration block at all times, essentially making it global throughout the function call.

Prototype

```c
typedef struct {
    IN UINT32 ImageBasePtr;
    IN UINT32 Func;
    IN UINT32 AltImageBasePtr;
    IN CALLOUT_ENTRY CalloutPtr;
    IN UINT8 HeapStatus;
    IN UINT64 HeapBasePtr;
    IN OUT UINT8 Reserved[7];
} AMD_CONFIG_PARAMS;
```

Parameters

**Func**

The identifier of the desired procedure. The identifiers are defined in a provided include file.

**ImageBasePtr**

This is the memory location where the host environment has placed the binary image.

**AltImageBasePtr**

This is the memory location where the host environment has placed another secondary binary image. This value is optional and should be set to 0x00000000 when not used.

**PcieBasePtr**

This is the base address of the memory-mapped I/O block for access to PCIe® configuration cycles.

**CalloutPtr**

This is a 32-bit pointer to where the host environment has placed the entry point for call-out routines. The AGESA™ software code transfers control to this address for processing of call-out functions. See “3.4 Binary Image Implementation” on page 35.

**HeapStatus**

This item identifies the heap location, such as in Cache-As-Ram or memory. AmdCreateStruct will set this field when it creates the header for each entry point based on the expected heap status at that entry point. See “Figure 4.6:
AGESA Boot Time Call Points” on page 40 for a description of how the entry points fit into a boot sequence.

*HeapBasePtr*

This is the base address of the AGESA heap. AmdCreateStruct will set this field when it creates the header for the entry point.

*Reserved*

This space is reserved for future use.
3.4 Binary Image Implementation

Binary image implementation information is contained in the following sections.

3.4.1 Binary Header

The following binary header exists in each binary image. It is the first element in the binary image and can be discovered by either implicit build knowledge or by searching the memory space for the signature constant. The binary image and therefore the signature must be aligned on a 32-Kbyte boundary in the memory address space.

Prototype

typedef struct {
    IN UINT32 Signature;
    IN CHAR8 CreatorID[8];
    IN CHAR8 Version[12];
    IN UINT32 ModuleInfoOffset;
    IN UINT32 EntryPointAddress;
    IN UINT32 ImageBase;
    IN UINT32 RelocTableOffset;
    IN UINT32 ImageSize;
    IN UINT16 Checksum;
    IN UINT8 ImageType;
    IN UINT8 V_Reserved;
} AMD_IMAGE_HEADER;

Parameters

Signature

Signature that identifies this as an AGESA™ software image. This is a constant value equal to the string “$AMD”.

Creator ID

Image creator ID signature. This is specified by a parameter to, and set by the BINUTI2L image editing tool during the build process.

Version

Release version of binary image.

ModuleInfoOffset

Offset of first occurrence of AmdModuleHeader relative to the start of the binary image.

EntryPointAddress

Offset of the entry point relative to the start of the binary image.
Image Base

Image base address. This the linear/physical address to which the image code has presently been located (where it expects to execute).

Reloc Table Offset

Offset of relocation table, if applicable. Set to 0 if table not present. This the offset relative to the start of the binary image.

Image Size

Size, in bytes, of the complete binary image including the header.

Checksum

Checksum of the binary image. The entire binary image sums to 0. Using a word summation of bytes style algorithm.

Image Type

Image type, for example, 1 – B1, 2 – B2.

V_Reserved

Must be 0.

3.4.2 Module Header

A module header exists for each code module included in the binary image. There may be more than one module, in which case the NextBlock parameter is used to chain the modules in the binary image.

Prototype

```c
typedef struct _AMD_MODULE_HEADER {
    IN UINT32 ModuleHeaderSignature;
    IN CHAR8 ModuleIdentifier[8];
    IN CHAR8 ModuleVersion[12];
    IN VOID *ModuleDispatcher;
    IN struct _AMD_MODULE_HEADER *NextBlock;
} AMD_MODULE_HEADER;
```

Parameters

Module Header Signature

Constant value equal to the string “$MOD”.

Module Identifier

Published name for this module.

Module Version

Release version of the module in string format. This string reflects the version numbering scheme defined in “2.1 Version Numbering” on page 23.
ModuleDispatcher
Offset of the module dispatcher relative to the start of the binary image.

NextBlock
Offset of the next AmdModuleInfoBlock relative to the start of the binary image. If no more blocks are present, this is set to 0x00000000.

3.5 Integrated Debug Services

Throughout the core files are macros which import debug services. These are the Integrated Debug Services (IDS) macros further defined in “Chapter 19 IDS Configuration Controls” on page 249. Expansion of all IDS macros is controlled by #define compile switches defined for the platform. When disabled, the macros are not expanded during compile and consume no code space.
Chapter 4  Operational Overview

4.1  AGESA™ Core Software

Figure 4.5 is a representation of the time line of a boot sequence depicting the major tasks performed in an average system. (This representation is not intended to be time proportionately accurate.)

![General Boot Time Line](image-url)

**Figure 4.5:**  General Boot Time Line
Marker points (Figure 4.5):

A — System reset. This occurs at first power-on of the system and also when system resets are performed by the software (warm reset).

B — Immediately after a reset some tasks must be performed in order to make a decision about the integrity of the ROM image.

C — The decision is made about the integrity of the ROM image. If the test fails, execution proceeds to the Recovery Mode. If the test passes, execution jumps to start the main boot sequence.

D — Recovery Mode. The software does minimal hardware initialization, locates the source for a new ROM image and initiates a Flash ROM update.

E — Main boot path. Proceed with full hardware initialization. Warm reset may be needed to instantiate new values into some registers.

F — Determine if the system is resuming from a suspend (ACPI S3) state. If yes, then jump to the restoration sequence.

G — Proceed to OS boot. Initialize all devices, create OS information tables, load the OS from storage, then jump to the OS entry.

H — Restoration. The system and OS state still reside in memory. Restart the system hardware devices, then re-enter the OS.

Many of the activities listed involve AMD silicon devices. The AGESA™ software call entry points are defined to occur at these time points. Figure 4.6 on page 40 shows the approximate positions of the AGESA™ software call entry points.
The call time point duties are outlined as:

**AmdInitReset**
- initialize heap ctl
- Primary ncHt link initialization
- SB initialization @ reset
- NB after HT

**AmdInitEarly**
- register load
- full HT initialization
- uCode patch load
- AP launch
- PwrMgmt Init
- NB post initialization
- Detect need for warm reset

**Figure 4.6: AGESA Boot Time Call Points**

Chapter 4  Operational Overview  40
Details of the actions performed by the AGESA™ software call entry points are listed in Chapter 14:“Entry Point Procedures” on page 100.

### 4.2 Operational Warnings

Do not call functions that are not published in the interface specification. Procedures that are not published are internal functions and may change from release to release.

Do not enable code execution caching before main memory is initialized, except through using the provided AGESA™ software functions. Failure to do so may result in undesired outcomes.

### 4.3 Reported Errors

The AGESA™ interface calls always return to the host environment. Actions to be taken are indicated by the error class, but the host environment is responsible for implementing the action.

#### 4.3.1 Returned Status Codes

The returned status codes depict the following types of conditions. Please refer to the AGESA.H file for declaration details.
AGESA_SUCCESS  No issue. Everything is fine. A log entry may have been made for information purpose. For example, test point, node discovered; ncChain initialized OK; #devices=_N_ (useful for HTX device detection).

AGESA_UNSUPPORTED  Used by the optional call-out functions to indicate that the function is not implemented or not supported in the host environment.

AGESA_BOUNDS_CHK  Indicates that one of the passed parameters was out of bounds. The output data of the procedure is invalid. Example: the Error Log is empty.

AGESA_ALERT  Do not stop POST, but a log event or message was made in which the end user may be interested. The host environment may need to preserve the message and display it or formally log the event. Examples: Sync flood; HT CRC error; MCA status<>0 on reset; thermal event at reset.

AGESA_WARNING  Minor degradation in performance or configuration but operation is not prevented. OS boot is permitted. The host environment should notify the user, but may choose to do so only on the first occurrence and not flag every occurrence or on every reset. Examples: Super Weird Mode invoked; HT device lied about ability; unknown CPU revision; Bank interleave not enabled when requested.

AGESA_ERROR  Significant degradation of performance, configuration, or operation. The host environment should take corrective actions. OS boot is permitted. The host environment should notify the user of this event every time. Examples: HT fall-back to 1P; HT device initialization failed; Zero common PStates found; Bad DIMM (?)..

AGESA_CRITICAL  Host environment should stop POST. Attempting to display or log a message is recommended. OS boot should NOT be allowed. Examples: Mixed families found; DP and MP parts mixed; BIST error.

AGESA_FATAL  Stop NOW. The host environment must stop POST immediately. Examples: no memory found; processor power > board capacity (possible damage situation).

All reported errors other than SUCCESS and BOUNDS_CHK imply that an event has been logged in the event log.

### 4.3.2 Error Logging

The event log buffer retains the 16 most recently reported events that may be retrieved using the user event log query interface “AmdReadEventLog” on page 97. The application procedure records various events, including enhanced error descriptions. An detailed explanation of the logged events and errors can be found in Chapter C: “Logged Error Messages” on page 283.
Section II - Porting Guide for Binary Module

Chapter 5 Binary Module Porting

5.1 Overview

All support for 16-bit Real Mode operation has been deprecated. The binary module is being retained as it is still viable in the 32-bit environment.

Execution within the binary module occurs in 32-bit protected mode (flat addressing).

5.2 Terms and Definitions

- **CallOut**: A CallOut is a call back to the host BIOS made from the AGESA™ software.
- **Bridge**: A Bridge is a procedural collection point routine that calls the AGESA™ software binary block from the system BIOS. All of the special details needed to make the call to the binary module are in just one location; not spread throughout the host code.
- **Dispatcher**: The Dispatcher is the entry point into the AGESA™ software. It takes a function number as entry parameter in order to invoke the published function.
- **Router**: The Router is the CallOut re-entry point to the host environment. It takes a function number as a parameter that selects the call-out function to be executed.

5.3 Theory of Operation

The funneling model, as shown in Figure 5.7, is used to interface the AGESA™ software binary image to a host BIOS. It consists of code compiled into the host environment BIOS, and the AGESA™ software binary image. The host side code (the bridge) calls into the AGESA™ software side (the dispatcher), executes the requested function, and returns to the caller. The model also provides a framework for the AGESA™ software side to call the host BIOS to perform platform specific operations.
The bridge code and the BIOS Call router code are built with the host environment BIOS. The dispatcher and call-out port is built with the AGESA™ code into the binary module as described in “Binary Image Design” on page 31.

5.3.1 Calling an AGESA™ Software Procedure

Figure 5.8 displays the steps involved in making a call to the AGESA™ software. This is the typical order followed by the host environment.

At the desired point in the BIOS code, a call is made to the bridge routine with parameters selecting a function. The bridge is the procedure that calls the AGESA™ software dispatcher function in the binary image. The dispatcher calls the desired function, then returns with a status code.
5.3.2 Call-Out Operation

Call-out operations work in much the same manner, but in reverse. Figure 5.9 displays the steps involved in making a call out to host environment code from within the AGESA™ software environment.

The AGESA™ software function calls the Call-Out port with parameters selecting the desired host environment procedure. The Call-Out port passes control to the Call-Out router routine that then calls the host environment procedure. When finished, the exit portion of the Call-Out router returns to the calling function.

Figure 5.8: Making a ROM image Call

The host BIOS environment bridge routine should treat the call to the dispatcher as a function call with the definition as described in “AmdAgesaDispatcher” on page 48.
Figure 5.9: Handling a Call-Out

The host BIOS procedure is called from the router as a function call with the definition as described in “Host BIOS Router Procedure” on page 50.
Chapter 6  The Binary Module API

This chapter covers the host environment requirements to implement the host BIOS interface mechanisms to access the AGESA™ software interface.

It is the responsibility of the host environment to establish a valid stack prior to making any call to the binary module interface.

6.1 Making Calls to Core Entry Points

All procedure calls are made using the module dispatchers described in “Binary Image Implementation” on page 35. The host environment procedures must properly create and fill the standard header data.

The identifiers for the published entry point functions can be found in the AMD.H include file.

At each point in the host environment code where a call to the AGESA™ software is desired, a call to an bridge procedure must be inserted. The procedure must locate the binary image entry point as described in “Binary Image Design” on page 31 then make the call to the AMD dispatcher which is defined below. An example of this procedure is available in the file AmdBridge32.asm.
AmdAgesaDispatcher

Execute an AGESA™ software function through the binary module interface. This is the definition of the routine contained in the binary module. The host bridge routine must match this definition.

Prototype

AGESA_STATUS
AmdAgesaDispatcher (  
   IN OUT VOID *localCfgBlock    
)

Parameters

localCfgBlock

A pointer to the configuration block (AMD_CONFIG_PARAMS). The value of the pointer is determined by either implicit knowledge of the host build environment or by scanning the memory address space for the binary image.

Related Definitions

AMD_CONFIG_PARAMS

The standard header definition shown in “Standard Header” on page 33.

Description

This procedure is the entry gateway or bridge to the binary module code.

An example call sequence:

localCfgBlock.Func = AMD_CREATE_STRUCT;
localCfgBlock.ImageBasePtr = AMD_MODULE_OFFSET;
localCfgBlock.AltImageBasePtr = 0;
localCfgBlock.PcieBasePtr = PCIE_BASE_ADDRESS;
localCfgBlock.CalloutPtr = hostCallOutRouter;
AmdAgesaDispatcher(localCfgBlock);

Dependencies

This procedure requires a stack. The host environment must establish the stack environment prior to making the call to this procedure.
6.2 Handling Core Call-Out Procedures

When using the binary image build model, all of the interface call-out functions defined in “Chapter 15 Call-Out Procedures” are collected and funneled through one interface portal, as described by the “Call Out” box in Figure 5.9 on page 46. This provides the host environment with a single point for filtering and dispatching the functions and keeps the call interface consistent over time.

All AGESA core call-outs are made using the call port as illustrated in Figure 5.9 on page 46. This means that the host environment must implement a call-out router function and properly load its address in the standard header. This procedure is implemented in the host environment and functions as described in “Call-Out Operation” on page 45.

The router translates the function number into an execution address for the call-out procedure. The call interface the router procedure exports must match the following.
Host BIOS Router Procedure

The router function is in the host environment space (external to the AGESA™ software binary module) and routes the AGESA code call-out to a host environment procedure that provides the requested service.

Prototype

```c
AGESA_STATUS CallOutRouter (  
    IN UINT32 Function,  
    IN UINTN FcnData,  
    IN CALL_OUT_PARAMS *ConfigPtr);  
```

Parameters

- **Function**  
  IN  
  An index or identifier used to select which call-out function operation is to be invoked. The definition of available functions is available in the AMD.H include file.

- **FcnData**  
  IN  
  A data element specific to the individual call-out function, meaning or purpose of the data is function-specific. This parameter is passed without conversion or translation, the call-out function may, for example, use this to select a sub-function operation.

- **ConfigPtr**  
  IN OUT  
  Pointer to the configuration data block in use by the calling procedure. This structure includes the standard header structure defined in “Standard Header” on page 33, which contains important information used by the router.

Related Definitions

- **AMD_CONFIG_PARAMS**  
  The standard header definition shown in “Standard Header” on page 33.

Description

This procedure is called by the Agesa call out port inside the binary module to access services from the host environment. This procedure is implemented in and by the host environment.

Dependencies

The procedure call is made using 32-bit protected mode flat addressing model.
Status Codes Returned

AGESA_SUCCESS         The function has completed successfully.
AGESA_UNSUPPORTED     The selected function is not implemented by the host environment.
Section III - Porting Guide for UEFI

Chapter 7 UEFI Porting

7.1 Overview

The present UEFI BIOS environment offers four stages of execution (SEC, PEI, DXE, and RTP) spanning three different execution modes, resulting in several pieces of code targeted for the following combinations:

1. 16-bit SEC
2. 32-Bit SEC
3. 32-Bit Platform Initialization (PEI Phase)
4. 64-Bit Platform Initialization (DXE Boot Services Phase)
5. 64-Bit Run Time Phase

To facilitate these combinations, the AGESA™ software core files are arranged into three library modules or groups.

1. AgesaSec (Includes) containing 16-bit execution code
2. AgesaPeiCommonLibs containing 32-bit execution code
3. AgesaDxeCommonLibs containing 64-bit execution code

In addition to these, the UEFI portion of the AGESA™ software adds four more libraries:

4. AgesaPlatformLib containing platform specific materials
5. AgesaPpiLib containing the PEI PPI code files
6. AgesaGuidLib containing GUID information
7. AgesaProtocolLib containing the DXE Protocol files
These libraries are used in the generation of four build targets which will be loaded into the platform UEFI FFS ROM image:

- AmdProcessorInitPeim
- AmdAgesaDxeDriver
- AmdResetManagerPeim
- AgesaProtocolLib

## 7.2 Tool Set

For the 16-bit SEC phase development, the following tools are used:

- MASM 6.15—To assemble 16-bit code for SEC phase.

For the 32-bit SEC phase and 32-bit platform initialization phase development, the following tools are used:

- ml — Microsoft Macro Assembler Version 8.00.50727.762
- CL — Microsoft 32-bit C/C++ Compiler Version 14.00.50727.42

For the 64-bit platform initialization phase and 64-bit runtime phase development, the following tools are used:

- ml — Microsoft Macro Assembler Version 8.0.40310.39
- CL — Microsoft 64 bit C/C++ Compiler Version 14.0.40310.41

## 7.3 Configuration Options

All the configuration options available for any specific platform build are described in Chapter 16 on page 181. Refer to the specified section for the details about each configuration option. The options listed here are additional options for the UEFI environment. They are also selectable through the `<plat>`Option.c file where `<plat>` is the name of the AMD platform solution set to which the platform belongs.

### 7.3.1 Build Time Options

There are no additional user options specific to the UEFI environment at this time.

### 7.3.2 Run Time Options

There are none defined at this time.
7.4 **Build Environment Installation**

This section talks about items that the action of porting these drivers to the host environment must understand or perform.

- UEFI re-definition of the StdHeader content - The 1st reserved element is used to store the handle for the PEI_Services so that the library level routines can connect with the PeiServices to perform their operations.

- UEFI uses special environment specific library routines as mentioned above to connect to services through the PeiServices PPI.
Chapter 8  The SEC Phase

The purpose of the SEC phase is to establish the C programming language environment - enter 32-bit execution mode and set up a stack region.

The AGESA™ software provides “AMD_CAR_SUPPORT (Deprecated)”, documented on page 75, to perform this duty. The host environment must include this procedure.

Figure 8.1: Overview of AMD SEC components
Chapter 9  The PEI Drivers

The PEI Driver needed to control the AMD initialization is divided into two PEIM modules, based upon the execution time line. This two PEIMs to support the AGESA™ software are:

- AmdProcessorInitPeim
- AmdInitPostPeim

Figure 9.1: Overview of AMD PEI module interactions
9.1 AmdProcessorInitPeim

This PEIM is responsible for initializing all the processor related components and subcomponents. This PEIM incorporates calls to the AGESA™ software core entry points:

- "AmdInitReset", defined on page 101.
- "AmdInitEarly", defined on page 105.

The PEIM will perform processor initialization, then publish the AmdCpuEarlyInit PPI. This allows any component depending upon processor initialization an opportunity to perform any post initialization operations they require.

This PEIM will register for a callback upon publication of the Memory Init PPI when the internal memory initialization completes.

This PEIM consumes the following events:
- MemoryInitPPI

This PEIM produces the following events (PPIs):
- AmdInitResetPPI
- AmdInitEarlyPPI
- AmdInitPostPPI

The PEIM produces the following HOBs.
- AmdMemoryInfoHob
AmdInitResetPPI

This PPI is published after early processor core initialization is complete.

GUID

#define AMD_PEI_INIT_RESET_PPI_GUID \
    { 0xba4ee111, 0xe663, 0x4c4f, 0x89, 0xc5, 0xf3, 0xea, 0x11, 0x64, 0xdd, 0xaf }

PPI Interface Structure

typedef struct _AMD_PEI_INIT_RESET_PPI {
    UINTN Revision;
} AMD_PEI_INIT_RESET_PPI;

Parameters

Revision

Revision number for this PEIM driver.
AmdInitEarlyPPI

This PPI is published after the call to AmdInitEarly returns and early processor core initialization is complete. This PPI may be used as a callback trigger or dependency for any other module that needs to run right after the processor core initialization completes.

GUID

```c
#define AMD_PEI_INIT_EARLY_PPI_GUID \
   { 0x9cf93fd4, 0xc274, 0x416d, { 0xab, 0x89, 0xe, 0xf0, 0x8f, 0x28, \
   0x6a, 0xc0 } }
```

PPI Interface Structure

```c
typedef struct _AMD_PEI_INIT_EARLY_PPI {
   UINTN  Revision;
} AMD_PEI_EARLY_INIT_PPI;
```

Parameters

- **Revision**

  Revision number for this PEIM driver.
AmdInitPostPPI

This PPI is published after the call to AmdInitPost is complete.

GUID

```c
#define AMD_PEI_INIT_POST_PPI_GUID {
  0xb83e4633, 0xd9a, 0x4463, 0x95, 0x86, 0x62, 0xe7, 0xf6, 0xce,
  0x48 }
```

PPI Interface Structure

```c
typedef struct _AMD_PEI_AMD_INIT_POST_PPI {
    UINTN    Revision;
} PEI_AMD_INIT_POST_PPI;
```

Parameters

*Revision*

Revision number for this PEIM driver.
AmdMemoryInfoHob

This HOB is published after the call to AmdInitPost is complete. This applies for boot modes other than BOOT_ON_S3_RESUME. This HOB provides info about the available system memory and UMA.

GUID

```c
#define AMD_MEMORY_INFO_HOB_GUID \
    { 0x45dc9e40, 0x336, 0x4878, 0xb5, 0xbb, 0xaa, 0x76, 0x75, 0xc5, 0xc8, 
        0xef }
```

Prototype

```c
typedef struct  {
    UINT32  Version;
    UINT32  NumberOfDescriptor;
    AMD_MEMORY_RANGE_DESCRIPTOR  Ranges[1];
} AMD_MEMORY_INFO_HOB;
```

Parameters

Version

Version of HOB structure. For this version of specification, this value is defined as below.

```c
#define AMD_MEMORY_INFO_HOB_VERSION        0x00000100ul  // Version 00.00.01.00
```

NumberOfDescriptor

Number of memory range descriptor. Value of 3 means that there are 3 memory range descriptors starting from address of AMD_MEMORY_RANGE_DESCRIPTOR Ranges parameter.

Ranges

Memory ranges array. Starting from address of Ranges, there are NumberOfDescriptor elements of the memory range descriptor array.

Related Definitions

```c
typedef struct { 
    UINT64  Base;
    UINT64  Size;
    UINT32  Attribute;
    UINT32  Reserved;
} AMD_MEMORY_RANGE_DESCRIPTOR;
```

Base
Base address of memory range

Size

Size of memory range, in bytes.

Attribute

Attribute of memory range. Valid definitions are listed below.

- AMD_MEMORY_ATTRIBUTE_AVAILABLE: Defines the described block as available memory.
- AMD_MEMORY_ATTRIBUTE_UMA: Declares the described block as reserved for Graphics display.
- AMD_MEMORY_ATTRIBUTE_RESERVED: Defines the block as a reserved memory area.

Reserved

For alignment purpose of AMD_MEMORY_RANGE_DESCRIPTOR on UINT64 boundaries. The value of this field should be ignored.
9.2 **AmdInitPostPeim**

This PEIM is responsible for initiating the post reset initialization duties. This PEIM incorporates calls to the AGESA™ software core entry points:

- “AmdInitPost”, defined on page 115.
- “AmdInitEnv”, defined on page 128.

This will initialize the memory subcomponents and publish the AmdInitPostPPI as indication that memory initialization has succeeded, which helps to launch any other post reset operation by other system modules.

This PEIM consumes or depends upon the following events:

- AmdInitEarlyPPI
- AmdResetComplete

This PEIM publishes the following events (PPIs):

- Memory Init PPI
MemoryInitPPI

This PPI is published to indicate that the main memory initialization has completed. This is used as an internal coordination event to notify the AmdProcessorInitPeim to perform post memory initialization clean-up and configuration. The system memory is not available for general system use until posting of the standard EfiMemory PPI.

GUID

```c
#define AMD_MEM_INIT_PPI_GUID = \n   { 0x8ba51c1c, 0x4b30, 0x47df, {0xa4, 0x4e, 0x22, 0x53, 0xe1, 0xa5, 0xd4, 0x2} }
```

PPI Interface Structure

```c
typedef struct _AGESA_MEM_PPI {
    UINTN Revision;
} AGESA_MEM_PPI;
```

Parameters

*Revision*

Revision number for this DXE driver.
9.3 AmdResetManager

This PEIM coordinates reset requests from multiple AMD PEIMs: the Chipset Northbridge, the SouthBridge along with the processor PEIM. Once loaded, this PEIM will check the status of the PPIs published by the other PEIMs to see if any of them have requested a warm reset to occur. If so, then the reset is generated; if not, then the PEIM will publish the reset-is-complete PPI to flag other PEIMs that they may continue with their post reset duties.

This PEIM consumes or depends upon the following events:

- AmdInitEarlyPPI

This PEIM publishes the following events (PPIs):

- AmdResetComplete
Chapter 10   The DXE Driver

The purpose of the DXE driver is to perform the late initialization and to supply to the system information about the AMD components, in the form of data tables.

The DXE driver incorporates calls to the AGESA™ software core entry points:

- “AmdInitMid”, defined on page 135.
- “AmdInitLate”, defined on page 137.

The AmdInitLate entry point generates several tables used by other drivers in the system. The AMD CPU DXE driver will make the call to AmdInitLate then store the generated tables for later use. A protocol is published, once the tables are available, for the other drivers to use to access the table data.

![Diagram of AMD DXE driver interaction](image)

Figure 10.1: Overview of AMD DXE driver interaction
AgesaDxeProtocol

The AgesaDxeProtocol is published as part of AmdCpuDxeDriverInit. This published protocol will be called during update of various tables during POST.

```c
#define AGESA_DXE_PROTOCOL_GUID \
    { 0xcdc636f9, 0x55be, 0x4a20, 0x99, 0x2f, 0xe8, 0xcc, 0x8f, 0x63, 0x25 }

//
// Protocol prototype
//

typedef enum {
    UndefinedProcessorTableType = 0,
    AcpiPstateType,
    AcpiSratType,
    AcpiSlitType,
    AcpiWheaHestCmcType,
    AcpiWheaHestMceType,
    DmiTableType,
    AcpiAlibType,
    AcpiIvrsType,
    MaxProcessorTableType
} AMD_PROCESSOR_TABLE_TYPE;

typedef typedef enum {
    UndefinedProcessorTableType = 0,
    AcpiPstateType,
    AcpiSratType,
    AcpiSlitType,
    AcpiWheaHestCmcType,
    AcpiWheaHestMceType,
    DmiTableType,
    AcpiAlibType,
    AcpiIvrsType,
    MaxProcessorTableType
} AMD_PROCESSOR_TABLE_TYPE;

typedef EFI_STATUS (EFIAPI *AMD_CREATE_PROCESSOR_TABLES) (
    IN AGESA_DXE_PROTOCOL *This,
    IN AMD_PROCESSOR_TABLE_TYPE TableType,
    IN OUT UINTN *BufferLength,
    IN OUT VOID **BufferPtr
);
AmdGpuVgaControlDxe

The AmdGpuVgaControlDxe driver controls VGA resource decoding for the processor GPU (iGPU). When installed, the driver will monitor requests through the PciIo protocol and will enable VGA decoding only if the host environment requests this using the attributes of the PciIo protocol for the iGPU.

This monitoring is performed if the driver is installed. There is no further interface to this driver.
Chapter 11  UEFI Porting Check List

11.1  Example Files

The files in the \Addendum directory of the release package are reference files showing examples of how to implement certain functions. The following files are for reference and are not intended to be included in any build.

Cpcar32.asm  This is an example of a wrapper file installing the Cache-As-Ram code into a 32-bit host environment.

The following file is intended for the host environment to copy this file to a platform tip build directory and be modified as needed to describe the specific platform. The settings in the \Addendum copy of this file will reflect the default settings determined by AMD.

<Plat>Options.c  This is the platform description of build options listed in section “Build Customization” on page 71 and “Build Configuration Elements” on page 186. This file is expected to be copied under the platform tip build directory. That directory is also expected to be the target of the vcproj build output files.

<Plat>RecoveryOptions.c  Similar to above, this file is expected to be in the platform target build directory and describes the platform build options to be used for recovery mode.

11.2  Build Control Files

For the UEFI build style, the control files are located in various directories under the \UEFI directory of the release package. These control files need to be integrated into the platform and host environment build systems.

AgesaPei0Libs.inf  This is a control file used to establish the required environment for the AGESA™ Software build process to be used in PEI Phase. The parameters for this console command line program are described in the file header.

AgesaPei1Libs.inf  This is a control file used to establish the required environment to build AGESA PEIM

AgesaDxe0Libs.inf  This is the file used to establish the required environment for AGESA™ software build process to be used in AGESA DXE Drivers

AgesaDxe0Libs.inf  This is the file used to establish the required environment to build AGESA DXE Drivers.
11.3 Environment Variables

The AGESA™ software build environment requires a few environment variables to be set in order to function properly. For the UEFI build, these variables are set in the platform master build control file and are expected to be set by the host environment prior to invoking the AGESA™ software build control .inf files.

- **AGESA_ROOT** Identifies the directory where the AGESA™ code is located. The top most directory, where AGESA.h is located. This must be the full path (e.g. D:\myPlatform\AGESA\ ) and includes the trailing ‘\’.

- **AGESA_OptsDir** Identifies the platform tip build directory where the platform options (<Plat>Options.c) and customization files are located. This must be the full path (e.g. D:\myPlatform\MotherBoards\Project\AGESA\ ) and includes the trailing ‘\’.

- **Solution** Identifies the name of the AMD Platform Solution being targeted for the build (e.g. “Maranello”).

11.4 UEFI Check List

Points to remember:

- Copy the <plat>Options.c file from the \Addendum directory to the platform tip build directory. AMD recommends the use of a sub-directory named ‘AGESA’ to contain these files and the build output files.
- Copy the OptionsIds.h content in “Example” on page 257 to OptionsIds.h in the platform build tip directory and make changes to enable the IDS support desired. It is highly recommended that you set the following for initial integration and development:
  
  ```
  #define IDSOPT_IDS_ENABLED TRUE
  #define IDSOPT_ERROR_TRAP_ENABLED TRUE
  #define IDSOPT_ASSERT_ENABLED TRUE
  ```
- Edit and modify the option selections in those two files to meet the needs of the specific platform.
- Set the environment variable ‘AGESA_ROOT’ as noted above.
- Set the environment variable ‘AGESA_OptsDir’ as noted above.
- Generate the doxygen documentation as described in “Internal Documentation” on page 26, or locate the file arch2008.chm within your AGESA™ release package.
- Enable CAR (Cache As Ram) before the call to AmdInitReset by using “AMD_ENABLE_UEFI_STACK” on page 76.
- Use the ‘ByHost’ allocation method for the call to AmdInitReset. Allocate the structure space before the call.
- The host environment code must not modify the SS or ESP registers while the CAR is enabled.
- The host environment MUST NOT modify the cache controls (MTRRs, etc) during the Cache-As-Ram time period (reset through final return from AmdInitPost).
Chapter 12  Introduction

This chapter describes some basics related to building or compiling the core code files.

The features that are available are arranged into sets for the various platform solution product lines. So the first level of selection for the user is to specify the platform solution to which their platform belongs. The second level of selection is the build method, then the third level is the individual options.

12.1  Platform solutions

A “platform solution” is a collection of AMD products that are related or are compatible for constructing a platform. A code name is assigned to each “solution” as a marketing reference. Current examples of platform solution names are “Danube” and “Maranello”. For the rest of this chapter the generic indicator of <plat> is used.

12.2  Build Methods

There are two primary methods to build the AGESA™ software core files as listed below. A project control file is provided for each method.

Binary Modules

AMD distributes the source code and build control files to create binary modules as described in “Binary Image Design” on page 31. This is referred to as the indirect method, since the interface calls are routed through a common entry point.

Source Integration

In the source integration method, the host environment integrates the distributed source files into their environment and builds a ROM image using their tool set. This is also referred to as the integrated or direct interface.

12.3  Build Customization

Build time defaults may be customized easily using the <plat>Options.c file for each platform. The full set of build customizations is presented in “Build Configuration Elements” on page 186. Because
appropriate defaults are provided automatically, it is only necessary to specify build customizations for items that need to be changed for the platform.
Chapter 13  Service Procedures

13.1  Stack Procedures

These stack procedures are provided to the host environment for use in establishing the stack environment. Since these procedures must be integrated into the host environment, they are provided as included code in the form of a macro. These must be called by the host environment.

The stack routines do not rely on segment names being imported from the host environment through include files. The procedures defined below are without segment declarations. The host environment must define a local file that establishes the proper execution environment for their needs and use the INCLUDE directive to pull in the stack code source file into the local file.

The routines are native assembly code. Their purpose is to establish or destroy the stack and therefore expect to execute in a stackless mode. They can be included into either an assembly host environment local file or, with care, can be included into a host environment C language file.

These stack procedures apply to the x86-64 architecture APUs. They will not be used by the AARCH64 APUs.
**AMD_RESET_ENABLEMENT**

This macro contains AMD silicon initialization controls that are required extremely early in POST.

**Prototype**

```assembly
OEM_SEGMENT1_START
; AMD_RESET_ENABLEMENT; Host Environment Procedure
; Input: EBX - Return address
PlatformReset PROC FAR PUBLIC

    AMD_RESET_ENABLEMENT
        jmp ebx ; Return to caller
PlatformReset ENDP

OEM_SEGMENT1_END
```

**Parameters**

*none*

**Description**

In the UEFI implementations, the earliest control point for AMD software is in the PEI phase. This may be too late for some critical settings. This macro provides a very early control point for the AMD software to establish the critical settings.

This macro should be placed as early as possible in the boot sequence. It must be before the use of the AMD_ENABLE_STACK macros and should be before entry to 32bit execution mode.

The AARCH64 APUs enhanced with the Platform Security Processor (PSP) will not use the stack and very early macros. The PSP will initialize the DRAM.

**Dependencies**

Registers destroyed: MMX0, all general purpose registers (except EBX).

Specifically preserved is the EBX register - for use as a stackless return.

**Status Codes Returned**

None.
AMD_CAR_SUPPORT (Deprecated)

This macro is used to reduce the code size for establishing the Cache-As-RAM (CAR) support in early-POST. This optional macro will select the specific SoC for which the BIOS is being built.

Prototype

AMD_CAR_SUPPORT <SolutionName>

Example:

OEM_SEGMENT1_START
;EnableStack : Host Environment Procedure
; Input: EBX - Return address
EnableStack PROC FAR PUBLIC
    AMD_CAR_SUPPORT Mullins
    AMD_ENABLE_STACK
        jmp ebx ; Return to caller
EnableStack ENDP

OEM_SEGMENT1_END

Parameters

SolutionName IN

The name of the SoC or ‘solution’ being built. The current members in this list are: ‘Kaveri’, ‘Richland’, ‘Kabini’, ‘Kyoto’, ‘Mullins’.

Description

This macro will select the target SoC for inclusion in the build. All other processor families will be excluded. This macro must be placed before the use of the AMD_ENABLE_STACK macros. If it is not present, CAR code for all supported families will be included.

If you need to specify more than one SoC, use the macro once for each SoC name. Example:

AMD_CAR_SUPPORT Kabini
AMD_CAR_SUPPORT Mullins
AMD_CAR_SUPPORT Kaveri

The AARCH64 APUs enhanced with the Platform Security Processor (PSP) will not use the stack and very early macros. The PSP will initialize the DRAM.

Status Codes Returned

An error will be generated during compilation if the SoC SolutionName is not recognized.
AMD_ENABLE_UEFI_STACK

This procedure is used to establish the stack within the host environment.

Prototype

Usage:

AMD_ENABLE_UEFI_STACK PspOutputBuffer StackPosition

Example:

OEM_SEGMENT1_START
; EnableStack ; Host Environment Procedure
; Input: EBX - Return address
EnableStack PROC FAR PUBLIC
    AMD_ENABLE_UEFI_STACK STACK_AT_BOTTOM
    jmp ebx ; Return to caller
EnableStack ENDP

OEM_SEGMENT1_END

Parameters

StackPosition

Specifies the position of the stack allocations within the Cache-As-RAM zone.

STACK_AT_BOTTOM - (Default) the stacks will be placed at the bottom, lower addresses, of the zone.

STACK_AT_TOP - the stacks will be placed at the top, higher addresses, of the zone.

EBX IN

return address - where to jump after macro completion.

EAX IN

The BIST value to save.

ECX IN

Size in bytes of initial execution cache allocation. Execution cache allocation will be made immediately below the 4 GByte boundary.

SS:ESP OUT

Points to the private stack location for this processor core.

EAX OUT

Contains the AGESA_STATUS return code.

1. PspOutputBuffer parameter applies only to APUs containing the new PlatformSecurity Processor (PSP).
**EDX**  
OUT  
Contains the event sub-class for status return codes of higher severity than AGESA_SUCCESS.

**ECX**  
OUT  
Upon success, contains this processor core’s stack size in byte.

**EDI**  
OUT  
Points to the stack frame. The stack frame will be initialized as follows below.

```c
[EDI]UEFI_SEC_PEI_HAND_OFF.BOOT_FIRMWARE_VOLUME_BASE = OEM_BFV_BASE  
[EDI]UEFI_SEC_PEI_HAND_OFF.BOOT_FIRMWARE_VOLUME_SIZE = OEM_BFV_SIZE  
[EDI+sizeof(UEFI_SEC_PEI_HAND_OFF)].OEM_DATA_DWORD[0] = BIST
```

**Related Definitions**

The EBX register is fully preserved by this routine. This provides the possibility for the host environment to use the EBX register as a return address at which execution resumes following the completion of the procedure.

The procedure will use the build time value of AMD_CAR_STACK_FRAME_PAD to determine the size of the SEC to PEI handoff stack frame. The default pad value is zero, which allocates four bytes for saving the BIST value.

**Description**

This procedure is native assembler source file and is “stackless” in its operation. Therefore the interface uses a register passing model.

The purpose is to initialize the processor and cache system to establish a viable stack region prior to main memory being available. The available pre-memory stack region is divided among the processor cores according to application needs. It then maps them to global address space and sets the processor MTRRs\(^1\) accordingly. This routine must be run on all processor cores.

The procedure checks whether protected mode is enabled and if so, does not modify the Stack Segment register (SS). In this case the host environment must point SS to a GDT descriptor with base address = 0x0000_0000 before entering this procedure. The Stack Pointer (ESP) is set to contain a 32-bit memory offset. If Real Mode is being used, SS:ESP is set to point to a 16-bit execution-compatible Segment:Offset format. The upper 16 bits of ESP will be zeroes.

The procedure will create an instance of UEFI_SEC_PEI_HAND_OFF in the specified stack frame area.

The AARCH64 APUs enhanced with the Platform Security Processor (PSP) will not use the stack and very early macros. The PSP will initialize the DRAM.

---

1. MTRRs apply to the x86-64 Architecture.
Dependencies

The host environment must use this procedure and not rely on any other sources to create the stack region.

Registers destroyed: EAX, ECX, EDX, EDI, ESI

If 16-bit environment, also destroyed: DS, ES

Status Codes Returned

AGESA_SUCCESS The stack space has been allocated for this core.

AGESA_WARNING CPU_EVENT_STACK_REENTRY - A stack is in use from a previous invocation of AMD_ENABLE_STACK. The stack will be reset to empty.

AGESA_FATAL CPUEVENT_UNKNOWN_PROCESSOR_FAMILY - The stack cannot be created because the processor family is unknown.
AMD_DISABLE_UEFI_STACK

This procedure is used to remove the pre-memory stack from within the host environment.

Prototype

```
OEM_SEGMENT2_START
;DisableStack ; Host Environment Procedure
; Input: EBX - Return address
DisableStack PROC FAR PUBLIC
   AMD_DISABLE_UEFI_STACK
   jmp ebx
DisableStack ENDP
```

Parameters

```
EAX    OUT
```

Contains the AGESA_STATUS return code

Related Definitions

The EBX register is fully preserved by this routine. This provides the possibility for the host environment to use the EBX register as a return address to which execution resumes following the completion of the procedure.

Description

This procedure is native assembler source file and is “stackless” in its operation. Therefore the interface uses a register passing model.

Their purpose is to return the processor and cache system to a non-stack-enabled state. This procedure is expected to be executed only once at the point where main memory becomes available. It is expected that the UEFI PEI core has relocated the stack to memory and the MTRR map has been synchronized. Therefore, this routine will not modify the MCRR settings, but will just disable CAR mode. This procedure must be run on all processor cores. All cache lines are flushed.

The exit state for the BSP is described as follows:

- Processor Cache is enabled (CD bit is cleared).
- MTRRs used for execution cache are kept.
- Cache content is flushed (invalidated without write-back).
- Any family-specific clean-up done.
The AARCH64 APUs enhanced with the Platform Security Processor (PSP) will not use the stack and very early macros. The PSP will initialize the DRAM.

**Dependencies**

This procedure should only be invoked by the BSP. The host environment must use this procedure and not rely on any other sources to break down the stack region.

If executing in 16-bit code, the host environment must establish the “Big Real” mode of 32-bit addressing of data.

Registers destroyed: EAX, ECX, EDX, ESI, ESP, EDI

**Status Codes Returned**

AGESA_SUCCESS  The stack space has been disabled for this core.
13.2 General Service Procedures

These are procedures provided to the host environment as an aid in performing its tasks.

**AmdCreateStruct**

Creates a storage space for a parameter block of an AGESA™ software call entry.

**Prototype**

```c
AGESA_STATUS
AmdCreateStruct (  
    IN OUT AMD_INTERFACE_PARAMS *InterfaceParams  
);  
```

**Parameters**

*InterfaceParams*

Pointer to the parameter structure containing the descriptor of the structure to be created.

**Related Definitions**

```c
typedef struct {  
    IN    AMD_CONFIG_PARAMS          StdHeader;  
    IN    AGESA_STRUCT_NAME         AgesaFunctionName;  
    IN    ALLOCATION_METHOD         AllocationMethod;  
    IN OUT UINT32                    NewStructSize;  
    IN OUT VOID                      *NewStructPtr;  
} AMD_INTERFACE_PARAMS;  
```

This is the parameter containment structure for the AmdCreateStruct function. Along with the standard header defined in “Standard Header” on page 33, it contains:

*AgesaFunctionName*

Name or identifier of the structure to be created. This parameter must be filled by the caller.

*AllocationMethod*

Identifier for the method to use for allocating the structure storage space. This parameter must be filled by the caller.

*NewStructSize*

This is the size in bytes of the storage space. Upon return, this value indicates the size of the structure created. If the allocation method specified is “ByHost”, then this parameter must be filled by the caller to indicate the amount of storage the host has already allocated.
NewStructPtr

This is a pointer to the created structure. This value is set by the procedure for use by the caller. The content of the StdHeader is copied to the new structure.

typedef enum {
    AMD_INIT_RECOVERY,
    AMD_CREATE_STRUCT,
    AMD_INIT_EARLY,
    AMD_INIT_ENV,
    AMD_INIT_LATE,
    AMD_INIT_MID,
    AMD_INIT_POST,
    AMD_INIT_RESET,
    AMD_INIT_RESUME,
    AMD_RELEASE_STRUCT,
    AMD_S3LATE_RESTORE,
    AMD_S3_SAVE,
    AMD_GET_APIC_ID,
    AMD_GET_PCI_ADDRESS,
    AMD_IDENTIFY_CORE,
    AMD_READ_EVENT_LOG,
    AMD_GET_EXECACHE_SIZE,
    AMD_LATE_RUN_AP_TASK,
    AMD_IDENTIFY_DIMMS
} AGESA_STRUCT_NAME;

This is an enumerated list of structure names that can be created.

typedef enum {
    PreMemHeap,
    PostMemDram,
    ByHost
} ALLOCATION_METHOD;

This is an enumerated list of methods by which to allocate the storage space for the structure.

PreMemHeap Use this allocation method for calls that occur before the main memory is available. The AGESA™ software uses its internal heap sub-system to allocate space in the Cache-as-RAM storage area.

PostMemDram Use this allocation method for calls that occur after main memory is available. The call-out “AgesaAllocateBuffer” on page 151 is used to allocate storage space.

ByHost This allocation method is provided for the host environment to pre-allocate the structure storage space by their own means. The procedure does not attempt to allocate any storage space but still calls the structure initializer functions.
Caution: When using this method, the host environment takes the responsibility to assure and maintain the size of space allocated is sufficient for the target structure.

Note: When using this method, the StdHeader parameter value is used as the base of the storage area. This means that upon a successful completion of the initializer, the target structure definition overlays the initial content of the CREATE_STRUCT_PARAMS parameter structure. The AllocMethod, StructSize, and NewStruct values are no longer available. If the pre-allocated space is not sufficient for the target structure an error is returned and the CREATE_STRUCT_PARAMS content is retained.

Description

This procedure creates storage space for the indicated structure, then pre-initializes the structure with default values. The storage for the specific structure is allocated per the indicated method, then the initializer function for that structure is called.

Dependencies

The creation and removal of the structure storage depends upon the host environment calling procedure using the AmdCreateStruct and AmdReleaseStruct procedures. Failure to release a structure can cause undesired outcomes.

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AGESA_SUCCESS</td>
<td>The target structure has been initialized successfully.</td>
</tr>
<tr>
<td>AGESA_ERROR</td>
<td>The storage space for the target structure is insufficient or could not be allocated.</td>
</tr>
<tr>
<td>AGESA_FATAL</td>
<td>Unable to initialize structure storage due to unrecognized processor family.</td>
</tr>
</tbody>
</table>
AmdGet2DDataEye

Obtain the data eye results for the specified DIMM.

Prototype

AGESA_STATUS
AmdGet2DDataEye (
    IN OUT AMD_GET_DATAEYE *AmdGetDataEye
);  

Parameters

AmdGetDataEye

Pointer to a data structure containing the parameter information.

Related Definitions

typedef struct {
    IN AMD_CONFIG_PARAMS StdHeader;
    IN AMD_POST_PARAMS PostParamsPtr;
    IN UINT8 Socket;
    IN UINT8 MemChannelId;
    IN UINT8 DimmId;
    IN UINT8 DataEyeType;
    OUT UINT8 *DataEyeBuffer;
} AMD_GET_DATAEYE;

Socket

Number of the socket on which the desired DIMM is populated.

MemChannelId

The memory channel on which the desired DIMM is populated.

DimmId

The DIMM for which results are desired.

DataEyeType

Indicates whether to return the data eye results for reads or writes.

DataEyeBuffer

Provides the data eye results as a bitmap representing a composite data eye of all the DIMM byte lanes.

Description

Return the data eye bitmap for the DIMM requested. The bitmap is thirty one elements of thirty two bits each.
Data eye results are normalized relative to the 1D trained Center [+16, -15].
Dependencies

The coherent HyperTransport™ links must be operational so that all processors are available.

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

This service call must be made from the AmdInitPost wrapper, before memory structures are deallocated. (See “AmdInitPost” on page 115.)

Status Codes Returned

AGESA_SUCCESS        The function has completed successfully.
AmdGetApicId

Obtain the APIC address for the specified processor core.

Note: This procedure only applies to the x86-64 architecture APUs.

Prototype

AGESA_STATUS
AmdGetApicId (IN OUT AMD_APIC_PARAMS *AmdParamApic);

Parameters

AmdParamApic

Pointer to a data structure containing the parameter information.

Related Definitions

typedef struct {
  IN AMD_CONFIG_PARAMS StdHeader;
  IN UINT8 Socket;
  IN UINT8 Core;
  OUT BOOLEAN IsPresent;
  OUT UINT8 ApicAddress;
} AMD_APIC_PARAMS;

Socket

Number of the socket for which to determine the APIC address.

Core

Number of the processor core relative to the socket, for which to determine the APIC address.

IsPresent

Indicates whether the indicated Socket-Core is present in the system.

ApicAddress

The procedure stores the APIC address for the specified socket and core into this structure element.

Description

Determine the APIC ID or address of the specified processor core. Core numbers are relative to the socket regardless if the processor has multiple die or not.

Dependencies

The coherent HyperTransport™ links must be operational so that all processors are available.
This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

**Status Codes Returned**

- **AGESA_SUCCESS**  
  The function has completed successfully.
AmdGetAvailableExeCacheSize

Returns available cache size for execution caching in the pre-memory time frame.

Note: This procedure only applies to the x86-64 architecture APUs.

Prototype

AGESA_STATUS
AmdGetAvailableExeCacheSize (IN OUT AMD_GET_EXE_SIZE_PARAMS *AmdGetExeSizeParams);

Parameters

AmdGetExeSizeParams

Pointer to a data structure containing the parameter information.

Related Definitions

typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    OUT UINT32 AvailableExeCacheSize;
} AMD_GET_EXE_SIZE_PARAMS;

AvailableExeCacheSize

The number of bytes available for use as execution cache on the current core.

Description

During the pre-memory time frame, the amount of cache available for execution caching is
limited and can vary depending on the processor(s) installed in the system. This routine
returns the amount of cache available for use as code execution cache. The value pertains to
the current execution core. The customer can use this information to decide the best regions to
target for code execution cache. This routine can be executed on all CPU cores. This routine
applies to the pre-memory time period only. After main system memory is available, the
aforementioned limits are removed.

Dependencies

This procedure requires a stack. The host environment must use one of the provided service
functions to establish the stack environment prior to making the call to this procedure.

Status Codes Returned

AGESA_SUCCESS The function has completed successfully.
AmdGetPciAddress

Obtain the base PCI address for the specified processor die.

Prototype

AGESA_STATUS
AmdGetPciAddress (IN OUT AMD_GET_PCI_PARAMS *AmdParamGetPci);

Parameters

AmdParamGetPci

Pointer to a data structure containing the parameter information.

Related Definitions

typedef struct {
    IN AMD_CONFIG_PARAMS StdHeader;
    IN UINT8 Socket;
    IN UINT8 Module;
    OUT BOOLEAN IsPresent;
    OUT PCI_ADDR PciAddress;
} AMD_GET_PCI_PARAMS;

Socket

Number of the socket for which to determine the PCI address.

Module

Number of the die relative to the socket, for which to determine the PCI address.

IsPresent

Indicates if the indicated Socket-Module is present in the system.

PciAddress

The procedure stores the PCI address for the indicated processor module into this structure element. The PCI address includes the segment, bus, and device values. The function and register fields are set to zero.

Description

Determine the base PCI address for the specified processor die. Each die within a processor has a separate PCI device number.

Dependencies

The coherent HyperTransport™ links must be operational so that all processors are available.
This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

**Status Codes Returned**

- **AGESA_SUCCESS** The function has completed successfully.
AmdIdentifyCore

Identifies the current executing processor core.

Prototype

AGESA_STATUS
AmdIdentifyCore (IN OUT AMD_IDENTIFY_PARAMS *AmdParamIdentify);

Parameters

AmdParamIdentify

Pointer to a data structure containing the parameter information.

Related Definitions

typedef struct {
   IN AMD_CONFIG_PARAMS StdHeader;
   OUT UINT8 Socket;
   OUT UINT8 Module;
   OUT UINT8 Core;
} AMD_IDENTIFY_PARAMS;

Socket

The procedure sets this to the number of the socket containing this processor core.

Module

The procedure sets this to the number of the die relative to the socket on which this core resides.

Core

The procedure sets this to the number of this processor core relative to the socket.

Description

This procedure is used to identify the current processor core. The system address is returned as socket, die, and core. This information can be used to determine other system addresses, for example, PCI base address and APIC address.

Dependencies

The coherent HyperTransport™ links must be operational so that this processor available.

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.
Status Codes Returned

AGESA_SUCCESS    The function has completed successfully.
AmdIdentifyDimm

Identifies the current executing processor core.

Prototype

AGESA_STATUS
AmdIdentifyDimm (
    IN OUT AMD_IDENTIFY_DIMM *AmdDimmIdentify
);

Parameters

AmdDimmIdentify

Pointer to a data structure containing the parameter information.

Related Definitions

typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    IN    UINT64    MemoryAddress;
    OUT   UINT8     SocketId;
    OUT   UINT8     MemChannelId;
    OUT   UINT8     DimmId;
    OUT   UINT8     ChipSelect;
    OUT   UINT8     Bank;
    OUT   UINT32    Row;
    OUT   UINT16    Column;
} AMD_IDENTIFY_DIMM

MemoryAddress

This is the system address which is the target of the inquiry.

SocketId

The procedure sets this to the number of the socket containing the memory responding to the specified address.

MemChannelId

The procedure sets this to the number of the channel relative to the socket that contains the memory responding to the specified address.

DimmId

The procedure sets this to the number of the DIMM relative to the channel that contains the memory responding to the specified address.

ChipSelect

The procedure sets this to the number of the chip select relative to the DIMM that contains the memory responding to the specified address.
Bank

The procedure sets this to the number of the bank relative to the chip select that contains the memory responding to the specified address.

Row

The procedure sets this to the number of the row relative to the bank that contains the memory responding to the specified address.

Column

The procedure sets this to the number of the column relative to the bank that contains the memory responding to the specified address.

The SocketId, MemChannelId, and DimmId values are the same as those provided to the call-out “AgesaReadSpd” on page 159. The DIMM number is directly related to the chip-select control line emanating from the memory controller, as shown in Table 1 on page 160. If the DimmId is greater than the number of DIMMs per channel for that processor, then the DIMM is a quad rank DIMM and DimmId minus two should be used to identify the DIMM.

Description

This procedure is used to identify the Field Replaceable Unit (FRU) memory device (DIMM) that corresponds to the given memory address. This can be useful to locate the FRU that is responsible for a memory failure. The SocketId, MemChannelId, and DimmId parameters provide FRU identification.

This procedure also provides error location information within the FRU. This can be used to support additional error reporting, handling, or testing. For example, it is useful with error injection testing to be able to confirm the error location to the chip select, bank, row, and column location.

Dependencies

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

Status Codes Returned

AGESA_SUCCESS The function has completed successfully.
AGESA_BOUNDSCHK The provided system address is outside the range for the main memory.
AmdAddMmioMapping

User interface call to merge the requested MMIO range with the current processor MMIO address maps.

Prototype

```c
AGESA_STATUS
AmdAddMmioMapping(
    IN AMD_ADD_MMIO_PARAMS AmdAddMmioParams
);
```

Parameters

**AmdAddMmioParams**

Pointer to a data structure containing the parameter information.

Related Definitions

```c
typedef struct {
    IN AMD_CONFIG_PARAMS StdHeader;
    IN UINT64 BaseAddress;
    IN UINT64 Length;
    IN PCI_ADDR TargetAddress;
    IN AMD_MMIO_ATTRIBUTE Attributes;
} AMD_ADD_MMIO_PARAMS;
```

**StdHeader**

AMD standard Header structure. See “Standard Header” on page 33.

**BaseAddress**

This is the starting address of the requested MMIO range.

**Length**

This is the length of the range to allocate, in bytes.

**TargetAddress**

This is the PCIe® address of the device for which this range is allocated, and it provides the bus, device, and function of the target device.

**Attributes**

This indicates the attributes of the requested range.

```c
typedef struct {
    UINT8 MmioReadableRange:1;
    UINT8 MmioWriteableRange:1;
    UINT8 MmioPostedRange:1;
    UINT8 MmioSecuredRange:1;
    UINT8 :3;
    UINT8 OverrideExisting:1;
} AMD_MMIO_ATTRIBUTE;
```
} AMD_MMIO_ATTRIBUTE;

MmioReadableRange
The requested range supports reads.

MmioWriteableRange
The requested range supports writes.

MmioPostedRange
The requested range supports posted transactions.

MmioSecuredRange
The requested range is secured.

OverrideExisting
If this request overlaps an existing allocation which has different attributes, this request should override the attributes for that overlapping range. Otherwise, the recommended and default behavior is to consider conflicting attributes as an error.

Description
User interface call to update the MMIO address mappings to include a requested range.

Dependencies
This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AGESA_SUCCESS</td>
<td>The function has completed successfully.</td>
</tr>
<tr>
<td>AGESA_BOUNDS_CHK</td>
<td>One or more input parameters are invalid. For example, the TargetAddress does not correspond to any device in the system.</td>
</tr>
<tr>
<td>AGESA_ERROR</td>
<td>The requested range could not be added because there are not enough mapping resources.</td>
</tr>
</tbody>
</table>
AmdReadEventLog

User interface call to obtain the next event log entry.

Prototype

\[
\text{AGESA\_STATUS} \\
\text{AmdReadEventLog (} \\
\text{\hspace{1em} IN EVENT\_PARAMS *Event} \\
\text{\hspace{2em})};
\]

Parameters

\text{Event}

Pointer to a data structure containing the parameter information.

Related Definitions

\[
\text{typedef struct} \\
\text{\hspace{1em} {\{} \\
\text{\hspace{2em} IN AMD\_CONFIG\_PARAMS StdHeader;} \\
\text{\hspace{2em} OUT UINT32 EventClass;} \\
\text{\hspace{2em} OUT UINT32 EventInfo;} \\
\text{\hspace{2em} OUT UINT32 DataParam1;} \\
\text{\hspace{2em} OUT UINT32 DataParam2;} \\
\text{\hspace{2em} OUT UINT32 DataParam3;} \\
\text{\hspace{2em} OUT UINT32 DataParam4;} \\
\text{\hspace{1em} {\}} EVENT\_PARAMS;}\\n\]

\text{StdHeader}

AMD standard Header structure. See “Standard Header” on page 33.

\text{EventClass}

This is the AGESA\_STATUS value reported to the caller by the application. This should match the error returned so the caller can match up the log entry with the returned error status.

\text{EventInfo}

This is a unique identifier to specify the application. It has bit fields defined by the application that are unique. A returned value of zero indicates the log was empty.

\text{DataParam[1:4]}

These are 4 data values provided by the application for logging. The meaning of the data is application-specific. Unused parameters are padded with 0.

Further information about the logged events can be found in “Logged Error Messages” on page 283.
Description

User interface call to obtain the next event log entry. User should note that there may be more than one log entry created by an application and should not assume only the first entry relates to the error returned by the application. The AmdReadEventLog routine reads the oldest entry from the circular buffer and places that information to the structure pointed to by the parameter. The internal pointers are incremented to remove the entry from buffer so that a subsequent call returns the next entry from the buffer. If the buffer is empty, the EventInfo value will be zero.

Dependencies

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

Status Codes Returned

AGESA_SUCCESS The function has completed successfully.
AmdReleaseStruct

Clears a storage space from allocation for a parameter block of an AGESA™ software call entry.

Prototype

```c
AGESA_STATUS
AmdReleaseStruct (  
    IN OUT AMD_INTERFACE_PARAMS    *InterfaceParams
);
```

Parameters

`InterfaceParams`

Pointer to the parameter structure that contains the descriptor information about the structure to be released.

Related Definitions

`AMD_INTERFACE_PARAMS`

This structure is the same as was defined in “AmdCreateStruct” on page 81.

Description

This procedure releases the storage space previously allocated for the interface structure.

This procedure may invoke calls to the following call-outs:

- “AgesaDeallocateBuffer” on page 153.

Dependencies

The creation and removal of the structure storage depends upon the calling procedure using the AmdCreateStruct and AmdReleaseStruct procedures. Failure to release a structure can cause undesired outcomes.

Status Codes Returned

`AGESA_SUCCESS` The storage space was released successfully.
Chapter 14  Entry Point Procedures

Entry procedures are listed in time point order.

Warning: Only the published entry functions are assured to be available over time. Use of other procedure names by the host environment that are found by source code inspection is strongly discouraged. AMD reserves the right to modify or remove internal procedure names not published in this specification.

14.1 Recovery Branch Functions

These functions should be located in the protected “boot block” section of the flash ROM. They set the base functionality in preparation to execute a flash ROM update utility. Performance and capability are not optimized. These routines are designed to establish operating settings applicable for present a some future upgrades to the target processor. Because today’s code cannot possibly know about tomorrow’s upgrades, only a common minimum set of capability is attempted.
AmdInitReset

This procedure performs minimal basic processor initialization after a system reset.

**Prototype**

```
AGESA_STATUS
AmdInitReset (
    IN OUT AMD_RESET_PARAMS *ResetParams
);
```

**Parameters**

*ResetParams*

Pointer to the parameter structure described below.

**Related Definitions**

```
typedef struct {
    IN AMD_CONFIG_PARAMS StdHeader;
    IN EXECUTION_CACHE_REGION CacheRegion[3];  
    IN FCH_RESET_INTERFACE FchInterface;
} AMD_RESET_PARAMS;
```

**CacheRegion**

This is an array of three structures, each defining an execution cache region. These regions must be located in the non-volatile program storage, for example, flash ROM address space. Only the regions specified are enabled for cache. This means that if the host environment does not specify any executable cache regions, then no area of the flash ROM is cached, resulting in slower boot times.

**FchInterface**

This is a structure containing parameters related to the FCH controller hub that need to be applied at the reset time point.

```
typedef struct {
    IN OUT UINT32 ExeCacheStartAddr;
    IN OUT UINT32 ExeCacheSize;
} EXECUTION_CACHE_REGION;
```

Note: This cache structure only applies to the x86-64 architecture APUs. This parameter will be unused for AArch64 APUs.

---

1. Not applicable for the AArch64 APUs. Parameter will be unused.
**ExeCacheStartAddr**

Requested start address for the execution region. This start address may need to be adjusted to conform to alignment requirements. The adjusted start address is placed in this same location for inspection upon exit.

**ExeCacheSize**

Requested execution region size. This size may need to be adjusted to conform to alignment requirements. The adjusted size is placed in this same location for inspection upon exit. To not allocate a region, set the input parameters to zero (ExeCacheSize=0).

typedef struct {
    BOOLEAN     UmiGen2;
    BOOLEAN     SataEnable;
    BOOLEAN     IdeEnable;
    BOOLEAN     GppEnable;
    GPP_LINKMODE GppLinkConfig;
    BOOLEAN     Xhci0Enable;
    BOOLEAN     Xhci1Enable;
} FCH_RESET_INTERFACE;

**UmiGen2**

This item controls whether a GEN2 data rate of UMI (Unified Media Interface, the link between chipset Northbridge and Southbridge) is enabled or disabled.

**SataEnable**

This item controls the SATA control function. When set to TRUE, the SATA controller function will be enabled.

**IdeEnable**

This item controls whether the IDE controller is to be made hidden. A FALSE value means the IDE controller is hidden and the Combined Mode is disabled, and the SATA controller has full control of all 6 ports when operating in non-IDE mode; a TRUE value means the IDE controller is exposed and the Combined Mode is enabled, the SATA controller will have control over port 0 through port 3, the IDE controller controls port 4 and 5.

**GppEnable**

This item controls whether the GPP ports are initialized and enumerated. A FALSE value means the ports are disabled. A TRUE value means the ports will be initialized and their devices enumerated.
**GppLinkConfig**

This item controls GPP Port configuration. The item is initialized by “BLDCFG_FCH_GPP_LINK_CONFIG” on page 220 and is presented here for possible modification.

**Xhci0Enable**

This item controls whether XHCI controller zero is enabled. A FALSE value means the controller and its ports are disabled. A TRUE value means the controller is enabled.

**Xhci1Enable**

This item controls whether XHCI controller one is enabled. A FALSE value means the controller and its ports are disabled. A TRUE value means the controller is enabled. In order for XHCI controller one to be enabled, controller zero must be enabled.

**Description**

A minimal initialization of the processor core is performed. This procedure must be called by all processor cores. The code path separates the BSP from the APs and performs a separate and appropriate list of tasks for each class of core.

For the BSP, the following actions are performed:

- Internal heap sub-system initialization
- Primary non-coherent HyperTransport™ link initialization
- Return to the host environment to test for Recovery Mode.

The AP processor cores do not participate in the recovery process; however, they execute this routine after being released to execute by the BSP during the main boot process. Their actions include the following:

- Internal heap sub-system initialization
- Proceed to a wait loop waiting for commands from the BSP

If indicated by “BLDCFG_PCI_MMIO_BASE” on page 189, the extended MMIO configuration is initialized and PCI configuration accesses will use MMIO rather than port IO.

For the cache regions, up to three regions of execution cache can be allocated following the following rules:

1. Once a region is allocated, it cannot be de-allocated. However, it can be expanded.
2. At most, two of the three regions can be located above 1 MByte. A region failing this rule is ignored.
3. All region addresses must be at or above the 0x000D0000 linear address. A region failing this rule is ignored.
4. The address is aligned on a 32-KByte boundary. Starting addresses is rounded down to the nearest 32-KByte boundary.

5. The execution cache size must be a multiple of 32 KByte. Size is rounded up to the next multiple of 32 KByte.

6. A region must not span either the 1-MByte boundary or the 4-GByte boundary. Allocated size is truncated to not span the boundary.

7. The granted cached execution regions, address, and size are calculated based on the available cache resources of the processor core. Allocations are made up to the limit of cache available on the installed processor.

**Warning:** Enabling instruction cache outside of this interface can cause data corruption.

**Dependencies**

This procedure is expected to be executed soon after a system reset for the main boot path or resume path of execution. See “AGESA™ Core Software” on page 38 for more discussion about the boot sequence.

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

Because the heap system is not yet operational at the point of the interface call, the host environment must allocate the storage for the `AMD_RESET_PARAMS` structure before making the first call to `AmdCreateStruct`. See the “ByHost” allocation method.

The host environment MUST NOT modify the cache controls (MTRRs, etc) during the Cache-As-Ram time period (reset through final return from AmdInitPost).

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AGESA_SUCCESS</td>
<td>Early initialization completed successfully.</td>
</tr>
<tr>
<td>AGESA_WARNING</td>
<td>One or more of the execution cache allocation rules were violated, but an adjustment was made and space was allocated. A BIST error was found on one of the cores.</td>
</tr>
<tr>
<td>AGESA_ERROR</td>
<td>One or more of the execution cache allocation rules were violated, which resulted in a requested cache region to not be allocated. The storage space allocated for the <code>AMD_RESET_PARAMS</code> structure is insufficient.</td>
</tr>
</tbody>
</table>

For WARNING or ERROR, a message is logged with data indicating which region caused the issue and which rule was violated. Please refer to “Sub-Class: Processor” on page 295.
14.2 Boot Branch Functions

AmdInitEarly

This procedure establishes the program environment needed for the host environment to start the boot sequence.

Prototype

AGESA_STATUS
AmdInitEarly (IN OUT AMD_EARLY_PARAMS *EarlyParams);

Parameters

EarlyParams

Pointer to the parameter structure described below.

Related Definitions

typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    IN EXECUTION_CACHE_REGION CacheRegion[3]; 1
    IN PLATFORM_CONFIGURATION PlatformConfig;
    IN GNB_CONFIGURATION GnbConfig;
} AMD_EARLY_PARAMS;

CacheRegion

This is the same as described in “AmdInitReset” on page 101. At this time point the host environment may add additional cache regions to cover the main boot code. (See footnote).

PlatformConfig

A structure containing platform-specific operational characteristics. This structure is initially populated by the initializer with a copy of the same structure that was created at build time using the build configuration controls.

GnbConfig

A structure containing the platform description of any special handling needs for the graphics and PCIe® subsystems and operational limitations imposed by the platform.

1. Not applicable for the AArch64 APUs. Parameter will be unused. See also AmdInitReset.
typedef struct {
    IN PERFORMANCE_PROFILE PlatformProfile;
    IN UINT8 CoreLevelingMode;
    IN PLATFORM_CSTATE_MODES CStateMode;
    IN UINT32 CStatePlatformData;
    IN UINT16 CStateIoBaseAddress;
    IN PLATFORM_CPB_MODES CpbMode;
    IN BOOLEAN UserOptionDmi;
    IN BOOLEAN UserOptionPState;
    IN BOOLEAN UserOptionCrat;
    IN BOOLEAN UserOptionCdit;
    IN BOOLEAN UserOptionWhea;
    IN UINT32 PowerCeiling;
    IN BOOLEAN ForcePstateIndependent;
    IN UINT32 PstatesPsdPolicy;
    IN UINT32 CpuFrequencyLimit;
    IN PLATFORM_CONNECTED_STANDBY_MODES CfgPlatformConnectedStandbyMode;
    IN UINT32 NumberOfIoApics;
    IN PLATFORM_VRM_CONFIGURATION VrmProperties[MaxVrmType];
    IN BOOLEAN ProcessorScopeInSb;
    IN CHAR8 ProcessorScopeName0;
    IN CHAR8 ProcessorScopeName1;
    IN UINT8 GnbHdAudio;
    IN UINT8 AbmSupport;
    IN UINT8 DynamicRefreshRate;
    IN UINT8 LcdBackLightControl;
    IN UINT16 HtcTemperatureLimit;  
    IN UINT16 LhtcTemperatureLimit;
    IN DISPLAY_RESOLUTION Resolution;
    IN ACP_SIZE AcpSize;
    IN UINT32 BatteryBoostTune;
    IN UINT32 PkgPwrLimitAC;
    IN UINT32 PkgPwrLimitDC;
    IN UINT32 SystemConfiguration;
    IN PLATFORM_STAPM_CONFIGURATION PlatStapmConfig;
    IN UINT32 ThermCtlLimit;  1
    IN UINT64 AzaliaCodecVerbTable;
    IN UINT32 GnbAzI2sBusSelect;
    IN UINT32 GnbAzI2sBusPinConfig;
    IN UINT32 AzaliaSsid;
} PLATFORM_CONFIGURATION;

PlatformProfile

Several configuration settings for the processor depend upon other parts and
general designer choices for the system. The determination of these data points
is not standard for all platforms, so the host environment needs to provide these
to specify how the system is to be configured.

---

1. Family Specific parameter. Please refer to “Family Specific Details” on page 263.
CoreLevelingMode

Indicates how to balance the number of cores per processor. This value is initially declared by the build configuration element “BLDCFG_CORE_LEVELING_MODE” on page 192. The value is presented here for possible host environment modification.

CStateMode

The element specifies the operational mode of the C State feature. The mode in use will depend on the capabilities of the processor that is installed and the chipset on the motherboard. This value is initially declared by the build configuration element “BLDCFG_PLATFORM_CSTATE_MODE” on page 191. The value is presented here for possible host environment modification.

CStatePlatformData

This data element will contain required operational information for the type of C State chosen by the CStateMode parameter. This value is initially declared by the build configuration element “BLDCFG_PLATFORM_CSTATE_OPDATA” on page 191. The value is presented here for possible host environment modification.

CStateIoBaseAddress

This item specifies a free block of 8 consecutive bytes of I/O ports that can be used to allow the CPU to enter C States. This value is initially declared by the build configuration element “BLDCFG_PLATFORM_CSTATE_IO_BASE_ADDRESS” on page 191. The value is presented here for possible host environment modification.

CpbMode

This item provides for forcing Core Performance Boost (CPB) to disabled. This value is initially declared by the build configuration element “BLDCFG_PLATFORM_CPB_MODE” on page 192. The value is presented here for possible host environment modification.

UserOptionDmi

When set to TRUE, the DMI data table is generated. The default is TRUE if the DMI feature is installed, else it is FALSE.

See also “BLDOPT_REMOVE_DMI” on page 183.

UserOptionPState

When set to TRUE, the PState data tables are generated. The default is TRUE if the PState feature is installed, else it is FALSE. See also “BLDOPT_REMOVE_ACPI_PSTATES” on page 183.
**UserOptionCrat**

When set to TRUE, the CRAT tables are generated.

**UserOptionCdit**

When set to TRUE, the CDIT tables are generated.

**UserOptionWhea**

When set to TRUE, the WHEA data table is generated. The default is TRUE if the WHEA feature is installed, else it is FALSE. See also “BLDOPT_REMOVE_WHEA” on page 183.

**PowerCeiling**

Specifies a maximum power usage limit for the platform. Default is zero, indicating no limit. This parameter is provided to allow end users to artificially establish a ceiling limit on the amount of power the processor core will use. This is a numerical value representing a power ceiling in milliwatts. This value is initially declared by the build configuration element “BLDCFG_AMD_TDP_LIMIT” on page 209. The value is presented here for possible host environment modification.

**ForcePstateIndependent**

Force P-States to be independent for each core. This value is initially declared by the build configuration element “BLDCFG_FORCE_INDEPENDENT_PSD_OBJECT” on page 190. The value is presented here for possible host environment modification.

**CpuFrequencyLimit**

Specifies the maximum frequency that the CPU cores are allowed to use. This value is initially declared by the build configuration element “BLDCFG_CPU_FREQUENCY_LIMIT” on page 189. The value is presented here for possible host environment modification.

**CfgPlatformConnectedStandbyMode**

Specifies whether or not the Connected Standby feature is to be enabled. This value is initially declared by the build configuration element “BLDCFG_CPU_CONNECTED_STANDBY_MODE” on page 191. The value is presented here for possible host environment modification.

**NumberOfIoApics**

Specifies the number of IO APICs in the system. This value is initially declared by the build configuration element “BLDCFG_PLATFORM_NUM_IO_APICS” on page 189. The value is presented here for possible host environment modification.
VrmProperties

Collects platform voltage regulator module (VRM) properties that are required for power management.

ProcessorScopeInSb

This value is initially declared by the build configuration element “BLDCFG_PROCESSOR_SCOPE_IN_SB” on page 191. The value is presented here for possible host environment modification.

ProcessorScopeName0

This value is initially declared by the build configuration element “BLDCFG_PROCESSOR_SCOPE_NAME0” on page 190. The value is presented here for possible host environment modification.

ProcessorScopeName1

This value is initially declared by the build configuration element “BLDCFG_PROCESSOR_SCOPE_NAME1” on page 191. The value is presented here for possible host environment modification.

GnbHdAudio

This item customizes the GFX High Definition (HD) audio controller. This value is initially declared by the build configuration element “BLDCFG_CFG_GNB_HD_AUDIO” on page 210. The value is presented here for possible host environment modification.

AbmSupport

This item customizes the Ambient Brightness Monitor (ABM) back light control for LVDS and eDP. This value is initially declared by the build configuration element “BLDCFG_CFG_ABM_SUPPORT” on page 211. The value is presented here for possible host environment modification.

DynamicRefreshRate

This item specifies the minimum refresh rate in Hz for the embedded display panel. This value is initially declared by the build configuration element “BLDCFG_CFG_DYNAMIC_REFRESH_RATE” on page 211. The value is presented here for possible host environment modification.

LcdBackLightControl

This item customizes support for Pulse Width Modulation (PWM) backlight control. This value is initially declared by the build configuration element “BLDCFG_CFG_LCD_BACK_LIGHT_CONTROL” on page 212. The value is presented here for possible host environment modification.
AcpSize

This item customizes support for Audio Co-Processor (ACP). This value is initially declared by the build configuration element “BLDCFG_ACP_SIZE” on page 212. The value is presented here for possible host environment modification.

```c
typedef struct {
    IN PLATFORM_CONTROL_FLOW PlatformControlFlowMode;
    IN BOOLEAN Use32ByteRefresh;
    IN BOOLEAN UseVariableMctIsocPriority;
    IN ADVANCED_PERFORMANCE_PROFILE AdvancedPerformanceProfile;
    IN MEMORY_PERFORMANCE_PROFILE MemoryPowerPolicy;
    IN BOOLEAN NbPstatesSupported;
} PERFORMANCE_PROFILE;
```

**PlatformControlFlowMode**

This value is used to select the optimum flow control method for the platform. This value is initially declared by the build configuration element “BLDCFG_PLATFORM_CONTROL_FLOW_MODE” on page 195. The value is presented here for possible host environment modification.

**UseVariableMctIsocPriority**

System chipsets may employ the Isochronous data channels for special packets to improve performance. This value is initially declared by the build configuration element “BLDCFG_USE_VARIABLE_MCT_ISOC_PRIORITY” on page 204. The value is presented here for possible host environment modification.

**Use32ByteRefresh**

This feature provides the refresh packet size to better optimize the Isochronous data channel performance. This value is initially declared by the build configuration element “BLDCFG_USE_32_BYTE_REFRESH” on page 202. The value is presented here for possible host environment modification.

**NbPstatesSupported**

This feature provides an indication of desired processor NB P-States setting. This value is initially declared by the build configuration element “BLDCFG_NB_PSTATES_SUPPORTED” on page 196. The value is presented here for possible host environment modification.

---

1. Family Specific parameter. Please refer to “Family Specific Details” on page 263.
typedef struct {
    IN UINT32 CurrentLimit;
    IN UINT32 LowPowerThreshold;
    IN UINT32 SlewRate;
    IN BOOLEAN HiSpeedEnable;
    IN UINT32 MaximumCurrentLimit;
    IN UINT16 SviOcpLevel;
} PLATFORM_VRM_CONFIGURATION;

typedef enum {
    CoreVrm,
    NbVrm,
    MaxVrmType
} PLATFORM_VRM_TYPE;

The platform configuration contains an array of PLATFORM_VRM_CONFIGURATION, with one structure for each voltage plane. The first element, CoreVrm, contains the VRM properties for the CPU Cores. The second element, NbVrm, contains the VRM properties for the processor Northbridge and the third contains the VRM properties for the Graphics processor. Each member of PLATFORM_VRM_CONFIGURATION has a build configuration item for each of the VRMs rails. Use the build configuration item corresponding to the CoreVrm or NbVrm or GFX to set the VRM properties for each. Not all processors support all possible settings; see processor specific documentation for details.

CurrentLimit
Provides the VRM current limit. This value is initially declared by the build configuration element “BLDCFG_VRM_CURRENT_LIMIT” on page 187 for the VRM property set. The value is presented here for possible host environment modification.

LowPowerThreshold
Provides information about the VRM’s low power mode. This value is initially declared by the build configuration element “BLDCFG_VRM_LOW_POWER_THRESHOLD” on page 187 for the VRM property set. The value is presented here for possible host environment modification.

SlewRate
Provides the rate at which the VRM can transition. This value is initially declared by the build configuration element “BLDCFG_VRM_SLEW_RATE” on page 188 for the VRM property set. The value is presented here for possible host environment modification.
HiSpeedEnable

The VRM bus interface is high speed. This value is initially declared by the build configuration element “BLDCFG_VRM_HIGH_SPEED_ENABLE” on page 188 for the VRM property set. The value is presented here for possible host environment modification.

MaximumCurrentLimit

Provides maximum current limit for the VRM. This value is initially declared by the build configuration element “BLDCFG_VRM_MAXIMUM_CURRENT_LIMIT” on page 188 for the VRM property set. The value is presented here for possible host environment modification.

SviOcpLevel

Provides the current level at which over current protection (OCP) is initiated by the VRM. This value is initially declared by the build configuration element “BLDCFG_VRM_SVI_OCP_LEVEL” on page 189 for the VRM property set. The value is presented here for possible host environment modification.

typedef struct {
    IN PCIe_COMPLEX_DESCRIPTOR *PcieComplexList;
    IN UINT8 PsppPolicy;
} GNB_CONFIGURATION;

For processors with PCIe® support, these items provide customization of PCIe® related settings. See “Graphics Northbridge Details” on page 348 for more details.

PcieComplexList

Provide all customizations for the PCIe® topology.

PsppPolicy

Provide the desired performance vs. power policy.

typedef struct {
    IN UINT32 Flags;
    IN UINT32 SocketId;
    IN PCIe_PORT_DESCRIPTOR *PciePortList;
    IN PCIe_DDI_DESCRIPTOR *DdiLinkList;
    IN VOID *Reserved;
} PCIe_COMPLEX_DESCRIPTOR;

Flags

Indicates if this is the last descriptor in the list.
(SocketId)

The socket ID for the processor which hosts this PCIe® topology.

(PciePortList)

A list of PCIe ports and their customization data.

(DdiLinkList)

A list of DDI links and their customization data.

Description

A full initialization of the processor is performed. Action details differ for the BSP and AP processor cores.

For the BSP, the following actions are performed:

- Full HyperTransport™ link initialization, coherent and non-coherent
- Processor register loading
- Microcode patch load
- Errata workaround processing
- Launch all processor cores
- Configure the processor power management capabilities
- Request a warm reset if needed

For the AP, the following actions are performed:

- processor register loading
- microcode patch load
- errata workaround processing
- configure the processor power management capabilities

Dependencies

This procedure is expected to be called before main memory initialization and before the system warm reset. Prior to this, the basic configuration done by the AmdInitReset routine must be completed.

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

The processes performed at this time point require communication between processor cores. The host environment must recognize that all processor cores are running in parallel and avoid activities that might interfere with the core-to-core communication, such as modifying the MTRR settings or writing to the APIC registers.
Status Codes Returned

AGESA_SUCCESS  The function has completed successfully.
AGESA_WARNING  One of more of the allocation rules were violated, but an adjustment was made and space was allocated.
AGESA_ERROR    One or more of the allocation rules were violated, which resulted in a requested cache region to not be allocated.
AGESA_FATAL    A processor is detected which has no family support installed in the current build.
AmdInitPost

Initialize system memory. Transition boot from pre-memory phase to post-memory phase.

Prototype

AGESA_STATUS
AmdInitPost (IN OUT AMD_POST_PARAMS *PostParams);

Parameters

PostParams

Pointer to a data structure containing the parameter information.

Related Definitions

typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    IN PLATFORM_CONFIGURATION PlatformConfig;
    IN MEM_PARAMETER_STRUCT MemConfig;
    IN GNB_POST_CONFIGURATION GnbPostConfig;
} AMD_POST_PARAMS;

PlatformConfig

A structure containing platform-specific operational characteristics. This is the same structure described in “AmdInitEarly” on page 105.

MemConfig

A structure containing platform configuration descriptions pertaining to the memory channels.

typedef struct {
    // Basic (Return parameters)
    // This section contains the outbound status of the memory init
    OUT BOOLEAN GStatus[GsbEOL];
    OUT UINT32 HoleBase;
    OUT UINT32 Sub4GCacheTop;
    OUT UINT32 Sub1THoleBase;
    OUT UINT32 SysLimit;
    OUT DIMM_VOLTAGE DDR3Voltage;
    OUT VDDP_VDDR_VOLTAGE VddpVddrVoltage;
    OUT UINT8 ExternalVrefValue;
    OUT MEM_DATA_STRUCT *MemData;
    // Memory Map/Mgt.
    IN UINT16 BottomIo;
    IN BOOLEAN LimitMemoryToBelow1Tb;
    // Dram Timing
}
Chapter 14  Entry Point Procedures

IN  USER_MEMORY_TIMING_MODE UserTimingMode;
IN  MEMORY_BUS_SPEED MemClockValue;
// Dram Configuration
IN  BOOLEAN EnableBankSwapOnly; 1
IN  BOOLEAN EnableBankIntlv;
IN  BOOLEAN EnableNodeIntlv;
IN  BOOLEAN EnableChannelIntlv;
IN  BOOLEAN EnableD11PDBypassMode;
IN  BOOLEAN EnableEccFeature;
IN  BOOLEAN EnablePowerDown;
IN  DRAM_MAXIMUM_ACTIVATE_CONT DramMacDefault;
IN  BOOLEAN EnableExtendedTemperatureRange;
IN  BOOLEAN EnableOnLineSpareCtl;
IN  UINT8 *TableBasedAlterations;
IN  PSO_TABLE *PlatformMemoryConfiguration;
IN  BOOLEAN EnableParity;
IN  BOOLEAN EnableBankSwizzle;
IN  BOOLEAN EnableMemClr;
IN  UMA_VERSION UmaVersion; 1
IN  UMA_MODE UmaMode;
IN  OUT UINT32 UmaSize;
OUT UINT64 UmaBase;
IN  BOOLEAN MemRestoreCtl;
IN  BOOLEAN SaveMemContextCtl;
IN  OUT AMD_S3_PARAMS MemContext;
IN  BOOLEAN IsCapsuleUpdate;
IN  BOOLEAN ExternalVrefCtl;
IN  FORCE_TRAIN_MODE ForceTrainMode;
IN  TECHNOLOGY_TYPE DimmTypeUsedInMixedConfig;
IN  BOOLEAN AmpEnable;
IN  BOOLEAN AmpWarningMsgEnable;
OUT AMP_STATUS AmpStatus;
OUT AMP_DIMM_VOLTAGE AmpVoltage;
IN  BOOLEAN DramDoubleRefreshRate;
IN  PMU_TRAIN_MODE PmuTrainMode;
IN  BOOLEAN CfgEccRedirection; 2
IN  UINT16 CfgScrubDramRate;
IN  UINT16 CfgScrubL2Rate;
IN  UINT16 CfgScrubL3Rate;
IN  UINT16 CfgScrubICRate;
IN  UINT16 CfgScrubDCRate;
IN  BOOLEAN CfgEccSyncFlood;
IN  UINT16 CfgEccSymbolSize;
IN  BOOLEAN CfgDqsTrainingControl
IN  BOOLEAN CfgUmaAbove4G;
IN  UMA_ALIGNMENT CfgUmaAlignment;
IN  BOOLEAN CfgMemoryAllClocksOn;
IN  UINT32 CfgMemoryBusFrequencyLimit;

1. Family Specific parameter. Please refer to “Family Specific Details” on page 263.
2. These features are not new, but are now exposed at the API level for modification.
### MEM_PARAMETER_STRUCT

```c
IN UINT32  CfgPowerDownMode;
IN BOOLEAN  CfgIgnoreSpdChecksum;
IN BOOLEAN  CfgMemoryModeUnganged;
IN BOOLEAN  CfgMemoryQuadRankCapable;
IN BOOLEAN  CfgMemoryRDimmCapable;
IN BOOLEAN  CfgMemoryLRDimmCapable;
IN BOOLEAN  CfgMemoryUDimmCapable;
IN BOOLEAN  CfgMemorySODimmCapable;
IN TECHNOLOGY_TYPE  CfgDimmTypeUsedInMixedConfig;
IN BOOLEAN  CfgDramDoubleRefreshRateEn;
IN BOOLEAN  DimmTypeDddr4Capable;
IN BOOLEAN  DimmTypeDddr3Capable;
IN UINT16  CustomVddioSupport;\(^1\)
} MEM_PARAMETER_STRUCT;
```

Note: some minor details may differ from the implementation. Please see the internal documentation for full details.

#### GStatus

Global Status. An array of indicators of various conditions found during memory initialization. The full definition of indicators can be found in the AGESA.H file.

#### HoleBase

This value is associated with BottomIO and usually has the same value as BottomIO. However, conditions can occur where the BottomIO value must be changed and then this value reflects the actual base used. They may occur when new PCI cards are installed, which require more IO space.

The value represents address bits 8 through 39 of the system address where the sub 4-Gbyte DRAM hole for HW remapping begins (BASE[39:8]). A value of zero indicates that the remapping is disabled.

#### Sub4GCacheTop

This value represents the address of the end of the memory zone located below the 4-Gbyte boundary that is able to be cached. This may or may not be same as HoleBase or BottomIO.

The value is the address of the last byte of cached memory below the 4-Gbyte boundary.

#### Sub1THoleBase

This value represents address bits 16 through 47 of the system address where the memory hole located below the 1 terabyte (TByte) boundary begins. This output is only valid if SysLimit is greater than 1 TByte.

---

1. Family Specific parameter. Please refer to “Family Specific Details” on page 263.
SysLimit

This value represents address bits 8 through 39 of the system address where the last byte of physical system memory is located. (LIMIT[39:8])

Ddr3Voltage

This output provides the DDR3 voltage for the system.

VddpVDDRVoltage

This item specifies the voltage to be supplied to the memory PHY power pins. If the IsValid element is TRUE, the host platform is expected to adjust the VRM to supply the indicated voltage. This check should be made during processing of the AgesaCallOut AgesaHookBeforeDramInit.

typedef struct {
  BOOLEAN IsValid;
  MEMORY_PHY_VOLTAGE Voltage; BOOLEAN AmpVoltageValid;
} VDDP_VDDR_VOLTAGE;

IsValid

Specifies if the memory PHY voltage in the next parameter is to be used.

TRUE - Valid, make the change. FALSE - Do not change voltage.

Voltage

Specifies the memory PHY voltage to be used. For values, see “BLDCFG_MEMORY_PHY_VOLTAGE” on page 200.

MemData

This is a pointer to an internal data structure used by the memory initialization code. This pointer is provided for use by expert diagnosticians only.

LimitMemoryToBelow1TB

This item allows memory to be limited below 1 TByte, if needed for certain operating systems. This value is initially declared by the build configuration element “BLDCFG_LIMIT_MEMORY_TO_BELOW_1TB” on page 202. The value is presented here for possible host environment modification.

EnableBankIntlv

Enables the system to use the DRAM bank (also known as chip-select) interleaving feature. This value is initially declared by the build configuration element “BLDCFG_MEMORY_ENABLE_BANK_INTERLEAVING” on page 198. The value is presented here for possible host environment modification.
EnableNodeIntlv

Enables the system to use the memory node interleaving feature. This value is initially declared by the build configuration element “BLDCFG_MEMORY_ENABLE_NODE_INTERLEAVING” on page 198. The value is presented here for possible host environment modification.

EnableChannelIntlv

Enables the system to use the memory channel interleaving feature. This value is initially declared by the build configuration element “BLDCFG_MEMORY_CHANNEL_INTERLEAVING” on page 198. The value is presented here for possible host environment modification.

DramMacDefault

This item sets the maximum memory row activates when the Maximum Activates Count (MAC) value is not present in the SPD. This value is initially declared by the build configuration element “BLDCFG_MEMORY_ALTERNATIVE_MAX_ACTIVATE_COUNT” on page 203. The value is presented here for possible host environment modification.

EnableExtendedTemperatureRange

This control allows the DIMM refresh rate to be adjusted depending upon the local DIMM temperature; increasing the refresh rate at higher temperatures. This value is initially declared by the build configuration element “BLDCFG_MEMORY_EXTENDED_TEMPERATURE_RANGE” on page 204. The value is presented here for possible host environment modification.

EnableOnLineSpareCtl

The item controls the operation of the On-line Spare feature. This feature is recommended only for expert users and is described in the BIOS and Kernel Developer's Guides (BKDG).

This value is initially declared by the build configuration element “BLDCFG_ONLINE_SPARE” on page 199. The value is presented here for possible host environment modification.

EnableParity

Use parity error detection if available on the DIMMs.

This value is initially declared by the build configuration element “BLDCFG_MEMORY_PARITY_ENABLE” on page 199. The value is presented here for possible host environment modification.
EnableBankSwizzle

This value is initially declared by the build configuration element “BLDCFG_BANK_SWIZZLE” on page 199. The value is presented here for possible host environment modification.

EnableMemClr

This value is initially provided based on installed processor support. The value is presented here for possible host environment modification.

UserTimingMode

Selects the timing mode.

This value is initially declared by the build configuration element “BLDCFG_TIMING_MODE_SELECT” on page 205. The value is presented here for possible host environment modification.

MemClockValue

Selects the memory-clock frequency.

This value is initially declared by the build configuration element “BLDCFG_MEMORY_CLOCK_SELECT” on page 205. The value is presented here for possible host environment modification.

EnableDllPDBypassMode

Enables low power mode for soldered down memory systems which follow the low power guidelines. This value is initially declared by the build configuration element “BLDCFG_DDR_PHY_DLL_BYPASS_MODE” on page 200. The value is presented here for possible host environment modification.

EnableEccFeature

Enables the system to use the ECC feature. This value is initially declared by the build configuration element “BLDCFG_ENABLE_ECC_FEATURE” on page 200. The value is presented here for possible host environment modification.

EnablePowerDown

This is a power conservation option whose value is initially declared by the build configuration element “BLDCFG_MEMORY_POWER_DOWN” on page 204. The value is presented here for possible host environment modification.

TableBasedAlterations

This is a pointer to an array of data bytes describing desired modifications to register settings. The format of this data table is described in “Memory Details” on page 297.
PlatformMemoryConfiguration

This is a pointer to a table that contains platform specific settings such as MemClk routing and the number of DIMM slots per channel. By default this will point to default conservative settings. This is presented here for possible host environment modification. The format of this data table is described in “Platform Specific Override” on page 300.

UmaMode

Specifies whether to allocate memory for UMA support. The value is initially declared by the build configuration element “BLDCFG_UMA_ALLOCATION_MODE” on page 201. The value is presented here for possible host environment modification.

UmaSize

The amount of memory requested. This is updated to reflect the amount of memory allocated. The value is initially declared by the build configuration element “BLDCFG_UMA_ALLOCATION_SIZE” on page 201. The value is presented here for possible host environment modification.

UmaBase

This output provides the 64 bit base address of the allocated UMA region.

MemRestoreCtl

Specifies whether to restore previously saved training configuration rather than performing training.

SaveMemContextCtl

Specifies whether to update the memory context output with the training configuration. This data may be saved in non-volatile storage.

MemContext

The memory context to either restore or output.

IsCapsuleUpdate

Specifies that the current boot has capsule data contained in the system memory. This will prevent the capsule data from being cleared during memory initialization.

FALSE - This is not a capsule reboot (default).
TRUE - This is a capsule reboot.

ExternalVrefCtl

Specifies the control of external Vref for 2D memory training. The value is initially declared by the build configuration element
“BLDCFG_ENABLE_EXTERNAL_VREF_FEATURE” on page 202. The value is presented here for possible host environment modification.

**ForceTrainMode**

Specifies whether to force memory training to the specified mode.

- 0 - Force 1D memory training for all configurations.
- 1 - Force 2D memory training for all configurations.
- 2 - Auto, the memory training mode will be selected automatically (default).

**DimmTypeUsedInMixedConfig**

Specifies how to handle installations of mixed memory technology. The value is initially declared by the build configuration element “BLDCFG_DIMM_TYPE_USED_IN_MIXED_CONFIG” on page 202. The value is presented here for possible host environment modification.

**AmpEnable**

Specifies whether AMP memory overclocking is to be enabled.

- TRUE - Enabled. FALSE - Disabled (default).

**AmpWarningMsgEnable**

Specifies to provide warning events if the AMP capability does not match the desired AMP mode.

- TRUE - Generate warning events to the event log.
- FALSE - Suppress warning events (default).

**AmpStatus**

Reports whether AMP memory overclocking is enabled. Warning status is also provided for error reporting. The warning status is set here regardless of the state of AmpWarningMsgEnable.

```c
typedef struct {
    BOOLEAN AmpVoltageValid;
    BOOLEAN AmpSupportDetectedButNotEnabled;
    BOOLEAN AmpSelectedButNotEnabled;
} AMP_STATUS;
```

**AmpVoltageValid**

The memory voltage is reported in AmpVoltage.

- TRUE - Valid. FALSE - Use Ddr3Voltage.

**AmpSupportDetectedButNotEnabled**

AMP support was detected, but not enabled.

- TRUE - Warning present. FALSE - No warning.
AmpSelectedButNotEnabled

AMP support was selected, but could not be enabled.

TRUE - Warning present. FALSE - No warning.

AmpVoltage

When the value of AmpStatus.AmpVoltageValid is TRUE, this specifies the memory DIMM AMP voltage.

DramDoubleRefreshRate

Specifies if the calculated memory refresh rate should be doubled (i.e. time period between refresh cycles cut in half).

PmuTrainMode

Specifies the memory data bus training mode which will be performed by the PMU. The value is initially declared by the build configuration element “BLDCFG_PMU_TRAINING_MODE” on page 208. The value is presented here for possible host environment modification.

CfgEccRedirection

This value is initially declared by the build configuration element “BLDCFG_ECC_REDIRECTION” on page 200. The value is presented here for possible host environment modification.

CfgScrubDramRate

This value is initially declared by the build configuration element “BLDCFG_SCRUB_DRAM_RATE” on page 206. The value is presented here for possible host environment modification.

CfgScrubL2Rate

This value is initially declared by the build configuration element “BLDCFG_SCRUB_L2_RATE” on page 207. The value is presented here for possible host environment modification.

CfgScrubL3Rate

This value is initially declared by the build configuration element “BLDCFG_SCRUB_L3_RATE” on page 207. The value is presented here for possible host environment modification.

CfgScrubIcRate

This value is initially declared by the build configuration element “BLDCFG_SCRUB_IC_RATE” on page 207. The value is presented here for possible host environment modification.
CfgScrubDcRate

This value is initially declared by the build configuration element “BLDCFG_SCRUB_DC_RATE” on page 207. The value is presented here for possible host environment modification.

CfgEccSyncFlood

This value is initially declared by the build configuration element “BLDCFG_ECC_SYNC_FLOOD” on page 207. The value is presented here for possible host environment modification.

CfgEccSymbolSize

This value is initially declared by the build configuration element “BLDCFG_ECC_SYMBOL_SIZE” on page 208. The value is presented here for possible host environment modification.

CfgDqsTrainingControl

This value is initially declared by the build configuration element “BLDCFG_DQS_TRAINING_CONTROL” on page 205. The value is presented here for possible host environment modification.

CfgUmaAbove4G

This value is initially declared by the build configuration element “BLDCFG_UMA_ABOVE4G_SUPPORT” on page 201. The value is presented here for possible host environment modification.

CfgUmaAlignment

This value is initially declared by the build configuration element “BLDCFG_UMA_ALIGNMENT” on page 201. The value is presented here for possible host environment modification.

CfgMemoryAllClocksOn

This value is initially declared by the build configuration element “BLDCFG_MEMORY_ALL_CLOCKS_ON” on page 199. The value is presented here for possible host environment modification.

CfgMemoryBusFrequencyLimit

This value is initially declared by the build configuration element “BLDCFG_MEMORY_BUS_FREQUENCY_LIMIT” on page 196. The value is presented here for possible host environment modification.

CfgPowerDownMode

This value is initially declared by the build configuration element “BLDCFG_POWER_DOWN_MODE” on page 205. The value is presented here for possible host environment modification.
CfgIgnoreSpdChecksum

This value is initially declared by the build configuration element “BLDCFG_IGNORE_SPD_CHECKSUM” on page 206. The value is presented here for possible host environment modification.

CfgMemoryModeUnganged

This value is initially declared by the build configuration element “BLDCFG_MEMORY_MODE_UNGANGED” on page 196. The value is presented here for possible host environment modification.

CfgMemoryQuadRankCapable

This value is initially declared by the build configuration element “BLDCFG_MEMORY_QUAD_RANK_CAPABLE” on page 196. The value is presented here for possible host environment modification.

CfgMemoryRDimmCapable

This value is initially declared by the build configuration element “BLDCFG_MEMORY_RDIMM_CAPABLE” on page 197. The value is presented here for possible host environment modification.

CfgMemoryLRDimmCapable

This value is initially declared by the build configuration element “BLDCFG_MEMORY_LRDIMM_CAPABLE” on page 197. The value is presented here for possible host environment modification.

CfgMemoryUDimmCapable

This value is initially declared by the build configuration element “BLDCFG_MEMORY_UDIMM_CAPABLE” on page 198. The value is presented here for possible host environment modification.

CfgMemorySODimmCapable

This value is initially declared by the build configuration element “BLDCFG_MEMORY_SODIMM_CAPABLE” on page 197. The value is presented here for possible host environment modification.

CfgDimmTypeUsedMixedConfig

This value is initially declared by the build configuration element “BLDCFG_DIMM_TYPE_USED_IN_MIXED_CONFIG” on page 202. The value is presented here for possible host environment modification.

CfgDramDoubleRefreshRateEn

This value is initially declared by the build configuration element “BLDCFG_DRAM_DOUBLE_REFRESH_RATE” on page 203. The value is presented here for possible host environment modification.
typedef struct {
    IN UINT8 IgpuEnableDisablePolicy;
} GNB_POST_CONFIGURATION;

*IgpuEnableDisablePolicy*

Specifies whether to enable or disable the processor’s internal graphics when discrete graphics cards are present. The value is initially declared by the build configuration element “BLDCFG_IGPU_ENABLE_DISABLE_POLICY” on page 216. The value is presented here for possible host environment modification.

**Description**

The main system memory is located, initialized, and brought on-line. The processors are prepared for full operation and control by the host environment. Action details differ for the BSP and AP processor cores.

For the BSP, the following actions are performed:

- Full memory initialization and configuration. BSP is the master for this process and may delegate some tasks to APs.
- Check the BIST status of the BSP
- AP collection of data for use later.
- Transfer the HOBs including the artifact data out of the pre-memory cache storage into a temporary holding buffer in the main memory.
- Shut down the APs.
- Prepare for the host environment to begin main boot activity.
- Disable the pre-memory stack.

For the APs, the following actions are performed:

- Check the BIST status of the AP
- Report core identity information.
- Execute indicated memory initialization processes as directed.
- Disable the pre-memory stack.
- Prepare to halt, giving control to host environment.
The exit state for the APs is described as follows:

- Memory region 00000—9FFFF MTRRs\(^1\) are set as WB memory.
- Memory region A0000—DFFFF MTRRs are set as UC IO.
- Memory region E0000—FFFFF MTRRs are set as UC memory.
- MTRRs used for execution cache are cleared.
- Processor Cache is disabled (CD bit is set).
- Top-of-Memory (TOM) set to the system top of memory as determined by the memory initialization routines.
- System lock command is enabled.
- Any family-specific clean-up done.

The entire range of system memory is enabled for Write-Back cache.

The fixed MTRRs and the variable MTRRs[7:6] are not changed in order to leave in place any flash ROM region currently set for Write-Protect execution cache.

**Dependencies**

This procedure is called after the host environment has determined that a normal boot to operating system should be performed after any system warm reset is completed and after the configuration done by AmdInitEarly has completed.

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

The processes performed at this time point require communication between processor cores. The host environment must recognize that all processor cores are running in parallel and avoid activities that might interfere with the core-to-core communication, such as modifying the MTRR settings or writing to the APIC registers.

**Status Codes Returned**

- AGESA_SUCCESS The function has completed successfully.
- AGESA_ALERT A BIST Error was observed.
- AGESA_WARNING
- AGESA_ERROR
- AGESA_FATAL

\(^1\) MTRRs apply to the x86-64 Architecture.
AmdInitEnv

This procedure closes down the pre-memory operations and transfers any artifact data into main memory.

Prototype

AGESA_STATUS
AmdInitEnv (IN OUT AMD_ENV_PARAMS *EnvParams);

Parameters

EnvParams

Pointer to a data structure containing the parameter information.

Related Definitions

typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    IN PLATFORM_CONFIGURATION PlatformConfig;
    IN GNB_ENV_CONFIGURATION GnbEnvConfiguration;
    IN FCH_INTERFACE FchInterface;
} AMD_ENV_PARAMS;

PlatformConfig

A structure containing platform-specific operational characteristics. This is the same structure described in “AmdInitEarly” on page 105.

GnbEnvConfiguration

A structure containing all the required input configuration settings for GNB initialization at the AmdInitEnv stage.

FchInterface

A structure containing all the required input configuration settings for FCH initialization at the AmdInitEnv stage.
IN UINT16   LvdsMaxPixelClockFreq;
IN UINT32   LcdBitDepthControlValue;
IN UINT8    Lvds24bbpPanelMode;
IN LVDS_MISC_CONTROL LvdsMiscControl;
IN UINT16   PcieRefClkSpreadSpectrum;
IN BOOLEAN  GnbRemoteDisplaySupport;
IN UINT8    LvdsMiscVoltAdjustment;
IN DISPLAY_MISC_CONTROL DisplayMiscControl;
IN DP_FIXED_VOLT_SWING_TYPE DpFixedVoltSwingType;
IN UINT32   GpuFrequencyLimit;
IN UINT8    EDPv1_4VSMode; 1
IN UINT8    ExtHDMIreDrvSlvAddr;
IN UINT8    ExtHDMIreDrvRegNum;
IN UINT64   ExtHDMIRegSetting;
} GNB_ENV_CONFIGURATION;

Gnb3dStereoPinIndex

This item configures which pin the platform uses for Stereo 3D. This value is initially declared by the build configuration element “BLDCFG_STEREO_3D_PINOUT” on page 212. The value is presented here for possible host environment modification.

IommuSupport

This item configures IOMMU support. The value is initially declared by the build configuration element “BLDCFG_IOMMU_SUPPORT” on page 213. The value is presented here for possible host modification.

LvdsSpreadSpectrum

This item configures LVDS spread spectrum support. The value is initially declared by the build configuration element “BLDCFG_GFX_LVDS_SPREAD_SPECTRUM” on page 213. The value is presented here for possible host modification.

LvdsSpreadSpectrumRate

This item configures the LVDS spread spectrum frequency. The value is initially declared by the build configuration element “BLDCFG_GFX_LVDS_SPREAD_SPECTRUM_RATE” on page 213. The value is presented here for possible host modification.

LvdsPowerOnSeqDigonToDe

This item configures panel initialization timing. The value is initially declared by the build configuration element “BLDCFG_LVDS_POWER_ON_SEQ_DIGON_TO_DE” on page 213. The value is presented here for possible host modification.

1. Family Specific parameter. Please refer to “Family Specific Details” on page 263.
**LvdsPowerOnSeqDeToVaryBl**

This item configures panel initialization timing. The value is initially declared by the build configuration element “BLDCFG_LVDS_POWER_ON_SEQ_DE_TO_VARY_BL” on page 214. The value is presented here for possible host modification.

**LvdsPowerOnSeqDeToDigon**

This item configures panel initialization timing. The value is initially declared by the build configuration element “BLDCFG_LVDS_POWER_ON_SEQ_DE_TO_DIGON” on page 214. The value is presented here for possible host modification.

**LvdsPowerOnSeqVaryBlToDe**

This item configures panel initialization timing. The value is initially declared by the build configuration element “BLDCFG_LVDS_POWER_ON_SEQ_VARY_BL_TO_DE” on page 214. The value is presented here for possible host modification.

**LvdsPowerOnSeqOnToOffDelay**

This item configures panel initialization timing. The value is initially declared by the build configuration element “BLDCFG_LVDS_POWER_ON_SEQ_ON_TO_OFF_DELAY” on page 214. The value is presented here for possible host modification.

**LvdsPowerOnSeqVaryBlToBlon**

This item configures panel initialization timing. The value is initially declared by the build configuration element “BLDCFG_LVDS_POWER_ON_SEQ_VARY_BL_TO_BLON” on page 214. The value is presented here for possible host modification.

**LvdsPowerOnSeqBlonToVaryBl**

This item configures panel initialization timing. The value is initially declared by the build configuration element “BLDCFG_LVDS_POWER_ON_SEQ_BLON_TO_VARY_BL” on page 214. The value is presented here for possible host modification.

**LvdsMaxPixelClockFreq**

This item configures the maximum pixel clock frequency supported. The value is initially declared by the build configuration element “BLDCFG_LVDS_MAX_PIXEL_CLOCK_FREQ” on page 214. The value is presented here for possible host modification.

**LcdBitDepthControlValue**

This item configures the LCD bit depth control settings. The value is initially declared by the build configuration element
“BLDCFG_LCD_BIT_DEPTH_CONTROL_VALUE” on page 215. The value is presented here for possible host modification.

Lvds24bppPanelMode

This item configures the LVDS 24 BBP mode. The value is initially declared by the build configuration element

“BLDCFG_LVDS_24BBP_PANEL_MODE” on page 215. The value is presented here for possible host modification.

LvdsMiscControl

This item configures LVDS miscellaneous support settings. This value is initially declared by the build configuration elements

“BLDCFG_LVDS_MISC_888_FPDI_MODE” on page 215,
“BLDCFG_LVDS_MISC_DL_CH_SWAP” on page 215,
“BLDCFG_LVDS_BIT_DEPTH” on page 215,
“BLDCFG_LVDS_PARAM_OVERWRITE_EN” on page 215,
“BLDCFG_LVDS_MISC_BLOK_ACTIVE_LOW” on page 215, and
“BLDCFG_LVDS_MISC_VOLT_OVERWRITE_ENABLE” on page 216.
The value is presented here for possible host modification.

PcieRefClkSpreadSpectrum

This provides the spread spectrum setting for the PCIe® reference clock, when the platform has enabled spread spectrum. This value is initially declared by the build configuration element

“BLDCFG_PCIE_REFCLK_SPREAD_SPECTRUM” on page 216. The value is presented here for possible host modification.

GnbRemoteDisplaySupport

This item configures remote wireless display support. The value is initially declared by the build configuration element

“BLDCFG_REMOTE_DISPLAY_SUPPORT” on page 216. The value is presented here for possible host modification.

LvdsMiscVoltAdjustment

This item configures output voltage adjustment. An adjustment may be needed for LVDS via Travis converters. This value is initially declared by the build configuration element “BLDCFG_LVDS_MISC_VOLT_ADJUSTMENT” on page 216. The value is presented here for possible host modification.

DisplayMiscControl

This item is a packed array of flags that configure miscellaneous display settings. This values of the flags are initially declared by build configuration elements:

“BLDCFG_DISPLAY_MISC_VBIOS_FAST_BOOT_ENABLE” on page 217.
The flags value is presented here for possible host modification.

**GpuFrequencyLimit**

This item defines the maximum GPU frequency in MHz. This value is used to disable GPU power states that would exceed this limit. This value is initially declared by the build configuration element “BLDCFG_GPU_FREQUENCY_LIMIT” on page 216. The value is presented here for possible host modification.

typedef struct _FCH_INTERFACE {
  SD_MODE      SdConfig;
  HDA_CONFIG   AzaliaController;
  IR_CONFIG    IrConfig;
  BOOLEAN      UmiGen2;
  SATA_CLASS   SataClass;
  BOOLEAN      SataEnable;
  BOOLEAN      IdeEnable;
  BOOLEAN      SataIdeMode;
  BOOLEAN      Ohci1Enable;
  BOOLEAN      Ohci2Enable;
  BOOLEAN      Ohci3Enable;
  BOOLEAN      Ohci4Enable;
  BOOLEAN      GppEnable;
  GPP_LINKMODE GppLinkConfig;
  BOOLEAN      FchPowerFail;
} FCH_INTERFACE;

*SdConfig*

Defines the Secure Digital (SD) controller mode.

*AzaliaController*

Azalia HD audio controller function, ENABLED/DISABLED/AUTO.

*IrConfig*

Infrared (IR) operation mode.

*UmiGen2*

This item controls whether a GEN2 data rate of UMI (Unified Media Interface, the link between chipset Northbridge and Southbridge) is enabled or disabled.

*SataClass*

This item defines the target the SATA controller operating mode.

*SataEnable*

This item controls the SATA control function. When set to TRUE, the SATA controller function will be enabled.
IdeEnable
This item controls whether the IDE controller is to be made hidden. A FALSE value means the IDE controller is hidden and the Combined Mode is disabled, and the SATA controller has full control of all 6 ports when operating in non-IDE mode; a TRUE value means the IDE controller is exposed and the Combined Mode is enabled, the SATA controller will have control over port 0 through port 3, the IDE controller controls port 4 and 5.

SataIdeMode
This item selects between native IDE mode and legacy IDE mode.

Ohci1Enable
This item enables or disables OHCI1 controller.

Ohci2Enable
This item enables or disables OHCI2 controller.

Ohci3Enable
This item enables or disables OHCI3 controller.

Ohci4Enable
This item enables or disables OHCI4 controller.

GppEnable
This item controls whether the GPP ports are initialized and enumerated. A FALSE value means the ports are disabled. A TRUE value means the ports will be initialized and their devices enumerated.

GppLinkConfig
This item controls GPP Port configuration. The item is initialized by “BLDCFG_FCH_GPP_LINK_CONFIG” on page 220 and is presented here for possible modification.

FchPowerFail
This item controls the action by the FCH when power is resumed after a power failure. A value of zero means to power the platform off when power resumes. A value of one means to power the platform on when power resumes. A value of three means to resume to the previous state.

Description
This procedure uses the AgesaAllocateBuffer call-out to acquire permanent buffer space for the UEFI Hand-Off Blocks (HOBs). This is also known as, or includes, artifact data being used by the AGESA™ software. Upon entry to this procedure, the data is being held in a
temporary memory location and it must be moved to a location controlled and protected by the host environment.

These actions are performed by the BSP. The APs are not assigned any tasks at this time point.

**Dependencies**

This procedure must be called after full memory is initialized and the host environment has taken control of main memory allocation. This procedure should be called before the PCI enumeration takes place and as soon as possible after the host environment memory allocation sub-system has started.

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

**Status Codes Returned**

- AGESA_SUCCESS: The function has completed successfully.
- AGESA_ERROR: The artifact data could not be found or the host environment failed to allocate sufficient buffer space.
AmdInitMid

Prepare the graphics sub-system.

**Prototype**

```c
AGESA_STATUS
AmdInitMid (
    IN OUT AMD_MID_PARAMS *MidParams
);
```

**Parameters**

*MidParams

Pointer to a data structure containing the parameter information.

**Related Definitions**

```c
typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    IN PLATFORM_CONFIGURATION PlatformConfig;
    IN GNB_MID_CONFIGURATION GnbMidConfiguration;
    IN FCH_INTERFACE FchInterface;
} AMD_MID_PARAMS;
```

**PlatformConfig**

A structure containing platform-specific operational characteristics. This is the same structure described in “AmdInitEarly” on page 105.

**GnbMidConfiguration**

A structure containing GNB parameters.

**FchInterface**

A structure containing FCH parameters. This is the same structure described in “AmdInitEnv” on page 128.

```c
typedef struct {
    IN UINT8 iGpuVgaMode;
    IN UINT8 PcieAcsCapability;
    IN UINT64 GnbIoapicAddress;
    IN UINT8 MaxNumAudioEndpoints;
} GNB_MID_CONFIGURATION;
```

**iGpuVgaMode**

This specifies whether the processor internal GPU will handle resources for the primary VGA.
**PcieAscCapability**

This specifies whether Access Control Services (ACS) capabilities are exposed to the operating system. ACS can be used by hypervisors and may also be needed for certain compliance testing.

- **PcieAcsDisabled** - Do not expose root bridge ACS (default).
- **PcieAcsEnabled** - Expose root bridge ACS.

**GnbIoapicAddress**

The base address for the IOAPIC in the GNB may be programmed by the platform BIOS or by AGESA. If this value (GnbIoapicAddress) is NULL, then AGESA expects platform BIOS to program the base address of the IOAPIC. If this value is not NULL, then AGESA will use this value to set the base address of the IOAPIC.

**MaxNumAudioEndpoints**

A number specifying the number of active audio endpoints desired for this platform. The value used will be the minimum of: `<this parameter>`, `BLDCFG_MAX_NUM_AUDIO_ENDPOINTS` and the number of endpoints supported by the APU.

**Description**

This procedure call performs special configuration requirements for the graphics display hardware.

These actions are performed by the BSP. The APs are not assigned any tasks at this time point.

**Dependencies**

This procedure must be called after PCI enumeration has allocated resources, but before the video BIOS call is performed.

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

**Status Codes Returned**

- **AGESA_SUCCESS** - The function has completed successfully.
- **AGESA_ALERT**
- **AGESA_WARNING**
AmdInitLate

Perform initialization and configuration duties late in the boot sequence, filling information tables for use by the operating system.

Prototype

AGESA_STATUS
AmdInitLate(    
    IN OUT AMD_LATE_PARAMS *LateParams
);

Parameters

LateParams

Pointer to the parameter structure described below.

Related Definitions

typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    IN PLATFORM_CONFIGURATION PlatformConfig;
    IN IOMMU_EXCLUSION_RANGE_DESCRIPTOR *
        *IvrsExclusionRangeList;
    OUT DMI_INFO *DmiTable;
    OUT VOID *AcpiPState;
    OUT VOID *AcpiSrat;
    OUT VOID *AcpiSlit;
    OUT VOID *AcpiWheaMce;
    OUT VOID *AcpiWheaCmc;
    OUT VOID *AcpiAlib;
    OUT VOID *AcpiIvrs;
    OUT VOID *AcpiCrat;
    OUT VOID *AcpiCdit;
    IN GNB_LATE_CONFIGURATION GnbLateConfiguration;
} AMD_LATE_PARAMS;

PlatformConfig

A structure containing platform-specific operational characteristics. This is the same structure described in “AmdInitEarly” on page 105.

IvrsExclusionRangeList

Describe the exclusion ranges which need to be reported in the ACPI IVRS table. See “IOMMU Exclusion Range Descriptor” on page 355 for details.

DmiTable

Pointer to the buffer area that contains the DMI information. The buffer is allocated by using the Call-Out AgesaAllocateBuffer.
Note: The DMI information does not include handle fields, since it is expected that the host environment must assign handle values. There is one exception. In order to correctly associate Type 20 structures, Memory Device Mapped Address, with Type 17 structures, Memory Device, temporary handle values will be provided to each Type 17 structure. Each Type 20 structure will have its MemoryDeviceHandle field set to the value of the Handle field of the associated Type 17 structure. These temporary values allow the host environment to preserve the relationship of the two structure types in the host’s SMBIOS table. The host SMBIOS table will use handle values calculated by the host environment, not the temporary handle values.

**AcpiPState**

Pointer to the buffer area that contains the PState information. The buffer is allocated by using the Call-Out AgesaAllocateBuffer. The buffer will contain the PState information within an SSDT table structure.

**AcpiWheaMce**

Pointer to the buffer area that contains the WHEA-MCE sub-table. The buffer is allocated by using the Call-Out AgesaAllocateBuffer. The size of the table is contained within the WHEA standard definition table structure.

**AcpiWheaCmc**

Pointer to the buffer area that contains the WHEA-CMC sub-table. The buffer is allocated by using the Call-Out AgesaAllocateBuffer. The size of the table is contained within the WHEA standard definition table structure.

**AcpiAlib**

Pointer to the ACPI ASL library sub-table. The buffer is allocated by using the Call-Out AgesaAllocateBuffer. See “ACPI ASL Library” on page 355 for details.

**AcpiIvrs**

Pointer to the APCI IVRS sub-table. The buffer is allocated by using the Call-Out AgesaAllocateBuffer.

**AcpiCrat**

Pointer to the buffer area that contains the CRAT information. The buffer is allocated by using the Call-Out AgesaAllocateBuffer.

**AcpiCdit**

Pointer to the buffer area that contains the CDIT information. The buffer is allocated by using the Call-Out AgesaAllocateBuffer.

**GnbLateConfiguration**

A structure containing platform-specific operational characteristics. These characteristics are used only in this late time period.
The ACPI and DMI structure definitions are defined by the industry standard to which they belong, except where noted. The tables are generated in a state ready for inclusion into their respective parent structures as defined by the standard. The Host Environment need only to link or copy them into the appropriate framework and no reformatting is required.

```c
typedef struct {
    IN BOOLEAN ReservedOrDockedTdpHeadroom;
    IN UINT8 GnbIoapicId;
    IN UINT8 FchIoapicId;
} GNB_LATE_CONFIGURATION;
```

**GnbIoApicId**

The AGESA software will create an ACPI structure known as the I/O Virtualization Reporting Structure (IVRS). Part of this structure contains the IO APIC IDs for the GNB and FCH devices. These are assigned by the platform BIOS and set here for inclusion into the IVRS. This value is between 0x00 and 0xFF, inclusive. The default value assigned is 0xFF which will cause the IVRS entry for the device to be skipped.

**FchIoApicId**

IO APIC ID for the FCH device. See *GnbIoApicId* above.

**Description**

The main purpose of this function is to generate informational data tables used by the operating system. The individual tables can be selected for generation through the user selection entries on the input parameters.

This routine uses the Call-Out AgesaAllocateBuffer to allocate a buffer of the proper size to contain the data.

The code path separates the BSP from the APs and perform a separate and appropriate list of tasks for each class of core.

For the BSP, the following actions are performed:

- Allocate buffer space for the tables.
- Generate the table contents.
- Make sure that the CPU is in a known good power state before proceeding to boot the OS.

For the APs, the following actions are performed:

- Final register settings preparing for entry to OS.
- Establish the final PState for entry to OS.
Dependencies

This routine is expected to be executed late in the boot sequence after main memory has been initialized, after PCI enumeration has completed, after the host environment ACPI sub-system has started, after the host environment has taken control of the APs, but just before the start of OS boot.

The host environment must provide the required call-outs listed in “Required Call-Out Procedures” on page 150 to provide the buffer space in main memory and execute code on the APs. The host environment must register the created ACPI table in the main ACPI pointer tables. This may require moving the generated tables to another location in memory.

This procedure requires a stack. The host environment must establish the stack environment prior to making the call to this procedure. Some functions depend upon the preservation of the heap data across the shift from pre-memory environment to a post-memory environment. If that data was not preserved, then those functions cannot complete and an error is returned.

Status Codes Returned

AGESA_SUCCESS   The function has completed successfully.
AGESA_ALERT     The system could not allocate the needed amount of buffer space; or could not locate the artifact data block in memory. Likely cause: the host environment may not have preserved the data properly.
**AmdInitRtb**

This procedure is called very late in POST at the Ready-To-Boot (RTB) time. It performs last minute configuration and saves silicon component registers to the SMM save area in preparation to enter system suspend mode.

Both entry names will be supported for a time to maintain backward compatibility in present systems.

**Prototype**

```c
AGESA_STATUS
AmdS3Save (
    IN OUT AMD_S3SAVE_PARAMS *AmdS3SaveParams
);
AGESA_STATUS
AmdInitRtb (
    IN OUT AMD_RTB_PARAMS *AmdInitRtbParams
);
```

**Parameters**

- **AmdS3SaveParams**
- **AmdInitRtbParams**

  Pointer to the parameter structure described below.

**Related Definitions**

```c
typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    IN PLATFORM_CONFIGURATION PlatformConfig;
    OUT AMD_S3_PARAMS S3DataBlock;
    IN FCH_INTERFACE FchInterface;
} AMD_RTB_PARAMS;
```

- **S3DataBlock**

  Structure of pointers to storage locations where the processor context will be stored. This parameter is allowed to be null when the S3 support is removed.

- **PlatformConfig**

  A structure containing platform-specific operational characteristics. This is the same structure described in “AmdInitEarly” on page 105.

- **FchInterface**

  A structure containing FCH parameters. This is the same structure described in “AmdInitEnv” on page 128.
OUT UINT32 Signature;
OUT UINT16 Version;
IN OUT UINT32 Flags;
IN OUT VOID *NvStorage;
IN OUT UINT32 NvStorageSize;
IN OUT VOID *VolatileStorage;
IN OUT UINT32 VolatileStorageSize;
} AMD_S3_PARAMS;

**Signature**

"ASTR" for AMD Suspend-To-RAM

**Version**

S3 Params version number

**Flags**

Indicates operation specifics

**NvStorage**

Pointer to memory critical save state data. The data in this section must be available to the restore process before the main memory is re-started. Therefore it is targeted to be stored in non-volatile storage.

**NvStorageSize**

The size, in bytes, of the NvStorage region. If the size is returned as zero, the non-volatile storage should not be updated.

**VolatileStorage**

Pointer to remaining AMD save state data. The data in this section is not critical to re-starting the main memory. Therefore, it may be stored in the main memory; or in non-volatile storage as desired.

**VolatileStorageSize**

The size, in bytes, of the DRAM storage region.

**Description**

This procedure saves critical registers and/or configuration information for preservation across a system suspend mode. All actions needed to prepare the processor for suspend mode is performed, however this procedure does NOT initiate the suspend process. The host environment is expected to perform that duty.

These actions are performed by the BSP. The APs are not assigned any tasks at this time point.
The initializer routine will NULL out the save area pointers and sizes. This procedure will determine the size of storage needed for all the processor context, and make a call out to the environment for allocation of one buffer to store all of the data. Upon exit, the pointers and sizes within the `AMD_S3_PARAMS` structure will be updated with the appropriate addresses within the buffer that was allocated. The host environment is expected to then transfer the data pointed to by NvStorage to a non-volatile storage area, and the data pointed to by VolatileStorage to either a non-volatile storage area or system RAM that retains its content across suspend.

**Dependencies**

The host environment must initiate the suspend process.

This procedure requires a stack. The host environment must establish the stack environment prior to making the call to this procedure.

**Status Codes Returned**

- **AGESA_SUCCESS** All suspend duties have been completed successfully.
- **AGESA_ALERT**
14.3 Resume Branch Procedures

These routines are used to restore the processors to the operational state that was saved earlier in time.

AmdInitResume

This procedure performs silicon device and memory re-initialization for the resume boot path.

Prototype

AGESA_STATUS
AmdInitResume (  
  IN AMD_RESUME_PARAMS *ResumeParams
);  

Parameters

ResumeParams

Pointer to the parameter structure described below.

Related Definitions

typedef struct {
  IN OUT AMD_CONFIG_PARAMS StdHeader;
  IN PLATFORM_CONFIGURATION PlatformConfig;
  IN AMD_S3_PARAMS S3DataBlock;
} AMD_RESUME_PARAMS;

PlatformConfig

A structure containing platform-specific operational characteristics. This is the same structure described in “AmdInitEarly” on page 105.

S3DataBlock

Structure of pointers to storage locations where the processor context is stored. This is the same structure described in “AmdInitRtb” on page 141.

Description

This procedure initializes or re-initializes the silicon components for the resume boot path. For the processor, main memory is brought out of self-refresh mode. This procedure will use the context data in the NvStorage area of the input structure to re-start the main memory.

The host environment must fill the AMD_S3_PARAMS NvStorage and VolatileStorage pointers and related size elements to describe the location of the context data. Note for this procedure, the two data areas do not need to be contained in one buffer zone; they can be anywhere in the accessible memory address space. If the host environment uses a non-volatile storage device accessed on the system address bus such as flash ROM, then the context data does not need to be moved prior to this call. If the host environment uses a non-volatile storage device not
located on the system address bus (e.g. CMOS or SSEPROM) then the host environment must transfer the context data to a buffer in main memory prior to calling this procedure.

These actions are performed by the BSP. The APs are not assigned any tasks at this time point.

Dependencies

The host environment must have determined that the system should take the resume path prior to calling this procedure. The configuration done by AmdInitEarly and any necessary warm reset must be complete. After this procedure, execution proceeds to general system restoration.

The host environment must restore MTRRs\(^1\).

This procedure requires a stack. The host environment must use one of the provided service functions to establish the stack environment prior to making the call to this procedure.

Status Codes Returned

- AGESA_SUCCESS  
  Re-initialization has been completed successfully.
- AGESA_ALERT
- AGESA_ERROR

---

\(^1\) MTRRs apply to the x86-64 Architecture.
AmdS3LateRestore

This procedure restores saved registers after the PCI control structures have been re-established.

**Prototype**

```c
AGESA_STATUS
AmdS3LateRestore (  
    IN OUT AMD_S3LATE_PARAMS *S3LateParams  
);  
```

**Parameters**

*S3LateParams*

Pointer to the parameter structure described below.

**Related Definitions**

```c
typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;  
    IN PLATFORM_CONFIGURATION PlatformConfig;  
    IN AMD_S3_PARAMS S3DataBlock;  
} AMD_S3LATE_PARAMS;  
```

*PlatformConfig*

A structure containing platform-specific operational characteristics. This is the same structure described in “AmdInitEarly” on page 105.

*S3DataBlock*

Structure of pointers to storage locations where the processor context is stored. This is the same structure described in “AmdInitRtb” on page 141.

**Description**

This procedure restores the processor state, reloads critical silicon component registers, and performs any re-initialization required by the silicon. This procedure will use the context data in the VolatileStorage area of the input structure to restore the processor registers.

The host environment must fill the **AMD_S3_PARAMS** NvStorage and VolatileStorage pointers and related size elements to describe the location of the context data. Note for this procedure, the two data areas do not need to be contained in one buffer zone; they can be anywhere in the accessible memory address space. If the host environment uses a non-volatile storage device accessed on the system address bus such as flash ROM, then the context data does not need to be moved prior to this call. If the host environment uses a non-volatile storage device not located on the system address bus (e.g. CMOS or SSEPROM) then the host environment must transfer the context data to a buffer in main memory prior to calling this procedure.

These actions are performed by the BSP. The APs are not assigned any tasks at this time point.
Dependencies

This procedure is called late in the resume sequence, after the PCI control space is restored.
The host environment must initiate the OS restart process.
This procedure requires a stack. The host environment must establish the stack environment prior to making the call to this procedure.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AGESA_SUCCESS</td>
<td>All resume processes have been completed successfully.</td>
</tr>
<tr>
<td>AGESA_ALERT</td>
<td></td>
</tr>
<tr>
<td>AGESA_WARNING</td>
<td></td>
</tr>
</tbody>
</table>
AmdS3FinalRestore

This procedure restores saved registers and prepares the silicon components for OS restart.

Prototype

AGESA_STATUS
AmdS3FinalRestore (  
    IN OUT AMD_S3FINAL_PARAMS*S3LateParams  
);  

Parameters

S3LateParams

Pointer to the parameter structure described below.

Related Definitions

typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    IN PLATFORM_CONFIGURATION PlatformConfig;
    IN AMD_S3_PARAMS S3DataBlock;
} AMD_S3FINAL_PARAMS;  

PlatformConfig

A structure containing platform-specific operational characteristics. This is the same structure described in “AmdInitEarly” on page 105.

S3DataBlock

Structure of pointers to storage locations where the processor context is stored. This is the same structure described in “AmdInitRtb” on page 141.

Description

This procedure performs any last restoration or re-initialization required by the silicon prior to OS re-entry. This entry point is called at the very end of the resume process, just prior to OS handoff, after the PEI_POST_BOOT_SCRIPT_TABLE_PPI_GUID is installed.

Dependencies

This procedure is called last in the resume sequence, just before resuming operating system execution.

The host environment must initiate the OS restart process.

This procedure requires a stack. The host environment must establish the stack environment prior to making the call to this procedure.
Status Codes Returned

AGESA_SUCCESS    All resume processes have been completed successfully.
Chapter 15 Call-Out Procedures

15.1 Required Call-Out Procedures

The procedures listed in this section are required to be implemented by the host environment. These functions provide essential information without which the AGESA™ software cannot function properly. Optional call-out functions are described in later sections along with the entry procedure that uses the specific call-out.
**AgesaAllocateBuffer CallOut**

This host environment function is used in the post memory period to request the host environment use its internal methodology to allocate a section of main memory for use as a data buffer.

**Prototype**

```c
AGESA_STATUS
AgesaAllocateBuffer (  
   IN UINTN          FcnData,  
   IN OUT AGESA_BUFFER_PARAMS *AllocParams
);
```

**Parameters**

*FcnData*

This standard call-out parameter is not used for this call-out.

*AllocParams*

Pointer to a structure containing the requirements for the requested memory block.

**Related Definitions**

```c
typedef struct {
   IN OUT AMD_CONFIG_PARAMS      StdHeader;
   IN OUT UINT32                 BufferLength;
   IN    UINT32                 BufferHandle;
   OUT   VOID                    *BufferPointer;
} AGESA_BUFFER_PARAMS;
```

*StdHeader*

AMD standard Header structure. See “Standard Header” on page 33.

*BufferLength*

On input, this is the requested size to be allocated. Upon successful completion, this is updated by the call-out procedure to indicate the amount actually allocated.

*BufferHandle*

This is an identifier used to name and locate the allocated block at some future time. The AGESA™ software uses the buffer handles defined in the enum list AMD_BUFFER_HANDLE for the buffers it needs to allocate. The host environment software may use BufferHandle to apply special processing to certain buffer types.
BufferPointer

This is a pointer to the memory space allocated by the host environment for use as the data buffer. Upon successful completion, this is updated by the call-out procedure with a 32-bit mode address of the buffer. The pointer should be NULL if allocation was not successful.

Description

This function is used after main memory has been initialized and the host environment has taken control of memory allocation. This function must allocate a buffer of the requested size or larger. This function is required to be implemented by the host environment.

Beginning at the AmdInitEnv boot time point and continuing, the item StdHeader->HeapStatus should be checked by the callout implementation for indicating HEAP_RUNTIME_SYSTEM_MEM, rather than a boot time point. When HEAP_RUNTIME_SYSTEM_MEM is indicated, the callout implementation should cause the allocated memory to persist at run-time as a reserved address region. For UEFI, the callout implementation can map HEAP_RUNTIME_SYSTEM_MEM to EfiACPIMemoryNVS or EfiRuntimeServicesData.

Dependencies

The following call-outs must work together in the host system. Parameters of the same name have the same function and must be treated the same in each function:

AgesaAllocateBuffer AgesaDeallocateBuffer
AgesaLocateBuffer
AgesaRunFcnOnAp AgesaRunFcnOnAllAps

The host environment may need to reserve a location in the buffer to store any host environment specific value(s). The returned pointer must not include this reserved space. The host environment on the AgesaDeallocateBuffer call needs to account for the reserved space. This reserved space may be an identifier or the “handle” used to identify the specific memory block.

Status Codes Returned

AGESA_SUCCESS The requested size of memory has been successfully allocated.
AGESA_UNSUPPORTED This is a required function, so this value being returned causes a critical error response value from the AGESA™ software function.
AGESA_WARNING Less than the requested amount of memory was allocated.
AgesaDeallocateBuffer

This host environment function de-allocates a valid buffer that was previously obtained from the AgesaAllocateBuffer function.

Prototype

```c
AGESA_STATUS
AgesaDeallocateBuffer
(
    IN UINTN FcnData,
    IN OUT AGESA_BUFFER_PARAMS *DeallocParams
);
```

Parameters

- **FcnData**
  - This standard call-out parameter is not used for this call-out.
- **DeallocParams**
  - This is the same structure used by the AgesaAllocateBuffer function.

Related Definitions

- **AGESA_BUFFER_PARAMS**
  - Note that this structure is the same as that used for AgesaAllocateBuffer. Please refer to that function definition for parameter details. In this usage, only the standard header and the BufferHandle elements need to be populated by the caller. This is sufficient to identify the buffer.

Description

This function is used after main memory has been initialized and the host environment has taken control of memory allocation. This function releases a valid working buffer. This function is **required** for the host environment to implement.

Dependencies

The following call-outs must work together in the host system. Parameters of the same name have the same function and must be treated the same in each function:

- AgesaAllocateBuffer
- AgesaLocateBuffer
- AgesaRunFcnOnAp
- AgesaDeallocateBuffer
- AgesaRunFcnOnAllAps

Status Codes Returned

The function must return a status value indicating one of the following:
AGESA_SUCCESS The function has completed successfully.

AGESA_BOUNDS_CHK The BufferHandle is invalid. The AGESA™ software continues with its function.

AGESA_UNSUPPORTED This is a required function, so this value being returned causes a critical error response value from the AGESA™ software function.
**AgesaDoReset**

This function does a system reset.

**Prototype**

```c
VOID AgesaDoReset ( 
    IN UINTN ResetType, 
    IN OUT AMD_CONFIG_PARAMS *StdHeader 
); 
```

**Parameters**

*ResetType*

This standard call-out parameter indicates which type of system reset to initiate; either a “cold” reset or a “warm” reset.

*StdHeader*

Pointer to a data structure containing the AMD standard Header structure.

**Related Definitions**

```c
#define WARM_RESET_WHENEVER 1
#define COLD_RESET_WHENEVER 2
#define WARM_RESET_IMMEDIATELY 3
#define COLD_RESET_IMMEDIATELY 4
```

A cold reset is characterized by the momentary deassertion of the PWRGOOD/PWROK signal. A warm reset is characterized by the momentary assertion of the RESET# signal with no change to the PWRGOOD/PWROK signal.

**Description**

This host environment function must initiate the specified type of system reset.

Implementation of this function by the host environment is **REQUIRED**. Some host environments may record this as a request allowing other elements in the system to perform some additional tasks before the actual reset is issued.

**Dependencies**

The AMD processor contains 3 bits (BiosRstDet[2:0]) in a PCI register (F0x6C Link Initialization Control Register) that indicate the reset status. These bits are reserved for use by the AGESA™ software and should not be modified by the host environment.

**Status Codes Returned**

AGESA_SUCCESS The function has completed successfully.
AGESA_UNSUPPORTED This is a required function, so this value being returned causes a critical error response value from the AGESA™ software function.
AgesaLocateBuffer

This host environment function returns a pointer to the buffer with the indicated handle.

Prototype

```c
AGESA_STATUS
AgesaLocateBuffer
(
    IN UINTN     FcnData,
    IN OUT AGESA_BUFFER_PARAMS   *LocateParams
)
```

Parameters

**FcnData**
This standard call-out parameter is not used for this call-out.

**LocateParams**
This is the same structure used by the AgesaAllocateBuffer function.

Related Definitions

AGESA_BUFFER_PARAMS

Note that this structure is the same as that used for AgesaAllocateBuffer. Please refer to that function definition for parameter details. In this usage, only the standard header and the BufferHandle elements need to be populated by the caller. This is sufficient to identify the buffer. The implemented routine must locate the buffer and then populate BufferLength and BufferPointer. If the requested buffer is not found, BufferLength should be zero and BufferPointer should be NULL.

Description

This function is used after main memory has been initialized and the host environment has taken control of memory allocation. This function must locate the buffer related to the indicated handle and return the address of the buffer and its length. This function is **required** to be implemented in the host environment.

Dependencies

The following call-outs must work together in the host system. Parameters of the same name have the same function and must be treated the same in each function:

- AgesaAllocateBuffer
- AgesaDeallocateBuffer
- AgesaLocateBuffer
- AgesaRunFcnOnAp
- AgesaRunFcnOnAllAps
Status Codes Returned

AGESA_SUCCESS The function has completed successfully.
AGESA_BOUNDS_CHK The presented handle is invalid or the buffer could not be located.
**AgesaReadSpd CallOut**

These call-outs read a block of memory SPD data and places it into the provided buffer.  

This routine is not used by newer APUs equipped with the Platform Security Processor (PSP) performing the memory initialization.

**Prototype**

```c
AGESA_STATUS AgesaReadSpd (  
    IN UINTN FcnData,  
    IN OUT AGESA_READ_SPD_PARAMS *ReadSpd  
);  
```

**Parameters**

- **FcnData**

  This standard call-out parameter is not used for this call-out.

- **ReadSpd**

  Pointer to a data structure containing the parameter information.

**Related Definitions**

```c
typedef struct {  
    IN OUT AMD_CONFIG_PARAMS StdHeader;  
    IN UINT8 SocketId;  
    IN UINT8 MemChannelId;  
    IN UINT8 DimmId;  
    IN OUT UINT8 *Buffer;  
    IN OUT MEM_DATA_STRUCT *MemData;  
} AGESA_READ_SPD_PARAMS;  
```

- **StdHeader**

  AMD standard Header structure. See “Standard Header” on page 33.

- **SocketID**

  Identifier indicating the socket where the target SPD is located. The motherboard designer must follow the design guidelines to make this match the silk screen labels on the board. Otherwise, the host environment needs to provide their own translation procedures.

- **MemChannelId**

  Index of the memory channel for which to read the SPD data. Channels are numbered 0 to 3 relative to the socket. Channel 0 matches with “channel A” in the processor specification, channel 1 with “channel B,”... channel 3 with “channel D.”
**DimmID**

Index of the DIMM for which to read the SPD data. DIMMs are numbered 0 to 3 relative to the channel. Each channel has memory chip-select lines that define the DimmID:

<table>
<thead>
<tr>
<th>Buffer</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pointer to a location to store the SPD data read from the DIMM. All 256 bytes of the DIM SPD should be read from the device and stored in the buffer. Use of the Block Read protocol is recommended for speed of operation.</td>
</tr>
</tbody>
</table>

**Description**

This procedure is called by the host environment call-out router. This call-out is used before main memory is initialized.

The SPD data is read over the SMBus using a platform specific SMBus controller. If supported by the SMBus controller, a block read operation is recommended to reduce the transfer time. The host environment must adjust any SMBus routing required to access the target DIMM.

**Dependencies**

The host environment is required to provide this function. The main system memory cannot be properly initialized without the SPD data.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AGESA_SUCCESS</td>
<td>Indicates the SPD block for the indicated DIMM was read successfully.</td>
</tr>
<tr>
<td>AGESA_BOUNDS_CHK</td>
<td>The specified DIMM is not present.</td>
</tr>
<tr>
<td>AGESA_UNSUPPORTED</td>
<td>This is a required function, so this value being returned causes a critical error response value from the AGESA™ software function and no memory initialized.</td>
</tr>
<tr>
<td>AGESA_ERROR</td>
<td>The DIMM SPD read process has generated communication errors.</td>
</tr>
</tbody>
</table>
AgesaRunFcnOnAp

AgesaRunFcnOnAllAps

This function causes code to be executed on an Application Processor.

The difference between the two functions is the target AP - either a specific AP, by APICID; or all APs. These functions are tightly tied to the following entry point AmdLateRunApTask.

Note: These procedures only apply to the x86-64 architecture APUs.

Prototype

AGESA_STATUS
AgesaRunFcnOnAp (  
    IN UINTN ApicIdOfCore,  
    IN AP_EXE_PARAMS *LaunchApParams  
);  

Parameters

ApicIdOfCore  
This is the APIC ID of the target AP that is to execute the function.

LaunchApParams  
Pointer to a structure containing the AP address and function data.

Related Definitions

typedef struct {  
    IN OUT AMD_CONFIG_PARAMS StdHeader;  
    IN UINT32 FunctionNumber;  
    IN VOID *RelatedDataBlock;  
    IN UINT32 RelatedBlockLength;  
    IN BOOLEAN AllAPs;  
} AP_EXE_PARAMS;

FunctionNumber  
This is a parameter to the AP that indicates the sub-function to perform. The AGESA™ software AP dispatcher uses this function number to select the target procedure.

RelatedDataBlock  
This is a pointer to a data block related to the function that the AP must perform. The host environment must make this data block available to the AP

1. Family specific call-out. Please check for details in the AGESA.H file for your family.
during its execution of the specified function. Simultaneous access to the data block by multiple processors is not required.

**RelatedBlockLength**

Length of the data block related to the function the AP must perform. If the length is zero, then there is no related data block.

**AllAPs**

Indicates whether or not to run the function on all APs or on one only

- TRUE - this function would be run on all APs
- FALSE - this function run on one AP

**Description**

This function is used after main memory has been initialized and the host environment has taken control of AP task dispatching. This function must cause the indicated function code to be executed upon the specified Application Processor. This procedure must be executed in 32-bit mode. This function is required to be implemented in the host environment.

**Dependencies**

The host environment must route execution to the target AP and have that AP call the“`AmdLateRunApTask`” entry point.

**Status Codes Returned**

The status code returned to the caller must also reflect the status returned by the AP when executing the requested function.

- **AGESA_SUCCESS** The function has completed successfully.
- **AGESA_UNSUPPORTED** This is a required function, so this value being returned causes a critical error response value from the AGESA™ software function and no memory initialized.
- **AGESA_WARNING** The AP did not respond.

1. Family specific call-out. Please check for details in the AGESA.H file for your family.
AmdLateRunApTask

This procedure is run by the Application Processor to perform a function as directed by the BSP.

Note: This procedure only applies to the x86-64 architecture APUs.

Prototype

AGESA_STATUS
AmdLateRunApTask(
    IN AP_EXE_PARAMS *AmdApExeParams
);

Parameters

AmdApExeParams

Pointer to the interface structure for requested routine.

Related Definitions

AP_EXE_PARAMS

This is the same structure used for “AgesaRunFcnOnAllAps” on page 161.

Description

This entry point is tightly connected with the “AgesaRunFcnOnAllAps” on page 161. The AGESA™ software will call the call-out “AgesaRunFcnOnAllAps”; the host environment will then call this entry point to have the AP execute the requested function. This is needed late in the Post and Resume branches for running an AP task since the AGESA™ software has relinquished control of the APs to the host environment.

Dependencies

The host environment must implement the “AgesaRunFcnOnAllAps” call-out and route execution to the target AP.

Status Codes Returned

The status code returned by this procedure must also be returned to the original caller of “AgesaRunFcnOnAllAps” on page 161.

AGESA_SUCCESS The function has completed successfully.
AGESA_UNSUPPORTED The requested function is unknown.
AGESA_BOUNDS_CHECK The MMIO base is not set.
AgesaPcieSlotResetControl

This function does a PCIe port reset.

Prototype

AGESA_STATUS
AgesaPcieSlotResetControl (  
    IN      UINTN                  FcnData,  
    IN      PCIe_SLOT_RESET_INFO *ResetInfo  
);  

Parameters

ResetInfo

Pointer to the interface structure for requested routine.

Related Definitions

PCle_SLOT_RESET_INFO

typedef struct {  
    IN      AMD_CONFIG_PARAMS     StdHeader;  
    IN      UINT8                ResetId;  
    IN      UINT8                ResetControl;  
} PCIe_SLOT_RESET_INFO;

StdHeader

The current configuration.

ResetId

The port, or group of ports, to be reset. Often corresponds to a GPIO.

ResetControl

Specifies the requested reset behavior. This is specified using
PCIE_RESET_CONTROL enum.

AssertSlotReset - Assert the reset.
DeassertSlotReset - Deassert the reset.

Description

This entry point performs PCIe port resets, by knowing how the platform maps each reset ID.

Dependencies

The reset ID for the port is provided as part of the PCIe topology.
Status Codes Returned

AGESA_SUCCESS The function has completed successfully.
AGESA_UNSUPPORTED The requested function is unknown.
AgesaWaitForAllApsFinished

This function checks for and waits until all APs have finished the allocated task.

**Prototype**

```c
AGESA_STATUS
AgesaWaitForAllApsFinished (VOID);
```

**Parameters**

*<none>*

**Description**

This entry point will check all of the APs for their status. Once all of the APs have indicated they have completed their task assignment, this routine will return to the caller.

**Status Codes Returned**

- **AGESA_SUCCESS** The function has completed successfully.
- **AGESA_UNSUPPORTED** The requested function is unknown.

---

1. Family specific call-out. Please check for details in the AGESA.H file for your family.
This function places the specified AP into idle mode.

**Prototype**

```
AGESA_STATUS
AgesaIdleAnAp (    
    IN UINTN ApicIdOfCore;
 );
```

**Parameters**

- **ApicIdOfCore**

  The APIC ID of the target core to put into idle mode.

**Description**

This entry point causes the specified core to go into its idle mode, waiting for its next task.

**Status Codes Returned**

- AGESA_SUCCESS The function has completed successfully.
- AGESA_UNSUPPORTED The requested function is unknown.

---

1. Family specific call-out. Please check for details in the AGESA.H file for your family.
15.2 Optional Call-Out Procedures

AgesaGetIdsData

Read a portion of IDS data from the non-volatile (NV) storage.

Prototype

AGESA_STATUS
AgesaGetIdsData (  
    IN UINTN FcnData,  
    IN OUT IDS_CALLOUT_STRUCT *IdsCalloutData
);

Parameters

FcnData
This parameter indicates the IDS sub-function desired.

IdsCalloutData
Pointer to a structure containing requirements for the IDS function

Related Definitions

typedef struct {
    IN AMD_CONFIG_PARAMS StdHeader;
    IN OUT IDS_NV_ITEM *IdsNvPtr;
    IN OUT UINTN Reserved;
} IDS_CALLOUT_STRUCT;

StdHeader
AMD standard Header structure. See “Standard Header” on page 33.

IdsNvPtr
Pointer to a buffer where the host environment should place the requested data. The data is an array of ID-Value pairs. The array is terminated with an entry containing 0xffff in the IdsNvId field.

typedef struct {
    IN UINT16 IdsNvId;
    OUT UINT16 IdsNvValue;
} IDS_NV_ITEM;
**IdsNvId**

This is the unique data element identifier.

**IdsNvValue**

This is the value of the data element.

**Description**

This host environment procedure must walk the array list of IDS element identifiers, translate the identifier to a platform NV storage location, read the value from the NV storage, and store that value into the array’s value entry. The identifiers for the IDS data elements are defined in the IDS.H include file.

This call-out is listed as optional since the IDS sub-system is also optional. However, if the IDS features are included into the build, then this call-out becomes required.

**Dependencies**

The NV storage must contain valid data values for the IDS elements.

**Status Codes Returned**

- **AGESA_SUCCESS** The host environment has successfully fill the array of IDS_NV_ITEM.
- **AGESA_ALERT** The IDS_NV_ITEM list contained an unrecognized IdsNvId.
- **AGESA_UNSUPPORTED** The host environment returning this value causes the default value(s) to be used for the related data elements.
AgesaHeapRebase CallOut

Allow the host environment to control the initial heap location.

Prototype

```c
AGESA_STATUS AgesaLocateBuffer
(
    IN UINTN FcnData,
    IN OUT AGESA_REBASE_PARAMS *RebaseParams
);
```

Parameters

- **FcnData**
  
  This standard call-out parameter is not used for this call-out.

- **RebaseParams**
  
  This structure communicates the heap base address.

Related Definitions

```c
typedef struct {
    IN OUT AMD_CONFIG_PARAMS StdHeader;
    OUT UINTN *HeapAddress;
} AGESA_BUFFER_PARAMS;
```

- **StdHeader**
  
  AMD standard Header structure. See “Standard Header” on page 33.

- **HeapAddress**
  
  Provides the base address to use for the heap data.

Description

Implementation of this function is **optional** for the host environment. This call-out is an opportunity for the host environment provide the heap base address to be used. This function can be used to provide alternate heap locations when the system is performing a secure resume and the default location is not available. If the function is not implemented or does not update the HeapAddress parameter, a default location will be used for the heap data.

Dependencies

None.
Status Codes Returned

AGESA_SUCCESS  The function has completed successfully.
AgesaHookBeforeDramInit

General-purpose hook called before the DRAM_Init bit is set.

**Prototype**

```c
AGESA_STATUS
AgesaHookBeforeDramInit (IN UINTN SocketIdModuleId,
     IN OUT MEM_DATA_STRUCT *MemData);
```

**Parameters**

- **SocketIdModuleId**

  This standard call-out parameter provides the processor socket and internal node number for the MCT which is about to be enabled. These bitfields are accessed as shown:
  
  SocketIdModuleId.SocketId - The processor’s socket.
  SocketIdModuleId.ModuleId - The internal node for this MCT.

- **MemData**

  Pointer to a data structure containing the memory information. This is the same data structure that was passed to the main memory routine. See “AmdInitPost” on page 115 for structure details.

**Description**

General-purpose hook called before the DRAM_Init bit is set. Called once per MCT.

Implementation of this function is optional for the host environment. This call-out is an opportunity for the host environment to make dynamic modifications to the memory timing settings specific to the board or host environment.

New structure member to note is VddpVddrVoltage. If the IsValid element is TRUE, the platform is expected to change the VRM controls to modify the voltage supplied to the Memory PHY power pin to the voltage specified. Please check the Power specification for the APU. Specific power requirements for the APU may change the implementation status of this hook to Required. This is presently the case for the Kaveri SoCs.

**Dependencies**

**Status Codes Returned**

- AGESA_SUCCESS The function has completed successfully.
- AGESA_UNSUPPORTED This function is not implemented by the host environment.
- AGESA_WARNING
AgesaHookBeforeDQSTraining

General-purpose hook called before the memory training begins.

Prototype

```c
AGESA_STATUS
AgesaHookBeforeDQSTraining (  
    IN UINTN SocketIdModuleId,  
    IN OUT MEM_DATA_STRUCT *MemData  
);  
```

Parameters

- **SocketIdModuleId**
  
  This standard call-out parameter provides the processor socket and internal node number for the MCT which is about to be enabled. These bitfields are accessed as shown:
  
  SocketIdModuleId.SocketId - The processor’s socket.
  SocketIdModuleId.ModuleId - The internal node for this MCT.

- **MemData**
  
  Pointer to a data structure containing the memory information. This is the same data structure that was passed to the main memory routine. See “AmdInitPost” on page 115 for structure details.

Description

General-purpose hook called just before the memory training processes begin. Called once per MCT.

Implementation of this function is optional for the host environment. This call-out is an opportunity for the host environment to make dynamic modifications to the memory timing settings specific to the board or host environment.

The host environment may also use this call-out for some board-specific features that should be activated at this time point, such as:

- Low voltage DIMMs — the host environment should set the recommended voltages found in the memory data structure for each memory channel. This needs to occur before training begins.

Status Codes Returned

- **AGESA_SUCCESS** The function has completed successfully.
- **AGESA_UNSUPPORTED** This function is not implemented by the host environment.
**AgesaExternal2dTrainVrefChange CallOut**

Called in order to change the external Vref for 2D memory training.  

**Prototype**

\[
\text{AGESA\_STATUS}\quad
\text{AgesaExternal2dTrainVrefChange}\quad
(\quad
\text{IN} \quad \text{UINTN} \quad \text{SocketIdModuleId}, \\
\text{IN} \quad \text{OUT} \quad \text{MEM\_DATA\_STRUCT} \quad \text{*MemData} \\
); \]

**Parameters**

**SocketIdModuleId**

This standard call-out parameter provides the processor socket and internal node number for the MCT which is about to be enabled. These bitfields are accessed as shown:

- **SocketIdModuleId.SocketId** - The processor’s socket.
- **SocketIdModuleId.ModuleId** - The internal node for this MCT.

**MemData**

Pointer to a data structure containing the memory information. This is the same data structure that was passed to the main memory routine. See “AmdInitPost” on page 115 for structure details.

**Description**

When indicated, this call out will be called in order to change the external Vref rather than using internal Vref control. The host environment should implement the platform specific external Vref control.

**Dependencies**

**Status Codes Returned**

- **AGESA\_SUCCESS** The function has completed successfully.
- **AGESA\_UNSupported** This function is not implemented by the host environment.
AgesaHookBeforeExitSelfRefresh

General-purpose hook called before exiting self-refresh mode during the resume process. **Optional**

**Prototype**

```c
AGESA_STATUS
AgesaHookBeforeExitSelfRefresh (
    IN UINTN FcnData,
    IN OUT MEM_DATA_STRUCT *MemData
);```

**Parameters**

*FcnData*

This standard call-out parameter is not used for this call-out.

*MemData*

Pointer to a data structure containing the memory information. This is the same data structure that was passed to the main memory routine. See “AmdInitPost” on page 115 for structure details.

**Description**

General purpose hook called before the exiting self refresh. This procedure is called once per channel.

Implementation of this function is **optional** for the host environment. This call-out is an opportunity for the host environment to make dynamic modifications to the memory timing settings specific to the board or host environment before exiting self refresh on S3 resume.

**Dependencies**

This procedure is called before the exit self refresh bit is set in the resume sequence. The host environment must initiate the OS restart process. This procedure requires a stack. The host environment must establish the stack environment prior to making the call to this procedure.

**Status Codes Returned**

- **AGESA_SUCCESS** The function has completed successfully.
- **AGESA_UNSUPPORTED** This function is not implemented by the host environment.
- **AGESA_WARNING**
AgesaGetVbiosImage

This function does a PCIe port reset.

Prototype

\[
\text{AGESA_STATUS} \quad \text{AgesaGetVbiosImage} (\text{IN UINTN FcnData, IN OUT GFX_VBIOS_IMAGE_INFO *VbiosImageInfo});
\]

Parameters

- \textbf{VbiosImageInfo}
  - Pointer to the video BIOS and control information.

Related Definitions

typedef struct {  
  \text{IN AMD_CONFIG_PARAMS StdHeader;}
  \text{OUT VOID *ImagePtr;}
  \text{IN PCI_ADDR GfxPciAddress;}
  \text{IN UINT32 Flags;}
} \text{GFX_VBIOS_IMAGE_INFO};

- \textbf{StdHeader}
  - The current configuration.
- \textbf{ImagePtr}
  - A pointer to the video BIOS image.
- \textbf{GfxPciAddress}
  - The configuration base address of the integrated graphics controller.
- \textbf{Flags}
  - Indicate whether a special repost is required.

Description

This entry point performs the special video BIOS repost call, if indicated, and returns a pointer to the video BIOS image.

Status Codes Returned

- \textbf{AGESA_SUCCESS}
  - The function has completed successfully.
- \textbf{AGESA_UNSUPPORTED}
  - The requested function is unknown.
AgesaFchOemCallout

This function provides expert level FCH customization.

**Prototype**

```c
AGESA_STATUS
AgesaGetVbiosImage (
    IN UINTN       FcnData,
    IN OUT VOID    *FchData
);
```

**Parameters**

`FchData`

Pointer to the current FCH data block structure.

**Related Definitions**

During PEI phase this points to FCH_RESET_DATA_BLOCK and during DXE phase this points to FCH_DATA_BLOCK. Refer to the internal documentation for the latest and most detailed information on these two structures ("Internal Documentation" on page 26).

**Description**

This callout provides the ability to make expert level customizations prior to both the PEI and DXE FCH initialization.

**Status Codes Returned**

- **AGESA_SUCCESS** The function has completed successfully.
- **AGESA_UNSUPPORTED** The requested function is unknown.
AgesaExternalVoltageAdjust CallOut

Called in order to change the external voltage as part of the memory test feature. While optional in general, this callout is required when using the MBIST feature.

Prototype

AGESA_STATUS
AgesaExternalVoltageAdjust (  
    IN UINTN SocketIdModuleId,  
    IN OUT VOLTAGE_ADJUST *AdjustValue  
);

Parameters

SocketIdModuleId

This standard call-out parameter provides the processor socket and internal node number for the MCT which is about to be enabled. These bitfields are accessed as shown:

SocketIdModuleId.SocketId - The processor’s socket.
SocketIdModuleId.ModuleId - The internal node for this MCT.

AdjustValue

Pointer to a data structure containing the voltage adjustment information.

Related Definitions

VOLTAGE_ADJUST
typedef struct {
    OUT AMD_CONFIG_PARARMS StdHeader;
    OUT MEM_DATA_STRUCT *MemData;
    IN UINT8 VoltageType;
    IN INT8 AdjustValue;
} VOLTAGE_ADJUST;

StdHeader

The current configuration.

MemData

Provides access to current memory data.

VoltageType

Specifies the type of voltage adjustment to make.

CPU_VREF - (Optional.) Normally this adjustment is made using processor hardware support. If desired by the platform, this callout can be used to
accomplish this adjustment with platform specific hardware support. To enable callout control provide the following build option:

```c
#define CFG_ENABLE_EXTERNAL_VREF TRUE
```

**DIMM_VREF** - A request to vary the DIMM side Vref voltage level in increments of +/- 1% from the level determined on the platform.

**VDDIO** - A request to vary the VDDIO voltage in increments of +/- 1% from the nominal VDDIO set by the platform.

**AdjustValue**

The signed adjustment value to be made to the voltage, in percentage.

**Description**

When the memory testing feature is enabled, this callout will be used to control voltage levels in order to stress test memory and verify the integrity of the memory subsystem.

**Dependencies**

Code is running from Cache-As-RAM (CAR) environment. Memory testing is destructive to memory content.

**Status Codes Returned**

AGESA_SUCCESS The function has completed successfully.

AGESA_UNSUPPORTED This function is not implemented by the host environment.
AgesaGnbOemCallout

Called to request a change to some platform specific controls.

While optional in general, this callout is required when the host platform implements specific hardware for tuning performance.

Prototype

AGESA_STATUS
AgesaGnbOemCallout (
   IN UINTN   FcnData,
   IN PCI_ADDR *Device
);

Parameters

FcnData

This standard call-out parameter is which specifies the function to be performed.

Device

This is a pointer to a PCI address for the target device.

Related Definitions

FcnData == AGESA_GNB_PCIE_CLK_REQ

The PCIe device, addressed by *Device, is capable of supporting the “CLKREQ#” mode of operation. This call-out is requesting the host environment to configure the clock generator device to also operate in the CLKREQ# mode.

Description

This is a general purpose call-out that requests the host environment to perform certain actions upon platform specific devices outside the control of the AGESA code. The requested action is indicated by the FcnData parameter.

Status Codes Returned

AGESA_SUCCESS The function has completed successfully.
AGESA_UNSUPPORTED This function is not implemented by the host environment.
Chapter 16  Customizing Platforms

Some platforms require special handling of certain characteristics. The following sections describe the customization controls available. Many of these controls require an advanced knowledge level and should not be used until the platform developer fully understands the processes involved.

There are four mechanisms available to the host environment to provide customized data:

1. *<Plat>Options.c Build Configuration settings* — user settings are defined in below. They fall into two categories:
   a. Platform-specific limits — predefined configuration elements to describe the platform
   b. User-defined register settings — user-defined register setting table.
   This form of customization is used for items that change from platform to platform but remain static on any single platform, meaning they don’t change from boot to boot nor are they likely to be the subject of an end-user choice.

2. Wrapper interaction after the call to AmdCreateStruct — as discussed in “Call Mechanics” on page 27, the host environment has an opportunity to modify parameters and/or register values after the call to AmdCreateStruct completes. This is a perfect place to insert user-specified settings retrieved from non-volatile storage (for example, host BIOS SETUP) or to make modifications based on a programmed algorithm.
   This form of customization is used for items that differ from the AMD defaults and are the same for a large sub-class of platforms, or are subject to an end-user choice not covered by the IDS features. For example, an IBV or OEM may use this form of customization to establish a corporate standard.

3. Integrated Debug Services (IDS) controls — these are described in “IDS Configuration Controls” on page 249. They are only available during the platform ‘bring-up’ and debug phase.

4. Defined call-outs — listed in “Optional Call-Out Procedures” on page 168, these call-outs occur at specific points in the initialization sequence. The host environment can perform register modifications and/or algorithmic modifications at these times.
   This form of customization is used for items that require active modification at a very specific point inside a running algorithm. Execution control is given over to a host environment sub-routine.

16.1 Build Options

Build options are boolean constants. The purpose of build options is to remove code from the build to reduce the overall code size present in the ROM image. Unless otherwise specified, the default action is to include all options. If a build option is not specifically listed as disabled, then it is included into the build.
The user specifies which build options are desired in a source file local to their project named <plat>Options.c. This file is compiled with the AGESA™ project, therefore the build control file needs to know the location of the platform project. The user must set the environment variable AGESA_OptsDir to the path to find the <plat>Options.c file.

To disable an option, a line such as the following must be included in the Options.c file:

```c
#define BLDOPT_REMOVE_???_SUPPORT TRUE
```

A value of TRUE disables or removes the option and the associated code is removed from the build. A value of FALSE means that the option is enabled and included into the build. A build option does not need to be listed in the Options.c file unless it is being changed from its default value. The defined build options are:

- **BLDOPT_REMOVE_UDIMMS_SUPPORT**
  - If unbuffered DIMMs are NOT expected to be required in the system, the code that handles unbuffered DIMMs can be removed from the build.

- **BLDOPT_REMOVE_RDIMMS_SUPPORT**
  - If registered DIMMs are NOT expected to be required in the system, the code that handles registered DIMMs can be removed from the build.

- **BLDOPT_REMOVE_LRDIMMS_SUPPORT**
  - If Load Reduced (LR) DIMMs are NOT expected to be required in the system, the code that handles LR DIMMs can be removed from the build.

**Note:** The above three options operate independently from each other; however, at least one of the unbuffered, registered, or load reduced options must be present in the build.

- **BLDOPT_REMOVE_DDR3_SUPPORT**
  - For systems supporting DDR3 memory and another memory type, such as GDDR5, the code for DDR3 may be removed if DDR3 memory is NOT expected to be required in the system. If the processor only supports DDR3 memory, this option is ignored.

- **BLDOPT_REMOVE_GDDR5_SUPPORT**
  - For systems supporting GDDR5 memory and another memory type, such as DDR3, the code for GDDR5 may be removed if GDDR5 memory is NOT expected to be required in the system. If the processor only supports GDDR5 memory, this option is ignored.

- **BLDOPT_REMOVE_ECC_SUPPORT**
  - Use this option to remove the code for Error Checking & Correction.

- **BLDOPT_REMOVE_DCT_INTERLEAVE**
  - Interleaving is a mechanism to do performance fine tuning. This option interleaves memory from two DRAM controllers.
**BLDOPT\_REMOVE\_BANK\_INTERLEAVE**

Interleaving is a mechanism to do performance fine tuning. This option interleaves memory between banks on a DIMM.

**BLDOPT\_REMOVE\_NODE\_INTERLEAVE**

Interleaving is a mechanism to do performance fine tuning. This option interleaves memory from two HyperTransport™ nodes.

**BLDOPT\_REMOVE\_PARALLEL\_TRAINING**

For multi-socket systems, training memory in parallel can reduce the time needed to boot.

**BLDOPT\_REMOVE\_HW\_RDDQS\_2D\_TRAINING**

Memory training that can take voltage into account as well as timing, is 2D training.

**BLDOPT\_REMOVE\_ONLINE\_SPARE\_SUPPORT**

Online Spare support is removed by this option. The operation of this feature is described in “On-Line Spares” on page 300.

**BLDOPT\_REMOVE\_ON\_DIMM\_THERMAL\_SUPPORT**

Support for on DIMM thermal sensors is removed by this option.

**BLDOPT\_REMOVE\_AMP\_SUPPORT**

Support for the AMP memory overclocking feature is removed by this option.

**BLDOPT\_REMOVE\_MULTISOCKET\_SUPPORT**

Many systems use only a single socket and may benefit in code space to remove this code. However, certain processors have multiple HyperTransport™ nodes within a single socket. For these processors, the multi-node support is required and this option has no effect.

**BLDOPT\_REMOVE\_ACPI\_PSTATES**

This option removes the code that generates the ACPI tables used in power management.

**BLDOPT\_REMOVE\_WHEA**

This option removes the code that generates the WHEA tables used in error handling and reporting.

**BLDOPT\_REMOVE\_DMI**

This option removes the code that generates the DMI tables used in system management.
**BLDOPT_REMOVE_DQS_TRAINING**
This option removes the code used in memory performance tuning.

**BLDOPT_REMOVE_C6_STATE**
This option removes the code which implements the C6 C-State feature.

**BLDOPT_REMOVE_CRAT**
This option removes the code which implements the ACPI Component Resource Affinity Table (CRAT).

**BLDOPT_REMOVE_CDIT**
This option removes the code which implements the ACPI Component Locality Distance Information Table (CDIT).

**BLDOPT_REMOVE_MEM_RESTORE_SUPPORT**
This option removes the memory context restore feature.

**BLDOPT_REMOVE_EARLY_SAMPLES**
Special support for Early Samples is included. Default setting is FALSE.

**BLDOPT_REMOVE_FAMILY_10_SUPPORT**
This option removes the code which implements support for family 10h processors. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_FAMILY_12_SUPPORT**
This option removes the code which implements support for family 12h processors. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_FAMILY_14_SUPPORT**
This option removes the code which implements support for family 14h processors. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_FAMILY_15_SUPPORT**
This option removes the code which implements support for family 15h processors, models 00h through 0Fh. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_FAMILY_15_MODEL_1X_SUPPORT**
This option removes the code which implements support for family 15h processors, models 10h through 1Fh. If the platform does not include support, then this option has no effect.
**BLDOPT_REMOVE_FAMILY_15_MODEL_3X_SUPPORT**
This option removes the code which implements support for family 15h processors, models 30h through 3Fh. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_AM3_SOCKET_SUPPORT**
This option removes the code which implements support for processors packaged for AM3 sockets. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_ASB2_SOCKET_SUPPORT**
This option removes the code which implements support for processors packaged for ASB2 sockets. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_C32_SOCKET_SUPPORT**
This option removes the code which implements support for processors packaged for C32 sockets. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_FM1_SOCKET_SUPPORT**
This option removes the code which implements support for processors packaged for FM1 sockets. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_FP1_SOCKET_SUPPORT**
This option removes the code which implements support for processors packaged for FP1 sockets. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_FS1_SOCKET_SUPPORT**
This option removes the code which implements support for processors packaged for FS1 sockets. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_FT1_SOCKET_SUPPORT**
This option removes the code which implements support for processors packaged for FT1 sockets. If the platform does not include support, then this option has no effect.

**BLDOPT_REMOVE_FP3_SOCKET_SUPPORT**
This option removes the code which implements support for processors packaged for FP3 sockets. If the platform does not include support, then this option has no effect.
BLDOPT_REMOVE_FM2_SOCKET_SUPPORT

This option removes the code which implements support for processors packaged for FM2 sockets. If the platform does not include support, then this option has no effect.

BLDOPT_REMOVE_FS2_SOCKET_SUPPORT

This option removes the code which implements support for processors packaged for FS2 sockets. If the platform does not include support, then this option has no effect.

BLDOPT_REMOVE_G34_SOCKET_SUPPORT

This option removes the code which implements support for processors packaged for G34 sockets. If the platform does not include support, then this option has no effect.

BLDOPT_REMOVE_S1G3_SOCKET_SUPPORT

This option removes the code which implements support for processors packaged for S1g3 sockets. If the platform does not include support, then this option has no effect.

BLDOPT_REMOVE_S1G4_SOCKET_SUPPORT

This option removes the code which implements support for processors packaged for S1g4 sockets. If the platform does not include support, then this option has no effect.

BLDOPT_REMOVE_CONNECTED_STANDBY

This option removes the code which implements support for Connected Standby. Some customers will prefer to use secure s3 instead of Connected Standby and will want to be able to completely remove the code. If the platform does not include support, then this option has no effect.

BLDOPT_REMOVE_S3_SUPPORT

This option removes the code which implements support for s3. Some customers prefer alternative power management like Connected Standby, or have ‘always on’ units.

16.2 Build Configuration Elements

Build configuration elements are settings that specify platform-specific boundaries chosen by the motherboard designer. These settings do not affect the size of code like the build options above. These elements are used to import into the build the data values that describe the individual motherboard on which the code build executes.
The user specifies build configuration elements in the `<plat>Options.c` source file local to their project. Use of these configuration elements is completely optional; the specified defaults are used if the element is not specified in the file.

### 16.2.1 Platform Descriptive Elements

This group of elements provide information to the AGESA software about the design implementation of the customer motherboard.

#### 16.2.1.1 Voltage Regulation Module Elements

The Voltage Regulation Modules (VRM) are built by third party vendors. The VRMs used on a platform must meet the requirements specified in the AMD Infrastructure Road Map docs (see “Related Documents” on page 20). The following elements describe the VRM capabilities to the AGESA software.

There are 3 main power rails supplied into the processor for which VRM capabilities can be indicated, the processor cores, the NorthBridge (memory & PCIe root complex) and the graphics processor cores. There is one set of elements for each power lane.

- `BLDCFG_VRM_CURRENT_LIMIT`
- `BLDCFG_VRM_NB_CURRENT_LIMIT`
- `BLDCFG_VRM_GFX_CURRENT_LIMIT`

This value indicates the maximum current that the voltage regulators is capable of providing to the (Core | NB | GFX) processor on a continuous basis. This a numeric value and must be in milliamperes. For example, a current limit of 12.6 amperes is represented as:

```c
#define BLDCFG_VRM_CURRENT_LIMIT 12600
```

- `BLDCFG_VRM_LOW_POWER_THRESHOLD`
- `BLDCFG_VRM_NB_LOW_POWER_THRESHOLD`
- `BLDCFG_VRM_GFX_LOW_POWER_THRESHOLD`

Some models of processor support an ability (output signal to the VRM) to indicate when the processor is in a low-power state. This feature can be used by the power regulator to place itself into a more power-efficient mode. This parameter specifies the maximum current in mA that the power regulator can supply to the (Core | NB | GFX) in its power efficiency mode. This value is translated into a PState threshold. When the processor enters a PState under this threshold, the power regulator is signaled that it can enter its power efficiency mode. Note that some VRMs may require this value to reflect a current “in-rush” component.

1. Family Specific parameter.
The default action is to set a value of zero, indicating to disable the feature. To specify a threshold, the value must be specified in milli-amps. For example, a current of 2.75 amps is represented as:

```
#define BLDCFG_VRM_LOW_POWER_THRESHOLD 2750
```

`BLDCFG_VRM_SLEW_RATE`

`BLDCFG_VRM_NB_SLEW_RATE`

`BLDCFG_VRM_GFX_SLEW_RATE`<sup>1</sup>

This value signifies the rate at which the executing core voltage regulator is capable of transitioning from one voltage level to the next, including any delay. This number is defined as the number of milli-volts per micro-second. For example, a slew rate of 2.5 mV/μS is represented as:

```
#define BLDCFG_VRM_SLEW_RATE 2500
```

`BLDCFG_VRM_HIGH_SPEED_ENABLE`

`BLDCFG_VRM_NB_HIGH_SPEED_ENABLE`

`BLDCFG_VRM_GFX_HIGH_SPEED_ENABLE`

This value indicates whether or not the VRM is capable of operating at high frequency. Set this according to the VRM for the board. The default is FALSE.

TRUE — The VRM supports high frequency operation.
FALSE — The VRM does not support high frequency operation.

Example:

```
#define BLDCFG_VRM_LINK_FREQUENCY TRUE
```

`BLDCFG_VRM_MAXIMUM_CURRENT_LIMIT`

`BLDCFG_VRM_NB_MAXIMUM_CURRENT_LIMIT`

`BLDCFG_VRM_GFX_MAXIMUM_CURRENT_LIMIT`

This value indicates the maximum current that the voltage regulator is capable of providing to the executing (Core | NB | GFX) for short amounts of time. This a numeric value and must be in milliamperes. For example, a current limit of 12.6 amperes is represented as:

```
#define BLDCFG_VRM_MAXIMUM_CURRENT_LIMIT 12600
```

---

<sup>1</sup> Family Specific parameter.
This value is the over-current level at which the VRM will reduce current in order to protect electrical components from damage. This a numeric value and must be in milliamperes. For example, a current limit of 18.9 amperes is represented as:

```c
#define BLDCFG_VRM_SVI_OCP_LEVEL 18900
```

### 16.2.2 System Descriptive Elements

**BLDCFG_CPU_FREQUENCY_LIMIT**

This element specifies a maximum frequency at which the CPU core should operate.

- Zero (0) - (default) No limit is applied. The core will run to their fused maximum frequency.

- N (non-zero) - This value will be used to limit boost and SW PStates. This value is presented in MegaHertz. For example, a limit of 1600Mhz is set as:

```c
#define BLDCFG_CPU_FREQUENCY_LIMIT 1600
```

**BLDCFG_PCI_MMIO_BASE**

Specifies an address to be used as the extended MMIO PCI configuration base address. The address may be up to 48 bits and must be aligned on “BLDCFG_PCI_MMIO_SIZE”. The default is zero, which disables the extended MMIO method.

**BLDCFG_PCI_MMIO_SIZE**

The size of the Extended MMIO region. Must be 1, 2, 4, 8, 16, 32, 64, 128, or 256 MBytes. Default is zero.

**BLDCFG_PLATFORM_NUM_IO_APICS**

This element provides the number of IO APICs that are used on the motherboard. This is used by the software to appropriately assign APIC IDs to the processors, leaving room for the motherboard devices. The default setting is 3.

For example:

```c
#define BLDCFG_PLATFORM_NUM_IO_APICS 4
```

1. Family Specific parameter.
16.2.3 Software Table Elements

This group of elements control the content and features of the software based features tables (e.g. ACPI, DMI, etc.)

BLDCFG_REMOVE_ACPI_PSTATES_PPC
Remove the ACPI PPC table from the ACPI table output.

BLDCFG_REMOVE_ACPI_PSTATES_PCT
Remove the ACPI PCT table from the ACPI table output.

BLDCFG_REMOVE_ACPI_PSTATES_PSD
Remove the ACPI PSD table from the ACPI table output.

BLDCFG_REMOVE_ACPI_PSTATES_PSS
Remove the ACPI PSS table from the ACPI table output.

BLDCFG_REMOVE_ACPI_PSTATES_XPSS
Remove the ACPI XPSS table from the ACPI table output.

BLDCFG_ACPI_SET_OEM_ID
Set the OEM ID field in ACPI table outputs to this string. The string must conform to the ACPI rules for the OEM ID field. The default value is “AMD”.

BLDCFG_ACPI_SET_OEM_TABLE_ID
Set the OEM TABLE ID field in ACPI table outputs to this string. The string must conform to the ACPI rules for the OEM TABLE ID field. By default arbitrary table names will be used.

BLDCFG_FORCE_INDEPENDENT_PSD_OBJECT
This element selects whether P-States should be forced to be independent, as reported by the ACPI _PSD object. This setting can improve performance for OS which support this feature. The default value is FALSE, which results in a processor specific setting. Processors which do not default to independent, default to dependent.

TRUE — Report independent P-State control.
FALSE — The PSD will report the default P-State independence or dependence.

BLDCFG_PROCESSOR_SCOPE_NAME0
This element allows a customized choice for the first letter in the ACPI processor scope name. The default is “C”.
BLDCFG_PROCESSOR_SCOPE_NAME1

This element allows a customized choice for the second letter in the ACPI processor scope name. The default is “0”.

BLDCFG_PROCESSOR_SCOPE_IN_SB

This element specifies whether ACPI _PSS objects are defined in the system bus or processor scope.
TRUE — The objects will be under the _SB scope.
FALSE — The objects will be under the _PR scope (default).

16.2.4 Processor and General Elements

BLDCFG_PLATFORM_CSTATE_MODE

This element specifies the C State operational mode. This can be used with processors which support C States other than C1e.
CStateModeDisabled — The feature is not enabled.
CStateModeC6 — (default) Enable C6 C State.

BLDCFG_PLATFORM_CSTATE_OPDATA

This element specifies some pertinent data needed for the operation of the C State feature. For CStateModeC6, this item is reserved.

BLDCFG_PLATFORM_CSTATE_IO_BASE_ADDRESS

This element specifies some pertinent data needed for the operation of the C State feature. This item specifies a free block of 8 consecutive bytes of I/O ports that can be used to allow the CPU to enter C States. This item should always be specified regardless of the C State mode selected. The default value of zero disables I/O C State transitions.

BLDCFG_CPU_CONNECTED_STANDBY_MODE

This element specifies how to enable the Connected Standby feature. Note the Connected Standby feature is an optional code block. This option will only be effective when the code is present, see “BLDOPT_REMOVE_CONNECTED_STANDBY” on page 186.
ConnectedStandbyAuto - (default) processors supporting Connected Standby will have it enabled.
ConnectedStandbyDisabled - force ConnectedStandby to be disabled. This does not affect the presence of the support code block.
**BLDCFG_PLATFORM_CPB_MODE**

This item allows Core Performance Boost (CPB) to be forced to disabled, even if the hardware provides this feature. By default, CPB is enabled for processors that support it.

CpbModeAuto - (default) processors with CPB will have it enabled.
CpbModeDisabled - force CPB to be disabled.

**BLDCFG_HYBRID_BOOST_ENABLE**

This element specifies to enable hybrid boost mode for processors which support it.

TRUE - The Hybrid Boost feature is enabled (default).
FALSE - The Hybrid Boost feature is not enabled.

**BLDCFG_CORE_LEVELING_MODE**

A multi-socket system can be populated with processors having various number of CPU cores. Many operating systems require a homogeneous system with regard to processor feature set and some operating systems are limited in how many cores they can support. This parameter allows control of how the number of CPU cores is leveled to meet the various requirements.

CORE_LEVEL_LOWEST—(default) also known as: Automatic mode. All processors are leveled to have the same number of cores. The number of cores is reduced to match the processor with the minimum number of cores.

CORE_LEVEL_TWO — Force all processors to use only two cores. This may be required by some operating systems that do not recognize processors with more than two cores. If any processor has only one core, then all processors are leveled to one core.

CORE_LEVEL_POWER_OF_TWO — Power of 2 mode. All processors are leveled to have the same number of cores. The number of cores is reduced to match the processor with the minimum number of cores, with an additional reduction to the nearest power of 2 (1, 2, 4, or 8). This is required by some operating systems.

CORE_LEVEL_NONE — No leveling performed. All processors are left at their natural number of cores. A very select few operating systems may support this configuration, which allows a system with processors having a variety of numbers of cores.

CORE_LEVEL_COMPUTE_UNIT — Level cores to one core per compute unit, with additional reduction to level all processors to match the processor with the minimum number of cores. For processors which do not have compute units, this is the same as CORE_LEVEL_LOWEST.

CORE_LEVEL_COMPUTE_UNIT_TWO — Level cores to two cores per compute unit, with additional reduction to level all processors to match the processor with the minimum number of cores. For processors which
do not have compute units, this is the same as CORE_LEVEL_LOWEST.

CORE_LEVEL_COMPUTE_UNIT_THREE — Level cores to three cores per compute unit, with additional reduction to level all processors to match the processor with the minimum number of cores. For processors which do not have compute units, this is the same as CORE_LEVEL_LOWEST.

For general purpose usage it is recommended to use one of the above leveling modes. However, for a few very specific applications the explicit leveling controls below are available. Note that some processors may not be capable of supporting all of these options. For example, MCM processors can not have an odd number of cores. For an odd CORE_LEVEL_N, MCM processors will be leveled as though CORE_LEVEL_N+1 was chosen.

Processors with compute units disable all cores in an entire compute unit at a time, or on an MCM processor, two compute units at a time. For example, on an SCM processor with two cores per compute unit, the effective explicit levels are CORE_LEVEL_ONE, CORE_LEVEL_TWO, CORE_LEVEL_FOUR, CORE_LEVEL_SIX, and CORE_LEVEL_EIGHT. The same example for an MCM processor with two cores per compute unit has effective explicit levels of CORE_LEVEL_TWO, CORE_LEVEL_FOUR, CORE_LEVEL_EIGHT, and CORE_LEVEL_TWELVE.

CORE_LEVEL_ONE — Explicit leveling. Set leveling to one core per processor. MCM processors will be leveled as though CORE_LEVEL_TWO was chosen.

CORE_LEVEL_THREE — Explicit leveling. Set leveling to three cores. If any processor has less than three cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. MCM processors will be leveled as though CORE_LEVEL_FOUR was chosen.

CORE_LEVEL_FOUR — Explicit leveling. Set leveling to four cores. If any processor has less than four cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen.

CORE_LEVEL_FIVE — Explicit leveling. Set leveling to five cores. If any processor has less than five cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. MCM processors will be leveled as though CORE_LEVEL_SIX was chosen. Additionally, processors with compute units will be leveled to contain complete compute units.

CORE_LEVEL_SIX — Explicit leveling. Set leveling to six cores. If any processor has less than six cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. Additionally, processors with compute units will be leveled to contain complete compute units.
CORE_LEVEL_SEVEN — Explicit leveling. Set leveling to seven cores. If any processor has less than seven cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. MCM processors will be leveled as though CORE_LEVEL_EIGHT was chosen. Additionally, processors with compute units will be leveled to contain complete compute units.

CORE_LEVEL_EIGHT — Explicit leveling. Set leveling to eight cores. If any processor has less than eight cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen.

CORE_LEVEL_NINE — Explicit leveling. Set leveling to nine cores. If any processor has less than nine cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. MCM processors will be leveled as though CORE_LEVEL_TEN was chosen. Additionally, processors with compute units will be leveled to contain complete compute units.

CORE_LEVEL_TEN — Explicit leveling. Set leveling to ten cores. If any processor has less than ten cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. Additionally, processors with compute units will be leveled to contain complete compute units.

CORE_LEVEL_ELEVEN — Explicit leveling. Set leveling to eleven cores. If any processor has less than eleven cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. MCM processors will be leveled as though CORE_LEVEL_TWELVE was chosen. Additionally, processors with compute units will be leveled to contain complete compute units.

CORE_LEVEL_TWELVE — Explicit leveling. Set leveling to twelve cores. If any processor has less than twelve cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen.

CORE_LEVEL_THIRTEEN — Explicit leveling. Set leveling to thirteen cores. If any processor has less than thirteen cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. MCM processors will be leveled as though CORE_LEVEL_FOURTEEN was chosen. Additionally, processors with compute units will be leveled to contain complete compute units.

CORE_LEVEL_FOURTEEN — Explicit leveling. Set leveling to fourteen cores. If any processor has less than fourteen cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. Additionally, processors with compute units will be leveled to contain complete compute units.

CORE_LEVEL_FIFTEEN — Explicit leveling. Set leveling to fifteen cores. If any processor has less than fifteen cores, then all processors are leveled as though CORE_LEVEL_LOWEST were chosen. MCM processors will be leveled as though CORE_LEVEL_LOWEST was chosen.
Additionally, processors with compute units will be leveled to contain complete compute units.

Example:

```
#define BLDCFG_CORE_LEVELING_MODE CORE_LEVEL_TWO
```

**BLDCFG_AP_MTRR_SETTINGS_LIST**

The ApMtrrSettingsList allows the customization of the APs' Fixed-Sized MTRR settings. The MTRR settings are applied after early initialization before IBV takes control of the APs. This control only applies to the x86-64 Architecture APUs.

The default value is NULL, indicating that no MTRR override setting is provided. To provide an override setting list, assign the build element to the name of a user defined settings table. For details, refer to the internal documentation, “Internal Documentation” on page 26.

Only the MTRRs listed in the user defined table will be overwritten; the settings for the other fixed-sized MTRRs will be set to default values. The default Fixed-Sized MTRR settings are:

- 0x00000 - 0x9FFFF : WB Memory
- 0xA0000 - 0xDFFFF : UC I/O
- 0xE0000 - 0xFFFFF : UC Memory

For example,

```
#define BLDCFG_AP_MTRR_SETTINGS_LIST &MyApMtrrsList
```

**BLDCFG_PLATFORM_CONTROL_FLOW_MODE**

This value is used to select the optimum flow control method for the platform. Considerations include Display Refresh, Isochronous Flow and IOMMU. The available values are listed in the AGESA.h file in the enumeration declaration for PLATFORM_CONTROL_FLOW. The default is Nfcm, for Normal Control Flow Mode.

Example:

```
#define BLDCFG_PLATFORM_CONTROL_FLOW_MODE Iommu
```

**BLDCFG_USE_SYNCFLOOD_AS_NMI**

This specifies the function of the SYNCFLOODNMI# pin.

- FALSE - The pin will be defined for sync flood (default).
- TRUE - The pin will be defined for NMI.
16.2.5 Memory Elements

16.2.5.1 Memory Configuration Elements

**BLDCFG_NB_PSTATES_SUPPORTED**

This value indicates whether to enable processor northbridge (NB) P-States (as opposed to processor core P-States).

- TRUE - Enable NB P-States, if supported by the processor (default).
- FALSE - Disable NB P-States.

**BLDCFG_MEMORY_BUS_FREQUENCY_LIMIT**

This is the maximum memory clock at which the platform memory busses are capable of performing.

- DDR400_FREQUENCY
- DDR667_FREQUENCY
- DDR1066_FREQUENCY
- DDR1600_FREQUENCY
- DDR2100_FREQUENCY
- DDR2400_FREQUENCY
- DDR533_FREQUENCY
- DDR800_FREQUENCY (default)
- DDR1333_FREQUENCY
- DDR1866_FREQUENCY
- DDR2133_FREQUENCY

Example:

```c
#define BLDCFG_MEMORY_BUS_FREQUENCY_LIMIT DDR1066_FREQUENCY
```

**BLDCFG_MEMORY_MODE_UNGANGED**

The platform should be set to use the memory channel unganged mode.

- TRUE (default)
- FALSE

Example:

```c
#define BLDCFG_MEMORY_MODE_UNGANGED FALSE
```

**BLDCFG_MEMORY_QUAD_RANK_CAPABLE**

This is a platform-specific setting indicating that the memory slots are capable of supporting Quad Rank DIMMs.

- TRUE (default)
- FALSE

Example:

```c
#define BLDCFG_MEMORY_QUAD_RANK_CAPABLE FALSE
```
**BLDCFG_MEMORY_QUADRANK_TYPE**

If the platform sets QRankCapable, then the Quad Rank DIMM slot type is one of the following:

- QUADRANK_REGISTERED (4-Rank Registered DIMMs) (default)
- QUADRANK_UNBUFFERED (Unbuffered SO-DIMMs)

If the platform is not indicated to be Quad Rank capable, then this element has no effect.

Example:

```c
#define BLDCFG_MEMORY_QUADRANK_TYPE QUADRANK_REGISTERED
```

**BLDCFG_MEMORY_SODIMM_CAPABLE**

Specifies if the platform is designed to be capable of supporting SoDIMMs.

- TRUE
- FALSE (default)

Example:

```c
#define BLDCFG_MEMORY_SODIMM_CAPABLE TRUE
```

**BLDCFG_MEMORY_LRDIMM_CAPABLE**

Specifies if the platform is designed to be capable of supporting LRDIMMs. This item has no effect when “BLDOPT_REMOVE_LRDIMMS_SUPPORT” is TRUE.

- TRUE
- FALSE (default)

Example:

```c
#define BLDCFG_MEMORY_LRDIMM_CAPABLE TRUE
```

**BLDCFG_MEMORY_RDIMM_CAPABLE**

Specifies if the platform is designed to be capable of supporting RDIMMs. This item has no effect when “BLDOPT_REMOVE_RDIMMS_SUPPORT” is TRUE.

Options are:

- TRUE (default)
- FALSE

Example:

```c
#define BLDCFG_MEMORY_RDIMM_CAPABLE TRUE
```
BLDCFG_MEMORY_UDIMM_CAPABLE

Specifies if the platform is designed to be capable of supporting UDIMMs. This item has no effect when “BLDOPT_REMOVE_UDIMMS_SUPPORT” is TRUE. Options are:

- TRUE (default)
- FALSE (default)

Example:

```c
#define BLDCFG_MEMORY_UDIMM_CAPABLE TRUE
```

BLDCFG_MEMORY_ENABLE_BANK_INTERLEAVING

Specifies if the system should use DRAM bank (also known as chip-select) interleaving. If the build option is set to include the code for this feature, then this setting activates the feature. If the feature code is removed from the build, then this element has no effect.

The AMD-recommended setting is indicated by the default setting. Changes to this setting must be based on individual platform testing.

- TRUE = enable
- FALSE = disable (default)

Example:

```c
#define BLDCFG_MEMORY_ENABLE_BANK_INTERLEAVING TRUE
```

BLDCFG_MEMORY_ENABLE_NODE_INTERLEAVING

Specifies if the system should use memory node interleaving. If the build option is set to include the code for this feature, then this setting activates the feature. If the feature code is removed from the build, then this element has no effect.

The AMD-recommended setting is indicated by the default setting. Changes to this setting must be based on individual platform testing.

- TRUE = enable
- FALSE = disable (default)

Example:

```c
#define BLDCFG_MEMORY_ENABLE_NODE_INTERLEAVING TRUE
```

BLDCFG_MEMORY_CHANNEL_INTERLEAVING

Specifies if the system should use memory channel interleaving for performance tuning. If the build option is set to include the code for this feature, then this setting activates the feature. If the feature code is removed from the build, then this element has no effect. Also, this option has no effect if the channel ganged mode is selected.
The AMD-recommended setting is indicated by the default setting. Changes to this setting must be based on individual platform testing.

TRUE = enable (default)    FALSE = disable

Example:

#define BLDCFG_MEMORY_ENABLE_CHANNEL_INTERLEAVING TRUE

BLDCFG_ONLINE_SPARE

This feature is recommended only for expert users and is described in the BIOS and Kernel Developer's Guides (BKDG).

TRUE = enable Spare    FALSE = disable Spare (default)

Example:

#define BLDCFG_ONLINE_SPARE TRUE

BLDCFG_MEMORY_PARITY_ENABLE

Parity is an error-detection tool available on some DIMMs. This control specifies whether or not the memory controller should activate parity checking. The feature is invoked only if the DIMMs present are all capable of supporting the parity detection.

TRUE = enable    FALSE = disable (default)

Example:

#define BLDCFG_MEMORY_PARITY_ENABLE TRUE

BLDCFG_BANK_SWIZZLE

Address swizzle is a performance fine-tuning element that swaps some address lines. See the BKDG for description.

TRUE - enable (default)    FALSE - disable

Example:

#define BLDCFG_BANK_SWIZZLE FALSE

BLDCFG_MEMORY_ALL_CLOCKS_ON

This is a power-usage control. To save power, unused memory clocks are disabled. Some platforms may not prefer to use this feature.

TRUE = Enable all memclocks whether they are used or not.    FALSE = Unused memclocks are disabled (default).

Example:
#define BLDCFG_MEMORY_ALL_CLOCKS_ON TRUE

**BLDCFG_DDR_PHY_DLL_BYPASS_MODE**

This element enables a low power DDR bus operation mode, which is useful for soldered down memory subsystems that follow low power design guidelines. This feature will limit the maximum DDR rate and should be disabled for high performance memory subsystem designs. This feature should be disabled for systems with DIMM slots rather than soldered down memory.

TRUE - Enable (default).
FALSE - Disable.

**BLDCFG_MEMORY_PHY_VOLTAGE**

This element specifies the voltage used to supply the Memory PHY circuits. This is a platform specific part of the design available for controlling power consumption. For more information, please refer to the processor power specification. Note that the platform may be requested to change the PHY voltage via the “AgesaHookBeforeDramInit” using the parameter “VddpVddrVoltage” on page 118.

VOLT0_95 - The platform design specifies use of the lower voltage to save power.
VOLT1_05 - (default) Use the standard required voltage.

**BLDCFG_ENABLE_ECC_FEATURE**

This turns on the correction action and enables the ability of the MCA sub-system to report errors. It does not activate the MCA error report interrupts. If the build option is set to include the code for the ECC feature, then this setting activates the feature. If the feature code is removed from the build, then this element has no affect.

TRUE = enable (default)
FALSE = disable

Example:

#define BLDCFG_ENABLE_ECC_FEATURE FALSE

**BLDCFG_ECC_REDIRECTION**

DRAM ECC redirection is a data-protection feature. Redirection is a special ECC feature that enables the scrubber to immediately scrub any address in which a correctable error is discovered.

The AMD recommended setting is indicated by the default setting. Changes to this setting must be based on individual platform testing.
TRUE = enable  FALSE = disable (default)

Example:

```c
#define BLDCFG_ECC_REDIRECTION TRUE
```

**BLDCFG_UMA_ALLOCATION_MODE**

Supply the UMA memory allocation mode build time customization, if any. The default mode is Auto.

- UMA_NONE — no UMA memory will be allocated.
- UMA_SPECIFIED — up to the requested UMA memory will be allocated.
- UMA_AUTO — allocate the optimum UMA memory size for the platform.
  For APUs with integrated graphics, this will provide the optimum UMA allocation for the platform and for other platforms will be the same as NONE.

**BLDCFG_UMA_ALLOCATION_SIZE**

Provide a build time customization of the UMA allocation size input. If the UmaAllocationMode is SPECIFIED, up to this amount of UMA memory will be allocated, otherwise, it will be ignored. The size must be a multiple of 64 KBytes.

**BLDCFG_UMA_ALIGNMENT**

This control specifies any alignment requirements for the UMA buffer dictated by the video device.

- NO_UMA_ALIGNED - (Default) There are no imposed restrictions.
- UMA_4MB_ALIGNED - The UMA buffer must be aligned to a 4MB boundary.
- UMA_128MB_ALIGNED - The UMA buffer must be aligned to a 128MB boundary.
- UMA_256MB_ALIGNED - The UMA buffer must be aligned to a 256MB boundary.
- UMA_512MB_ALIGNED - The UMA buffer must be aligned to a 512MB boundary.

**BLDCFG_UMA_ABOVE4G_SUPPORT**

Video devices and their associated drivers may require that the UMA buffer be located in the 32bit address space. This control provides that selection.

- FALSE - (Default) Keep the UMA buffer in the 32bit address range (e.g. below the 4GB boundary).
- TRUE - The UMA buffer may be placed above the 4GB boundary, in the 64bit address space.
**BLDCFG_LIMIT_MEMORY_TO_BELOW_1TB**

This item provides for ensuring that the top of memory is limited to below 1 TByte. This may be needed for certain operating systems.

FALSE - Not limited. Top of memory will be greater than 1 TByte if sufficient memory is installed. Memory may be hoisted above 1 TByte to make it accessible.

TRUE - Limited (default). Top of memory will be below 1 TByte no matter how much memory is installed; any additional memory will not be accessible.

**BLDCFG_ENABLE_EXTERNAL_VREF_FEATURE**

This item specifies whether to use an external, platform specific, memory Vref control.

FALSE - Use internal Vref control (default).

TRUE - Use the callout AgesaExternal2dTrainVrefChange.

**BLDCFG_DIMM_TYPE_USED_IN_MIXED_CONFIG**

Specifies how to handle installations of mixed memory technology. If the processor supports more than one memory technology, only channels with the specified memory technology will be enabled and other channels will be disabled. Both sets of channels must contain supported memory technology DIMMs. Specifying a memory type that is not supported by the processor is treated the same as specifying UNSUPPORTED_TECHNOLOGY. The default is DDR3_TECHNOLOGY if the processor supports it, otherwise it is family specific.

- DDR2_TECHNOLOGY - Unsupported.
- DDR3_TECHNOLOGY - Enable only DDR3 memory channels (default).
- GDDR5_TECHNOLOGY - Enable only GDDR5 memory channels.
- UNSUPPORTED_TECHNOLOGY - Do not support mixed installations.

### 16.2.5.2 Memory Operations Elements

**BLDCFG_USE_32_BYTE_REFRESH**

This is a performance optimization setting and indicates whether or not to enable use of smaller refresh packets. This is a BOOLEAN value:

FALSE — Do not enable the feature (default).

TRUE — Activate the feature.

Example:

```c
#define BLDCFG_USE_32_BYTE_REFRESH TRUE
```
**BLDCFG_DRAM_DOUBLE_REFRESH_RATE**

This is a performance optimization setting and indicates whether or not to refresh the memories at twice the rate calculated or as indicated in the SPD information. This faster frequency refresh is likely to be employed in cases where extended temperature support is desired or smaller geometry DRAM technologies are utilized.

This is a BOOLEAN value:

FALSE — Use the standard refresh rate (default). {Example: 7.8us}

TRUE — Double the refresh rate (cut period in half). {Example: 3.9us}

Example:

```c
#define BLDCFG_DRAM_DOUBLE_REFRESH_RATE TRUE
```

**BLDCFG_MEMORY_ALTERNATIVE_MAX_ACTIVATE_COUNT**

This is a performance and security optimization setting that indicates a limit on how fast back-to-back accesses are permitted. This is a new feature to the JEDEC DDR3 and DDR4 specifications to prevent a security vulnerability referred to as ‘hammering’. The addition was a MAC parameter (Maximum Activity Count). This control works in conjunction with the “BLDCFG_DRAM_DOUBLE_REFRESH_RATE” control above.

For AMD APUs, this feature is implemented as a T\textsubscript{rpage} timing parameter.

For APUs without T\textsubscript{rpage}:

```c
if (BLDCFG_MEMORY_ALTERNATIVE_MAX_ACTIVATE_COUNT == MAC_UNTESTEDMAC)
    T\textsubscript{ref} is set according to BLDCFG_DRAM_DOUBLE_REFRESH_RATE
else
    { 
        if (BLDCFG_MEMORY_ALTERNATIVE_MAX_ACTIVATE_COUNT != MAC_UNRESTRICTEDMAC)
            if (SPD.MAC == 'Unrestricted')
                T\textsubscript{ref} is set according to BLDCFG_DRAM_DOUBLE_REFRESH_RATE
            else 
                T\textsubscript{ref} is always set to double refresh rate; 
    }
```

For APUs with T\textsubscript{rpage}:

```c
T\textsubscript{ref} is always set according to BLDCFG_DRAM_DOUBLE_REFRESH_RATE.
if (SPD.MAC = 'untested')
{ // (0x00)defined by JEDEC as backward compatible SPD entry
    if (BLDCFG_MEMORY_ALTERNATIVE_MAX_ACTIVATE_COUNT == MAC_UNTESTEDMAC)
        'Unrestricted MAC’ is applied to T\textsubscript{rpage}
    else
        BLDCFG_MEMORY_ALTERNATIVE_MAX_ACTIVATE_COUNT is applied as the platform specified MAC to T\textsubscript{rpage}.
}
The following are permitted values:

MAC_UNTESTEDMAC - (Default) Use the SPD setting or the double rate refresh per the above equations.
MAC_700k - Allow 700K accesses within a single refresh period.
MAC_600k - Allow 600K accesses within a single refresh period.
MAC_500k - Allow 500K accesses within a single refresh period.
MAC_400k - Allow 400K accesses within a single refresh period.
MAC_300k - Allow 300K accesses within a single refresh period.
MAC_200k - Allow 200K accesses within a single refresh period.
MAC_UNRESTRICTEDMAC - Unrestricted - allow unlimited accesses.

Example:

#define BLDCFG_MEMORY_ALTERNATIVE_MAX_ACTIVATE_COUNT MAC_200k

One caution: limiting the number of accesses within a refresh period may reduce overall performance.

BLDCFG_MEMORY_EXTENDED_TEMPERATURE_RANGE

This feature will maintain a refresh rate appropriately higher for the DIMM based upon the temperature. This may cause higher power consumption and a slight loss of performance.

FALSE - (default) the feature is disabled. Normal (0-85°C) range is expected.
TRUE - The device may support the extended temperature range (0-95°C). The refresh rate will be adjusted as the temperature on the DIMM changes.

BLDCFG_USE_VARIABLE_MCT_ISOC_PRIORITY

This indicates whether or not to enable the memory controller to use special handling for ISOC transfers. This is a BOOLEAN value:

FALSE — Do not enable the feature (default).
TRUE — Activate the feature.

Example:

#define BLDCFG_USE_VARIABLE_MCT_ISOC_PRIORITY TRUE

BLDCFG_MEMORY_POWER_DOWN

This feature conserves power in the DIMMs by placing them into self-refresh when the memory on a channel is not actively being accessed. They quickly exit self-refresh upon the next processor access.

TRUE = enable
FALSE = disable (default)

Example:

#define BLDCFG_MEMORY_POWER_DOWN TRUE
**BLDCFG_POWER_DOWN_MODE**

This is a power-usage control that performs memory clock enable-based power-down control. If the platform enables power-down capability, then this element describes the platform method chosen, which is one of the following:

- `POWER_DOWN_BY_CHANNEL`
- `POWER_DOWN_BY_CHIP_SELECT`
- `POWER_DOWN_MODE_AUTO` (default)

If the platform is not indicated to have power-down capability, then this element has no affect.

Example:

```c
#define BLDCFG_POWER_DOWN_MODE POWER_DOWN_BY_CHIP_SELECT
```

**BLDCFG_TIMING_MODE_SELECT**

Allows the platform to select how the determination is made for the memory clock that is to be used in the system. (See also `BLDCFG_MEMORY_CLOCK_SELECT`.)

- TIMING_MODE_AUTO — The AGESA™ software calculates the best memory clock rate (default).
- TIMING_MODE_LIMITED — The AGESA™ software calculates the best memory clock, restricted by a maximum user limit provided in `BLDCFG_MEMORY_CLOCK`.
- TIMING_MODE_SPECIFIC — The platform specifies the clock rate, which is provided in `BLDCFG_MEMORY_CLOCK`.

Example:

```c
#define BLDCFG_TIMING_MODE_SELECT TIMING_MODE_LIMITED
```

**BLDCFG_MEMORY_CLOCK_SELECT**

This is the specified memory clock to be used in the system as determined by the selected mode. (See also `BLDCFG_TIMING_MODE_SELECT`.)

- DDR400_FREQUENCY
- DDR533_FREQUENCY
- DDR667_FREQUENCY
- DDR800_FREQUENCY
- DDR1066_FREQUENCY
- DDR1333_FREQUENCY
- DDR1600_FREQUENCY
- DDR1866_FREQUENCY
- DDR2100_FREQUENCY
- DDR2133_FREQUENCY
- DDR2400_FREQUENCY

The default value used depends upon the type of memory present. DDR2 memories use a default value of DDR400_FREQUENCY. DDR3 memories use a default value of DDR800_FREQUENCY.

**BLDCFG_DQS_TRAINING_CONTROL**

DQS signal timing training control is a platform selection to specify whether the automatic timing training routine is desired or a set of pre-defined timing
values should be used. This can provide boot speed improvement by bypassing
the active training algorithm and using previously stored values.

TRUE = perform active DQS training (default)
FALSE = skip DQS training

This feature is recommended only for expert users. Further details can be
found in “Customizing the Environment — Library Functions” on page 222.

Example:

```c
#define BLDCFG_DQS_TRAINING_CONTROL FALSE
```

### BLDCFG_IGNORE_SPD_CHECKSUM

When the checksum of the SPD record fails, the typical action is to drop the
DIMM and not attempt to configure it into the system. The software indicates
via return code that this condition has occurred.

Under certain conditions, the platform can decide to accept the associated risk
and choose to ignore the SPD checksum.

TRUE — Ignore faulty SPD checksum and continue DIMM initialization.
FALSE — If the checksum of an SPD is found to be invalid, then the memory
initialization process is terminated for that DIMM (default).

Example:

```c
#define BLDCFG_IGNORE_SPD_CHECKSUM TRUE
```

### BLDCFG_USE_BURST_MODE

This is a performance fine-tuning element. The effect is described in the
BKDG. This element may not be available in all families.

TRUE — enable (4-beat burst when width is 64 bits)
FALSE — disable (default)

Example:

```c
#define BLDCFG_USE_BURST_MODE TRUE
```

### BLDCFG_SCRUB_DRAM_RATE

This value selects how often the ECC background scrubber makes a pass
through the DRAM. This is a numeric value and the value can vary from
processor family to family.

0 = Disabled (default) 

x_x_x = Scrub Rate, see the BKDG.

Example:

```c
#define BLDCFG_SCRUB_DRAM_RATE 0x0f
```
**BLDCFG_SCRUB_L2_RATE**

This value selects how often the ECC background scrubber makes a pass through the L2 cache. This is a numeric value and the value can vary from processor family to family.
0 = Disabled (default)  x_x_x = Scrub Rate, see the BKDG.

Example:

```
#define BLDCFG_SCRUB_DRAM_RATE 0x0f
```

**BLDCFG_SCRUB_L3_RATE**

This value selects how often the ECC background scrubber makes a pass through the L3 cache. This is a numeric value and the value can vary from processor family to family and may not be available on all families.
0 = Disabled (default)  x_x_x = Scrub Rate, see the BKDG.

Example:

```
#define BLDCFG_SCRUB_DRAM_RATE 0x0f
```

**BLDCFG_SCRUB_IC_RATE**

This value selects how often the ECC background scrubber makes a pass through the IC (Instruction Cache). This is a numeric value and the value can vary from processor family to family.
0 = Disabled (default)  x_x_x = Scrub Rate, see the BKDG.

Example:

```
#define BLDCFG_SCRUB_DRAM_RATE 0x0f
```

**BLDCFG_SCRUB_DC_RATE**

This value selects how often the ECC background scrubber makes a pass through the DC (Data Cache). This is a numeric value and the value can vary from processor family to family.
0 = Disabled (default)  x_x_x = Scrub Rate, see the BKDG.

Example:

```
#define BLDCFG_SCRUB_DRAM_RATE 0x0f
```

**BLDCFG_ECC_SYNC_FLOOD**

This indicates whether or not to cause a sync flood in the system when uncorrectable ECC errors are detected. This is a BOOLEAN value:

FALSE = Do not enable the MCA feature (default).
TRUE = Please see the BKDG for a description of the use of the Sync Flood and why a platform may choose to make use of this feature.

Example:

```c
#define BLDCFG_ECC_SYNC_FLOOD TRUE
```

**BLDCFG_ECC_SYMBOL_SIZE**

This is an error-detection control. Please see the BKDG for a description. This is a numeric value of 0, 4, or 8. Zero means to use the BKDG recommendation. The default is 4.

Example:

```c
#define BLDCFG_ECC_SYMBOL_SIZE 0x00
```

**BLDCFG_PMU_TRAINING_MODE**

For processors which provide a Phy Micro-controller Unit (PMU), this parameter selects the memory data bus training mode which the PMU will perform.

- PMU_TRAIN_1D - perform 1D training only.
- PMU_TRAIN_1D_2D_READ - perform both 1D and 2D read only training.
- PMU_TRAIN_1D_2D - perform both 1D and 2D training.
- PMU_TRAIN_AUTO - The training mode will be automatically selected based on configuration (default).

**BLDCFG_HEAP_DRAM_ADDRESS**

During the transition from pre-memory use of the cache as RAM to the post memory initialization time when main memory storage becomes available, the contents of the AGESA™ software heap must be transferred. This configuration element allows the platform to specify the main memory address where the heap contents will be temporarily stored during the transition. The default memory address used is 0x000B0000. The temporary storage location must be 64K in length. This location must be in the 32bit address space and must be preserved after the call to AmdInitPost until the call to AmdInitEnv.

Example:

```c
#define BLDCFG_HEAP_DRAM_ADDRESS 0x00600000
```

### 16.2.6 Thermal and Power Control Elements

**BLDCFG_BAPM_ENABLE**

Specifies the active state of the BAPM thermal control feature

---

1. This section has Family Specific controls. Please refer to “Family Specific Details” on page 263.
TRUE — (default) the BAPM controls will be used.
FALSE — Disable the BAPM features.

**BLDCFG_AMD_TDP_LIMIT**

Specifies a maximum power limit for the platform. This indicates the capability of the thermal solution (e.g. heat sink) implemented on this platform to dissipate power.

For processors with BAPM support, this limit will be used as the target BAPM TDP. In addition, P-State capping may be used to implement the TDP limit. The default is zero, indicating not to limit TDP but to use the recommended settings. This value is the integer number, in milliwatts, to be used as the TDP limit.

**BLDCFG_GNB_THERMAL_SENSOR_CORRECTION**

This specifies an increment to the default temperature junction (Tj) Offset. This control is for calibrating the on-chip thermal sensor. The thermal sensor correction value corrects for natural sensor variances inherent in the manufacturing process. See the processor’s Thermal Design Guide for details.

### 16.2.7 HD Audio Elements

Two HD Audio devices exist in the system. One is an analog device targeting output to a 3.5mm speaker/headphone jack; and the other is a digital device targeting output to the HDMI/DP display ports.

#### 16.2.7.1 Analog HD Audio

The analog device is migrating from the FCH section to the GNB section in new families. The AGESA interface needs to support both versions, so you will see two controls, each targeting a specific device instance.

**BLDCFG_AZALIA_SSID**

This item is used to set the SSID of the Azalia analog device located in the FCH section.

**BLDCFG_GNB_AZ_SSID**

This item is used to set the SSID of the Azalia analog device located in the GNB section.

---

1. This section has Family Specific controls. Please refer to “Family Specific Details” on page 263.
16.2.7.2 Digital HD Audio

The digital HSD audio device is a component of the GNB or IGPU sections. You may see references to “GNB” or “IGPU”. This instance uses a digital CODEC device for encoding the audio stream. Many of these controls are intended to inform the software as to where to find the device and how to communicate.

**BLDCFG\_CFG\_GNB\_HD\_AUDIO**

This indicates whether to enable HD Audio.

- FALSE - Disabled (default).
- TRUE - Enable HD audio.

**BLDCFG\_MAX\_NUM\_AUDIO\_ENDPOINTS**

This option defines the maximum number of audio endpoints supported by the platform. To be applied, this value must be less than the number of display pipes supported by the APU. This value should be defined if the platform supports a number of audio endpoints that is smaller than the number supported by the APU.

This is a numeric value:

- N - The number of active display pipes, or audio endpoints on the host platform.
- 255 - Max value (Default). Using the default, or not specifying a value will use all endpoints supported on the APU.

**BLDCFG\_GNB\_AZ\_I2SBUS\_SELECT**

Newer CPU/APU designs allow the pins used to connect the (former) Azalia bus can be configured to use the new I2SBus protocol. This option specifies the pin functions.

- GnbAcpAzalia - (default) Use the standard Azalia protocol.
- GnbAcpI2sBus - Use the industry standard I2S Bus protocol.

**BLDCFG\_GNB\_AZ\_I2SBUS\_PIN\_CONFIG**

Newer CPU/APU designs allow the pins used to connect the (former) Azalia bus can be configured to use the new I2S Bus protocol. When **BLDCFG\_GNB\_AZ\_I2SBUS\_SELECT** is set select the I2S Bus protocol, this additional option specifies the I2S protocol.

- GnbAcp4Tx4RxBluetooth - (default).
- GnbAcp2Tx4RxBluetooth - .
- GnbAcp6Tx4RxBluetooth - .

---

Chapter 16 Customizing Platforms 210
**BLDCFG\_IGPU\_HD\_AUDIO\_SUBSYSTEM\_ID**

This item specifies a customized PCIe® Subsystem ID for the IGPU’s (digital) HD Audio device. The default is zero.

### 16.2.8 Graphics and PCIe® Elements

**BLDCFG\_CFG\_ABM\_SUPPORT**

This indicates whether to enable ABM support for display panel back light.

- FALSE - Disabled (default).
- TRUE - Enable ABM.

**BLDCFG\_CFG\_DYNAMIC\_REFRESH\_RATE**

This provides the dynamic display refresh rate. This value is dependent on the display panel used.

If an embedded panel supports a contiguous range of refresh rates but the minimum is not described in its EDID, then this parameter allows the platform to expose the capability. The value here defines the minimum refresh rate, while the maximum refresh rate is obtained from the EDID.

This value is dependent on the display panel used.

*This value has a different meaning for the newer APU s. For 2013 and older APU products, this definition is being deprecated.*

- 0 - Either the embedded panel carries the information in its EDID, or the Platform doesn't need this feature.
- Non-zero: choose one of the following bits to indicate the minimum refresh rate that the panel supports:
  - SUPPORTED\_LCD\_REFRESH\_RATE\_30Hz = 0x0004
  - SUPPORTED\_LCD\_REFRESH\_RATE\_40Hz = 0x0008
  - SUPPORTED\_LCD\_REFRESH\_RATE\_50Hz = 0x0010
  - SUPPORTED\_LCD\_REFRESH\_RATE\_60Hz = 0x0020
  - SUPPORTED\_LCD\_REFRESH\_RATE\_48Hz = 0x0040

For 2014 and onward APU products:

- 0 - Either the embedded panel carries the information in its EDID, or the Platform doesn't need this feature.
- N - A numeric value to indicate the minimum refresh rate that the panel supports.
**BLDCFG_CFG_LCD_BACK_LIGHT_CONTROL**

This provides support for PWM back light control. The value is dependent on the PWM controller and platform characterization.

0 - No display rate specified.
N - Use this number, N, for the PWM control.

**BLDCFG_ACP_SIZE**

This element specifies the size of the Audio Co-Processor (ACP) region. ACP is an audio signal processor used to accelerate audio encode and decode.

- NO_ACP_SIZE   Do not use ACP (default).
- ACP_SIZE_2MB  ACP is allocated 2MBytes region.
- ACP_SIZE_4MB  ACP is allocated 4 MBytes region.

**BLDCFGSTEREO_3D_PINOUT**

Specifies the pin index associated with the Stereo 3D feature.

0 - Stereo 3D is disabled (default).
1 - Use processor pin HPD1.
2 - Use processor pin HPD2.
3 - Use processor pin HPD3.
4 - Use processor pin HPD4.
5 - Use processor pin HPD5.
6 - Use processor pin HPD6.

**BLDCFG_IGPU_SUBSYSTEM_ID**

This item specifies a customized PCIe® Subsystem ID for the processor’s Internal Graphics Processing Unit (IGPU) device. The default is zero.

**BLDCFG_APU_PCIE_PORTS_SUBSYSTEM_ID**

This item specifies a customized PCIe® Subsystem ID for the processor’s PCIe® ports. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_PCIE_TRAINING_ALGORITHM**

This item selects the training algorithm for PCIe® links. Customizing the algorithm used may provide better boot performance, depending on system design. Refer to the internal documentation for the latest and most detailed information (“Internal Documentation” on page 26).

- PcieTrainingStandard - Standard algorithm (default).
- PcieTrainingDistributed - Training is distributed over multiple entry points. This potentially improves S3 resume time, but PCIe® devices are not accessible until later in the boot sequence.
**BLDCFG_IOMMU_SUPPORT**

This indicates whether to enable IOMMU support.

FALSE - Disable IOMMU support.
TRUE - Enable IOMMU support for processors with IOMMU (default).

**BLDCFG_IOMMU_EXCLUSION_RANGE_LIST**

This specifies the IOMMU exclusion ranges for I/O Virtualization.

Details on how to create the list content can be found in “IOMMU Exclusion Range Descriptor” on page 355.

The default value is NULL, indicating that no list is provided. To provide a user-defined list, assign the above name to the name of the user-created data table.

For example:

```c
#define BLDCFG_IOMMU_EXCLUSION_RANGE_LIST MyIommuExclusionList
```

**BLDCFG_GNB_IOAPIC_ADDRESS**

This specifies the IOAPIC base address for the processor IOAPIC. The value is a 64 bit address aligned to 256 byte boundaries. The default value of NULL signifies that the host environment will set the base address itself.

**BLDCFG_GFX_LVDS_SPREAD_SPECTRUM**

This specifies the LVDS spread spectrum value.

0 - Spread spectrum is disabled (default).

n - Values greater than zero specify a setting of 0.0n %. For example, 3 corresponds to a setting of 0.03%.

**BLDCFG_GFX_LVDS_SPREAD_SPECTRUM_RATE**

This specifies the spread spectrum frequency, if “BLDCFG_GFX_LVDS_SPREAD_SPECTRUM” is not disabled.

0 - 40 kHz (default).

n - Values greater than zero specify a setting of (40 + (n * 10)) kHz. For example, 2 corresponds to 60kHz.

**BLDCFG_LVDS_POWER_ON_SEQ_DIGON_TO_DE**

This specifies the LVDS power up sequence time for the delay from DIGON active to Data Enable (DE) active.

0 - Use the video BIOS default (default). The video BIOS default is 32ms.

n - Values other than zero specify a setting of (4 * n) milliseconds time delay.
**BLDCFG_LVDS_POWER_ON_SEQ_DE_TO_VARY_BL**

This specifies the LVDS power up sequence time for the delay from Data Enable (DE) active to Vary Back Light (Vary BL) active.

0 - Use the video BIOS default (default). The video BIOS default is 90 or 360ms.

n - Values other than zero specify a setting of \((4 \times n)\) milliseconds time delay.

**BLDCFG_LVDS_POWER_ON_SEQ_DE_TO_DIGON**

This specifies the LVDS power off sequence time for the delay from DE active to DIGON active.

0 - Use the video BIOS default (default). The video BIOS default is 32ms.

n - Values other than zero specify a setting of \((4 \times n)\) milliseconds time delay.

**BLDCFG_LVDS_POWER_ON_SEQ_VARY_BL_TO_DE**

This specifies the LVDS power up sequence time for the delay from active to active.

0 - Use the video BIOS default (default). The video BIOS default is 32ms.

n - Values other than zero specify a setting of \((4 \times n)\) milliseconds time delay.

**BLDCFG_LVDS_POWER_ON_SEQ_ON_TO_OFF_DELAY**

This specifies the LVDS power sequence time for the delay from OFF to next ON.

0 - Use the video BIOS default (default). The video BIOS default is 500ms.

n - Values other than zero specify a setting of \((4 \times n)\) milliseconds time delay.

**BLDCFG_LVDS_MAX_PIXEL_CLOCK_FREQ**

This specifies the maximum pixel clock frequency.

0 - use the video BIOS default (default). The video BIOS default is 85 MHz.

n - Values other than zero specify a setting of \(n\) MHz.
**BLDCFG_LCD_BIT_DEPTH_CONTROL_VALUE**

This specifies the bit depth control settings, which can be used to tune display panel performance.

0 - Use video BIOS default (default). The video BIOS will auto detect the best settings to use.

n - Values other than zero specify the low level control settings.

**BLDCFG_LVDS_24BBP_PANEL_MODE**

This specifies the LVDS 24 BBP mode.

0 - Use LDI mode (default).

1 - Use FPDI mode.

**BLDCFG_LVDS_MISC_888_FPDI_MODE**

This specifies a miscellaneous control for LVDS.

TRUE - Use FPDI mode.

FALSE - Use LDI mode (default).

**BLDCFG_LVDS_MISC_DL_CH_SWAP**

This specifies a miscellaneous control for LVDS.

TRUE - The upper and lower channel are swapped.

FALSE - The upper and lower channel are not swapped (default).

**BLDCFG_LVDS_BIT_DEPTH**

This specifies a miscellaneous control for LVDS: the bit depth of the panel. The EDID interface may not be able to specify the 24bit (8x8x8) value. This control is used to let the user indicate the proper panel capability.

TRUE - The panel supports 24bit (8x8x8)

FALSE - The panel is 18bit (6x6x6) (default).

**BLDCFG_LVDS_PARAM_OVERWRITE_EN**

This defines the LVDS parameter overwrite enable

TRUE - LVDS parameter overwrite enable

FALSE - LVDS parameter overwrite disable (default).

**BLDCFG_LVDS_MISC_BLON_ACTIVE_LOW**

This specifies a miscellaneous control for LVDS.

TRUE - The BLON signal is active low.

FALSE - The BLON signal is active high (default).
**BLDCFG_LVDS_MISC_VOLT_OVERWRITE_ENABLE**

This specifies the output voltage adjustment, which may be needed with Travis.

FALSE - Use recommended setting (default).
TRUE - Overwrite the output voltage using LVDS Volt Adjustment.

**BLDCFG_LVDS_MISC_VOLT_ADJUSTMENT**

This specifies the output voltage adjustment to be made if enabled, see “BLDCFG_LVDS_MISC_VOLT_OVERWRITE_ENABLE” on page 216.

**BLDCFG_IGPU_ENABLE_DISABLE_POLICY**

This specifies policies for enable or disable of the processor’s internal graphics processing unit (GPU) when discrete graphics cards are present.

0 - Disable the internal graphics if the graphics card is not an AMD PCIe® graphics card (default).
1 - Disable the internal graphics if any graphics card is present.

**BLDCFG_PCIE_REFCLK_SPREAD_SPECTRUM**

When the platform has spread spectrum enabled on the PCIe® reference clock, this item should be used to provide that setting.

0 - Spread spectrum is not enabled for the platform PCIe® reference clock (default).

n - Spread spectrum is enabled at 0.0n %.

**BLDCFG_REMOTE_DISPLAY_SUPPORT**

This specifies whether remote, wireless display is supported.

FALSE - Do not support wireless display (default).
TRUE - Support wireless display.

**BLDCFG_DP_FIXED_VOLT_SWING**

The enhanced Display Port has the ability to handle several signal types that vary in both voltage and DB ranges. Please see the definition of DP_FIXED_VOLT_SWING_TYPE in the file AGESA.H.

**BLDCFG_GPU_FREQUENCY_LIMIT**

This specifies the maximum GPU frequency to be allowed, in MHz. This value is used to disable GPU power states that would exceed this frequency. This control may be used to improve (reduce) power consumption.

0 - (default) No limit is applied.

n - The GPU power states will be restricted to this limit. Power states using a frequency grater than this value will be disabled.
**BLDCFG\_DISPLAY\_MISC\_VBIOS\_FAST\_BOOT\_ENABLE**

This specifies whether the video BIOS software should skip display detection steps in order to reduce boot time.

FALSE - Fast boot is disabled (default).
TRUE - Fast boot is enabled.

### 16.2.9 FCH Elements

**BLDCFG\_SMBUS0\_BASE\_ADDRESS**

This item specifies a customized base I/O address for the processor’s System Management Bus (SMBUS) primary controller. The default is an AMD assigned address.

**BLDCFG\_SMBUS1\_BASE\_ADDRESS**

This item specifies a customized base I/O address for the processor’s System Management Bus (SMBUS) secondary controller. The default is an AMD assigned address.

**BLDCFG\_SIO\_PME\_BASE\_ADDRESS**

This item specifies a customized base I/O address for the System I/O (SIO) controller Power Management Event (PME) block. The default is an AMD assigned address.

**BLDCFG\_ACPI\_PM1\_EVT\_BLOCK\_ADDRESS**

This item specifies a customized base I/O address for the processor’s ACPI PM1 event block. The default is an AMD assigned address.

**BLDCFG\_ACPI\_PM1\_CNT\_BLOCK\_ADDRESS**

This item specifies a customized base I/O address for the processor’s ACPI PM1 control block. The default is an AMD assigned address.

**BLDCFG\_ACPI\_PM\_TMR\_BLOCK\_ADDRESS**

This item specifies a customized base I/O address for the processor’s ACPI Power Management Timer block. The default is an AMD assigned address.

**BLDCFG\_ACPI\_CPU\_CNT\_BLOCK\_ADDRESS**

This item specifies a customized base I/O address for the processor’s ACPI CPU control register block. The default is an AMD assigned address.

**BLDCFG\_ACPI\_GPE0\_BLOCK\_ADDRESS**

This item specifies a customized base I/O address for the processor’s General Purpose Event (GPE) block. The default is an AMD assigned address.
**BLDCFG_WATCHDOG_TIMER_BASE**

This item specifies a customized base address for the processor’s Watch Dog Timer. The default is an AMD assigned address.

**BLDCFG_ACPI_PMA_BLK_ADDRESS**

This item specifies a customized base I/O address for the processor’s ACPI PMA power management controller. The default is an AMD assigned address.

**BLDCFG_SMI_CMD_PORT_ADDRESS**

This item specifies a customized base I/O address for the processor’s SMI command port. The default is an AMD assigned address.

**BLDCFG_ROM_BASE_ADDRESS**

This item specifies a customized base address for the system SPI ROM. The default is an AMD assigned address.

**BLDCFG_GEC_SHADOW_ROM_BASE**

This item specifies a customized base address for the GEC Shadow ROM. The default is an AMD assigned address.

**BLDCFG_HPET_BASE_ADDRESS**

This item specifies a customized base address for the processor’s High Precision Event Timer (HPET). The default is an AMD assigned address.

**BLDCFG_AZALIA_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s Azalia HD audio controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_SMBUS_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s System Management Bus (SMBUS) controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_IDE_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s IDE Controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_SATA_AHCI_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s SATA AHCI controller. The default is an AMD assigned device ID with the AMD vendor ID.
**BLDCFG_SATA_IDE_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s SATA IDE controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_SATA_RAID5_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s SATA RAID 5 Controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_SATA_RAID_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s SATA RAID controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_EHCI_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s EHCI USB controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_OHCI_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s OHCI USB controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_LPC_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s LPC controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_SD_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s Secure Digital (SD) controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_XHCI_SSID**

This item specifies a customized PCIe® Subsystem ID for the processor’s XHCI controller. The default is an AMD assigned device ID with the AMD vendor ID.

**BLDCFG_FCH_PORT80_BEHIND_PCIB**

This item specifies whether port 80 access should be directed to PCIe® or LPC. TRUE - direct port 80 accesses to PCIe®. FALSE - direct port 80 accesses to LPC (default).
**BLDCFG_FCH_ENABLE ACPI_SLEEP_TRAP**

This item specifies whether SMI traps are enabled for ACPI sleep.

TRUE - ACPI sleep SMI traps are enabled (default).
FALSE - ACPI sleep SMI traps are disabled.

**BLDCFG_FCH_GPP_LINK_CONFIG**

This item allows the GPP Link configuration to be specified to match the limits of the board or to balance performance.

0 - Port A has all four lanes (default).
2 - Port A has two lanes and Port B has two lanes.
3 - Port A has two lanes and Ports B and C each have one lane.
4 - All four ports have one lane each.

**BLDCFG_FCH_GPP_PORT0_PRESENT**

This item indicates whether GPP Port 0 is present.

FALSE - The port is not present (default).
TRUE - The port is present.

**BLDCFG_FCH_GPP_PORT1_PRESENT**

This item indicates whether GPP Port 1 is present.

FALSE - The port is not present (default).
TRUE - The port is present.

**BLDCFG_FCH_GPP_PORT2_PRESENT**

This item indicates whether GPP Port 2 is present.

FALSE - The port is not present (default).
TRUE - The port is present.

**BLDCFG_FCH_GPP_PORT3_PRESENT**

This item indicates whether GPP Port 3 is present.

FALSE - The port is not present (default).
TRUE - The port is present.

**BLDCFG_FCH_GPP_PORT0_HOTPLUG**

This item indicates whether GPP Port 0 supports hotplug.

FALSE - Hotplug is not supported by the port (default).
TRUE - Hotplug is supported by the port.

**BLDCFG_FCH_GPP_PORT1_HOTPLUG**

This item indicates whether GPP Port 1 supports hotplug.

FALSE - Hotplug is not supported by the port (default).
TRUE - Hotplug is supported by the port.

`BLDCFG_FCH_GPP_PORT2_HOTPLUG`

This item indicates whether GPP Port 2 supports hotplug.
FALSE - Hotplug is not supported by the port (default).
TRUE - Hotplug is supported by the port.

`BLDCFG_FCH_GPP_PORT3_HOTPLUG`

This item indicates whether GPP Port 3 supports hotplug.
FALSE - Hotplug is not supported by the port (default).
TRUE - Hotplug is supported by the port.
16.3 Customizing the Environment — Library Functions

These procedures interface the application software with the hardware. Most of these procedures provide access to processor instructions not available in the standard C language. These procedures are documented for the expert user who needs to modify the underpinnings of the software for their platform configuration. This is useful when porting the software to new software code bases.

Procedures are listed in alphabetical order.

**WARNING:** Only the published entry points are assured to be available over time. Use of other procedure names by the host environment that were found by code inspection is strongly discouraged. AMD reserves the right to modify or remove internal procedure names not published in this specification.

**Common Parameters**

All of the environment library functions accept the following parameter:

```
StdHeader
```

Pointer to a StdHeader. This structure was defined in “Standard Header” on page 33 and contains host environment data that the library function can use in performing its function.

Similarly, many library functions use the operation width-definition type:

```
typedef enum ACCESS_WIDTH {
    AccessWidth8 = 1,
    AccessWidth16,
    AccessWidth32,
    AccessWidth64,
} ACCESS_WIDTH;
```

The complete definition can be found in the AGESA.H include file.
LibAmdCpuidRead

Perform the CPUID instruction and return the response.

Note: This procedure only applies to the x86-64 architecture APUs.

Prototype

VOID LibAmdCpuidRead (  
    IN UINT32 CpuidFcnAddress,  
    OUT CPUID_DATA *Value,  
    IN OUT AMD_CONFIG_PARAMS *StdHeader  
);

Parameters

CpuidFcnAddress

Parameter to the CPUID instruction passed in EAX.

Value

Pointer to location where to place the instruction response.

Related Definitions

typedef struct {  
    OUT UINT32  EAX_Reg;  
    OUT UINT32  EBX_Reg;  
    OUT UINT32  ECX_Reg;  
    OUT UINT32  EDX_Reg;  
} CPUID_DATA;

Description

This library function executes the processor CPUID instruction and stores the response values into the provided data structure.
LibAmdIoRead
LibAmdIoWrite

Perform an Input/Output cycle using the IN or OUT processor instruction.

Prototype

VOID LibAmdIoRead (  
    IN     ACCESS_WIDTH           AccessWidth,  
    IN     UINT16                IoAddress,  
    OUT    VOID                  *Value,  
    IN OUT AMD_CONFIG_PARAMS     *StdHeader 
);  

VOID LibAmdIoWrite (  
    IN     ACCESS_WIDTH           AccessWidth,  
    IN     UINT16                IoAddress,  
    IN     VOID                  *Value,  
    IN OUT AMD_CONFIG_PARAMS     *StdHeader 
);  

Parameters

AccessWidth

Indicates the data size of the operation.

IoAddress

Address in the IO address space to which the operation pertains.

Value

Pointer to location where to obtain (Write) or place (Read) the instruction data value.

Description

Performs the IO cycle of the specified size to the indicated IO space address.
LibAmdLocateImage

Find the binary image containing a module with the specified signature.

Prototype

VOID *LibAmdLocateImage (  
  IN VOID *StartAddress,  
  IN VOID *EndAddress,  
  IN UINT32 Alignment,  
  IN CHAR8 ModuleSignature[8]  
);

Parameters

  StartAddress
  Pointer to location where to start the search.

  EndAddress
  Pointer to location where to end the search.

  Alignment
  Specifies how big a step to take when searching. If this value is zero, then a default value of 4096 bytes is used.

  ModuleSignature
  Pointer to an 8-character string that matches the module identifier.

Description

This procedure searches from StartAddress to EndAddress incrementing, or stepping, by Alignment bytes to locate a code module with the identifier that matches the ModuleSignature parameter.

Returned Value

The functions return value is a pointer to the binary image containing the module. If the return value is NULL, then a module with the specified signature could not be located.
LibAmdMemCopy
LibAmdMemFill

Move or fill a block of memory.

Prototype

VOID LibAmdMemCopy (  
    IN VOID *Destination,  
    IN VOID *Source,  
    IN UINTN CopyLength,  
    IN OUT AMD_CONFIG_PARAMS *StdHeader  
);  

VOID LibAmdMemFill (  
    IN VOID *Destination,  
    IN UINT8 Value,  
    IN UINTN FillLength,  
    IN OUT AMD_CONFIG_PARAMS *StdHeader  
);  

Parameters

Source
    Pointer to the memory location where to find the data.

Destination
    Pointer to the memory location where to place the data.

CopyLength

FillLength
    Length in bytes of the memory area to be copied or filled.

Value
    Value with which to fill the memory area.

Description

The MemCopy procedure copies data from one memory location to another. The data is copied from low address to high address. Overlapping source and destination areas must have the destination area begin at least 4 bytes higher than the originating area.

The MemFill procedure fills the memory area with the value provided.
LibAmdMemRead
LibAmdMemWrite

Access a memory location above the 4-Gbyte address range.

Prototype

VOID LibAmdMemRead (  
    IN ACCESS_WIDTH AccessWidth,  
    IN UINT64 MemAddress,  
    OUT VOID *Value,  
    IN OUT AMD_CONFIG_PARAMS *StdHeader
);

VOID LibAmdMemWrite (  
    IN ACCESS_WIDTH AccessWidth,  
    IN UINT64 MemAddress,  
    IN VOID *Value,  
    IN OUT AMD_CONFIG_PARAMS *StdHeader
);

Parameters

AccessWidth
Indicates the data size of the operation.

MemAddress
Address where to perform the operation.

Value
Pointer to location where to obtain (Write) or place (Read) the operation data value.

Description

These procedures use a special access mechanism of the AMD processor to read or write a value to a memory location above the 4-Gbyte address boundary — an address needing more than 32 bits to represent, thus a standard C language pointer could not access. The calling procedure is responsible to assure that the data location is of the proper size or type to contain the data.
LibAmdMsrRead

LibAmdMsrWrite

Perform an RDMSR or WRMSR processor instruction and return the response.

Note: This procedure only applies to the x86-64 architecture APUs.

Prototype

VOID LibAmdMsrRead (  
    IN UINT32 MsrAddress,  
    OUT UINT64 *Value,  
    IN OUT AMD_CONFIG_PARAMS *StdHeader 
);  

VOID LibAmdMsrWrite (  
    IN UINT32 MsrAddress,  
    IN UINT64 *Value,  
    IN OUT AMD_CONFIG_PARAMS *StdHeader 
);  

Parameters

MsrAddress

MSR register number or address where to perform the operation.

Value

Pointer to location where to obtain (Write) or place (Read) the operation data value.

Description

These library functions execute the processor RDMSR or WRMSR instruction. The MsrRead procedure accesses the MSR register and stores the contents into the provided data location. The MsrWrite sets the contents of the MSR to the value in the provided data location.
LibAmdPciRead  
LibAmdPciWrite

Generate a PCI configuration cycle to access a PCI device register.

Prototype

VOID LibAmdPciRead (  
    IN ACCESS_WIDTH AccessWidth,  
    IN PCI_ADDR PciAddress,  
    OUT VOID *Value,  
    IN OUT AMD_CONFIG_PARAMS *StdHeader
);

VOID LibAmdPciWrite (  
    IN ACCESS_WIDTH AccessWidth,  
    IN PCI_ADDR PciAddress,  
    IN VOID *Value,  
    IN OUT AMD_CONFIG_PARAMS *StdHeader
);

Parameters

AccessWidth

Indicates the data size of the operation.

PciAddress

The PCI device register address where to perform the operation.

Value

Pointer to location where to obtain (Write) or place (Read) the operation data value.

Related Definitions

typedef struct {
    IN OUT UINT32 Register:12;
    IN OUT UINT32 Function:3;
    IN OUT UINT32 Device:5;
    IN OUT UINT32 Bus:8;
    IN OUT UINT32 Segment:4;
} EXT_PCI_ADDR;

Description

These procedures use the bit field PCI register address to locate the target register and then perform a PCI configuration access cycle to read or write the target register. If the PcieBasePtr element of the StdHeader is filled with a proper pointer (not = NULL) to a memory-mapped
IO region, then the access is performed through the MMIO base, else the access is performed using the PCI configuration IO ports.
Section V - Integrated Debug Services (IDS)

Chapter 17  IDS Overview

The Integrated Debug Services (IDS) of the AGESA™ software bring several abilities to the host environment and the platform developer that enhance the ability to alter code actions and give flexibility of choice to the platform developer. As indicated by the name, this sub-system is intended for use in debugging a platform in preparing it for production delivery.

The intent is for these controls to be removed for the production build.

17.1  Goals

The IDS sub-system is intended to aid platform debugging and, optionally, provide a mechanism to import end-user choices into the operations of the platform. The goals of this sub-system are:

• Provide Controls structure to allow flexibility in defining the platform feature set operation
• Create a common feature control set across all platforms
• Be closely integrated with the AGESA™ software, providing a consistent interface over time
• Define a common data definition for interfacing to the host environment
• Implement entirely in the C language
• Optional inclusion—because these controls are not intended for the production build, the controls that are not included in the build implementation have a Zero code-size impact.

17.2  Capabilities

The IDS sub-system provides services in three broad categories:

Configuration Controls - The IDS controls allow a porting engineer to make run time decisions which affect configuration settings in the system. These controls typically select an alternative value for a configuration register bitfield for the purposes of testing the hardware platform during the ‘bring-up’ phase. This is the period a platform manufacturer is readying the platform for production.

Trace services - The IDS sub-system provides several tools to trace the progression of certain algorithms in the AGESA™ software. These tools can give insight to the platform engineer about what is happening on the platform.
**Performance Analysis** - The IDS sub-system has the capability to collect time stamp data at certain points in the code. This data can then be analyzed to show what sections of code are taking more time than others.

### 17.3 Host Environment

The Integrated Debug Services rely upon having access to run time decisions made by the platform developer. The results of these decisions are recorded in non-volatile storage within the platform.

Figure 17.2 gives an overview of the host environment and the interaction with the IDS. The figure shows two distinct sections:

The **front end UI** - This is the user interface (UI) that enables the platform developer make decisions and stores information about those decisions in non-volatile storage (NV). This code and services exist in and are provided by the host environment. For example, the SETUP utility. Each BIOS vendor supplies a version of SETUP. (The UEFI environment uses a standard UI tool. For the UEFI environment AMD supplies code components to insert into the standard UI tool, which provides the user selection ability for the IDS control fields defined in this specification.)

The **back end code** - This is the code embedded into the AGESA™ software. This code invokes actions based upon the decisions made by the platform developer.

The communication method between these two sections is based on an “IDS element ID.” Each piece of data used by the IDS is identified by a unique ID value, the ‘element ID’. The element ID names are defined in the include file AGESA.h.
The back-end code uses the call-out “AgesaGetIdsData” on page 168 to obtain values for the IDS elements.

### 17.4 Installation and Configuration

Because the IDS is intended for advanced to expert users for the purpose of debugging a platform for production delivery, the reader and user of these features are assumed to have an advanced to expert level of programming ability.

The IDS sub-system uses several build switches to allow the platform developer to specify how many and which IDS controls are enabled in the back-end code. They allow the platform developer to control the trade-off between flexibility, code size, and boot time.
The IDS build switches are defined in a special file named OptionsIds.h located in the platform build tip directory. An example version of this file is available in 20.2 “Example” on page 257. The platform developer may copy this example to the platform build tip directory and make changes to enable the IDS support desired.

The build switches which are available are defined along with the configuration controls they affect in “IDS Build Switches” on page 249.
Chapter 18  IDS Macros

Throughout the core files there are macros which import debug services. These are the Integrated Debug Services (IDS) macros further defined in “IDS Configuration Controls” on page 249. Expansion of all IDS macros is controlled by #define compile switches defined for the platform. When disabled, the macros are not expanded during compile and consume no code space.

These macros are used to establish execution hooks in the AGESA™ software so that the special services can be invoked.
AGESA_TESTPOINT

Prototype

AGESA_TESTPOINT(TestPoint)

Parameters

TestPoint

The value for display indicating progress

Description

This Macro is always enabled. The default action is to write the TestPoint value to an I/O port. The I/O port is 8 bits in size and the default address is 0x80. IDS_DEBUG_PORT may be defined to another value to use a different address. Example:

#define IDS_DEBUG_PORT 0x84
STOP_HERE

Prototype

STOP_HERE(VOID)

Parameters

<none>

Description

This macro is always enabled. The default action is to generate a compiler error.

This macro forces a program halt to allow a debugger tool to gain control and investigate the platform. This macro should NOT remain in the code after the debug session is complete, thus the default action is to generate a compiler error to flag the developer to remove the macro.

Dependencies

If IDSOPT_ASSERT_ENABLED is TRUE, then this macro causes the program to halt with stop code display (see “Debugging Using IDS” on page 258).
**ASSERT**

**Prototype**

```c
ASSERT(*expression*)
```

**Parameters**

`*expression*`

This is an expression that must evaluate to a BOOLEAN value.

**Description**

This macro makes the assertion that *expression* is TRUE. This is used to do parameter checks, bounds checking, range checks, and “sanity” checks.

**Dependencies**

If IDSOPT_ASSERT_ENABLED is TRUE, then this macro evaluates the *expression* to a BOOLEAN value. If the *expression* is true, then no action is taken (no error). If the *expression* is False, an error stop is generated to halt the program with stop code display (see “Debugging Using IDS” on page 258). Use this to check for software errors that must be resolved before production.
IDS_ERROR_TRAP

Prototype

IDS_ERROR_TRAP;

Parameters

There are no parameters to IDS_ERROR_TRAP.

Description

This macro works similarly to a use of “ASSERT (FALSE);”. This is used to provide debug support for severe errors, including those potentially caused by wrapper and platform BIOS errors. These severe errors are normally reported to the host environment via an AGESA return status. This macro can be enabled to debug the cause closer to the source of the error. The macro is used for cases that return AGESA_ERROR, AGESA_CRITICAL, and AGESA_FATAL.

Dependencies

If IDSOPT_ERROR_TRAP_ENABLED is TRUE, then this macro generates an error stop to halt the program with stop code display (see “Debugging Using IDS” on page 258).
IDS_OPTION_HOOK

Prototype

IDS_OPTION_HOOK(IdsOption, DataPtr, StdHeader);

Parameters

IdsOption

IDS Option index to select the function to perform at this hook point.

DataPtr

Pointer to data relevant to the hook point. This may contain values the hook point procedure overrides.

StdHeader

Pointer to the standard header.

Description

Invoke the specified IDS option hook procedure. These hook procedures may perform actions to modify an algorithm or make changes to an entry point’s input parameters or modify specific register values. In general, an option hook adds code to the code seen in the source file.

Dependencies

If IDSOPT_IDS_ENABLED is TRUE, then this macro calls the specified IDS hook procedure, passing the DataPtr and StdHeader as parameters.
IDS_SKIP_HOOK

Prototype:

IDS_SKIP_HOOK(IdsOption, DataPtr, StdHeader) {
    // skipable code
};

Parameters

IdsOption
IDS Option index to select the function to perform at this hook point. This function returns a boolean value.

DataPtr
Pointer to data relevant to the hook point. This may contain values the hook point procedure overrides.

StdHeader
Pointer to the standard header.

Description

Invoke the specified IDS skip hook procedure. In general, a skip hook removes code from execution from what is seen in the source file. The IdsOption function returns a boolean. The macro evaluates the boolean and if it is FALSE, it skips the code inside the curly braces. If the boolean is TRUE then the code inside the curly braces is executed.

These hook procedures may also perform actions to modify an algorithm or make changes to an entry point’s input parameters or modify specific register values. Another potential use is to replace the main code inside the curly braces with an alternate debug version.

Dependencies

If IDSOPT_IDS_ENABLED is TRUE, then this macro calls the specified IDS hook procedure, passing the DataPtr and StdHeader as parameters. If IDSOPT_IDS_ENABLED is FALSE, then the macro is not expanded and the code inside the curly braces is always executed.
IDS_HDT_CONSOLE

Prototype:

IDS_HDT_CONSOLE(Group, FormatString, <VarArgs...>)

Parameters

Group

Specifies which group this debug output belongs to, so that it can be filtered by the HDT script.

FormatString

Text string to be displayed with an HDT script. This string uses classic ‘printf’ format to display the arguments that comes after it.

VarArgs

List of arguments that will be formatted and displayed along with FormatString.

Description

This macro invokes communications with the HDT to allow users to pipe out trace data from BIOS. The protocol of this communication is described in the IDS Doxygen internal documentation. Users can write their own HDT console script to extract data or use the AGESA™ provided scripts supplied in the AMDTools sub-directory.

Dependencies

Ensure $(AGESA_OptsDir)/OptionsIds.h exists and contains these two definitions:

IDSOPT_IDS_ENABLED must be TRUE.

IDSOPT_TRACING_ENABLED must be TRUE.

See “HDT Console” on page 260 for additional setup and use information.
CONSOLE

Prototype:

CONSOLE(FormatString, <VarArgs...>)

Parameters

FormatString

Text string to be displayed with an HDT script. This string uses classic ‘printf’ format to display the arguments that comes after it.

VarArgs

List of arguments that will be formatted and displayed along with FormatString.

Description

This macro is always enabled. The default action is to generate a compiler error.

This macro invokes communications with the HDT to allow users to pipe out trace data from BIOS. The protocol of this communication is described in the IDS Doxygen internal documentation. Users can write their own HDT console script to extract data or use the AGESA™ provided scripts supplied in the AMDTools sub-directory. This macro should NOT remain in the code after the debug session is complete, thus the default action is to generate a compiler error to flag the developer to remove the macro.

Dependencies

Ensure $(AGESA_OptsDir)/OptionsIds.h exists and contains these two definitions:

IDSOPT_IDS_ENABLED must be TRUE.

IDSOPT_TRACING_ENABLED must be TRUE.

See “HDT Console” on page 260 for additional setup and use information.
IDS_HDT_CONSOLE_INIT

Prototype:

IDS_HDT_CONSOLE_INIT(AMD_CONFIG_PARAMS *StdHeader)

Parameters

StdHeader

Pointer to a standard header structure.

Description

This macro is used to initiate communications with the HDT console script.

Dependencies

IDSOPT_IDS_ENABLED must be TRUE.
IDSOPT_TRACING_ENABLED must be TRUE.

See “HDT Console” on page 260 for additional setup and use information.
**IDS_HDT_CONSOLE_EXIT**

**Prototype:**

```c
IDS_HDTOUT_EXIT(AMD_CONFIG_PARAMS *StdHeader)
```

**Parameters**

*StdHeader*

Pointer to a standard header structure.

**Description**

This macro closes the communication session with the HDT script.

**Dependencies**

IDSOPT_IDS_ENABLED must be TRUE.

IDSOPT_TRACING_ENABLED must be TRUE.

See “HDT Console” on page 260 for additional setup and use information.
IDS_PERF_TIMESTAMP

Prototype:

`IDS_PERF_TIMESTAMP(AMD_CONFIG_PARAMS *StdHeader, UINT32 TestPoint)`

Parameters

- `StdHeader`
  
  Pointer to a standard header structure.

- `TestPoint`
  
  The AGESA software test point value for which to record this time stamp.

Description

This macro records the time stamp counter for use later to analyze boot times.

Dependencies

- `IDSOPT_IDS_ENABLED` must be TRUE.
- `IDSOPT_PERF_ANALYSIS` must be TRUE.
IDS_PERF_ANALYSE

Prototype:

IDS_PERF_ANALYSE(AMD_CONFIG_PARAMS *StdHeader)

Parameters

StdHeader

Pointer to a standard header structure.

Description

This macro transfers the time stamp data to the HDT script for analysis.

Dependencies

IDSOPT_IDS_ENABLED must be TRUE.
IDSOPT_PERF_ANALYSIS must be TRUE.
IDS_EXCEPTION_TRAP

Prototype:

IDS_EXCEPTION_TRAP(FunctionId, DataPtr, StdHeader)

Parameters

FunctionId

Designates the action to be taken.

- IDS_IDT_REPLACE_IDTR_FOR_BSC - Create an IDT for the boot core, saving any IDT currently in use.
- IDS_IDT_RESTORE_IDTR_FOR_BSC - Restore any IDT that was previously in use for the boot core.
- IDS_IDT_UPDATE_EXCEPTION VECTOR FOR AP - Update the exception vectors.

DataPtr

Provide data relevant to the desired action. For updating vectors, provide the base address of the IDT.

StdHeader

Pointer to a standard header structure.

Description

This macro installs an IDT for catching exceptions. All the exception handlers are set to a spin loop routine. During debug, this prevents faults or resets and allows analysis of why the exception occurred.

Dependencies

Ensure $(AGESA_OptsDir)\OptionsIds.h exists and contains these two definitions:

IDSOPT_IDS_ENABLED must be TRUE.
IDSOPT_IDT_EXCEPTION_TRAP must be TRUE.
Chapter 19  IDS Configuration Controls

19.1  IDS Build Switches

The IDS enable switches are layered and grouped to allow fine tuning of the enabled pieces.

The defined IDS build switches are listed below. Each option switch is a BOOLEAN, so can be set to either TRUE or FALSE. The default setting is FALSE.

- **IDSOPT_IDS_ENABLED**
  This is the master switch for the IDS sub-system. Use this option to enable or remove the entire IDS feature set. This switch must be TRUE for any of the other options to function.

- **IDSOPT_ASSERT_ENABLED**
  This is the switch for halting support for debugging. If the switch is TRUE ASSERT macros will be enabled. Also temporary use of STOP_HERE is enabled when this switch is TRUE.

- **IDSOPT_ERROR_TRAP_ENABLED**
  This switch enables additional debug halting associated with detected severe events.

- **IDSOPT_CONTROL_ENABLED**
  This is the main switch for the IDS configuration controls. This switch must be TRUE for any of the configuration controls to function.

- **IDSOPT_HEAP_CHECKING**
  When set to TRUE this switch enables internal checking of heap consistency, checking for issues such as buffer overrun.

- **IDSOPT_TRACING_ENABLED**
  This is the main switch for the IDS console controls, macros and support code needed to enable tracing of algorithms. This switch must be TRUE for any of the tracing features to function.

- **IDSOPT_TRACE_USER_OPTIONS**
  This switch enables reporting of the user options on the console. IDSOPT_TRACING_ENABLED must be TRUE for this switch to have any effect. Code size increases due to enabling tracing can be reduced by setting this switch to FALSE.
IDSOPT_IDT_EXCEPTION_TRAP

When set to TRUE, this switch enables use of IDS_EXCEPTION_TRAP to debug exceptions.

IDSOPT_PERF_ANALYSIS

This is the main switch for the IDS performance analysis controls, macros and support code needed to enable time data gathering. This switch must be TRUE for any of the performance analysis features to function.

19.2 UI Interface Controls

The controls in this section are enabled by the IDSOPT_CONTROL_ENABLED build option switch. These User Interface (UI) controls allow the Platform developer to adjust a limited set configuration registers or enable diagnostic tools for the purpose of debugging their platform hardware. These controls are intended for use in the platform ‘bring-up’ and debug phase of preparing the platform for production release. The IDS sub-system must be disabled for the production release.

The IDS configuration controls exist because the affected settings are not exposed through the defined program interfaces. The affected settings will be platform constants or automatically determined by the AGESA™ software in the production release.

The following sections describe the user selection controls that are provided and the selection option values available for those controls. These will appear in the following format:

AGESA_IDS_NV_CONTROL_NAME (This is the identifier name defined in the IDS.H file)
This control does this.... (this is the description of the control)

IDS_SELECTION Value description. (Each valid selection is listed by the identifier name defined in the IDS.H file.)

IDS_SELECTION Value description.

Please note that when activated, the IDS control overrides any corresponding build configuration option that may affect the same setting. There are no default values, the value returned from the IDS user interface will be the value used. It is the responsibility of the host environment user interface to provide any user default settings and assure the final selection value is proper for the control field.

19.2.1 Configuration Controls

19.2.1.1 Processor Core Controls

AGESA_IDS_NV_UCODE

This control provides the ability to control whether the microcode patch will be loaded. This control will be evaluated at the entry point AmdInitReset and will override the default action of loading microcode patches.
IDS_DISABLED  Disable the microcode patching. No patch will be loaded even if one is present that matches the processor.

IDS_ENABLED  Enable the microcode patching. Normal patch loading action per the BKDG.

**AGESA_IDS_NV_TARGET_PSTATE**

This control provides the ability to specify the P-state at which entry to OS will occur. This control will be evaluated at the entry point AmdInitLate. This control may be useful for an OS that does not support ACPI.

IDS_TARGETPSTATE_AUTO  Automatic. No override is performed. The PState is determined by BIOS based on the installed processors’ capabilities.

IDS_TARGETPSTATE_HIGHEST  set the target PState to highest

IDS_TARGETPSTATE_LOWEST  set the target PState to Lowest

IDS_TARGETPSTATE_0  set the target PState to state 0 if supported

IDS_TARGETPSTATE_1  set the target PState to state 1 if supported

IDS_TARGETPSTATE_2  set the target PState to state 2 if supported

IDS_TARGETPSTATE_3  set the target PState to state 3 if supported

IDS_TARGETPSTATE_4  set the target PState to state 4 if supported

IDS_TARGETPSTATE_5  set the target PState to state 5 if supported

IDS_TARGETPSTATE_6  set the target PState to state 6 if supported

IDS_TARGETPSTATE_7  set the target PState to state 7 if supported

**AGESA_IDS_NV_POSTPSTATE**

This control provides the ability to override the P-state entered before memory initialization during BIOS post. This control will be evaluated at the entry point AmdInitEarly.

IDS_POSTPSTATE_AUTO  Automatic base on BIOS execution

IDS_POSTPSTATE_HIGHEST  set the post PState to highest

IDS_POSTPSTATE_LOWEST  set the post PState to Lowest

IDS_POSTPSTATE_0  set the post PState to state 0 if supported

IDS_POSTPSTATE_1  set the post PState to state 1 if supported

IDS_POSTPSTATE_2  set the post PState to state 2 if supported

IDS_POSTPSTATE_3  set the post PState to state 3 if supported

IDS_POSTPSTATE_4  set the post PState to state 4 if supported

IDS_POSTPSTATE_5  set the post PState to state 5 if supported

IDS_POSTPSTATE_6  set the post PState to state 6 if supported

IDS_POSTPSTATE_7  set the post PState to state 7 if supported

Note that if the desired P-State number is numerically greater than the lowest performance P-State, the core is set to the lowest performance P-State.

**AGESA_IDS_NV_POWER_POLICY**
This control provides the ability to override settings which provide a trade off of power savings or performance. See the internal documentation, described in “Internal Documentation” on page 26, for details on what settings are affected by this control.

IDS_POWER_POLICY_AUTO Policy is set according to configuration.
IDS_POWER_POLICY_POWER Policy is forced to maximize battery life.
IDS_POWER_POLICY_PERFORMANCE Policy is forced to maximize performance.

19.2.1.2 Memory Cache & ECC Controls

AGESA_IDS_NV_SCRUB_REDIRECTION

This control provides the ability to override build parameters used by the memory routines. This control will be evaluated at the entry point AmdInitPost, and used as the value for the CfgEccRedirection parameter.

IDS_DISABLED Disable this feature.
IDS_ENABLED Enable the northbridge to force a write to dram with corrected data when a correctable error on the dram bus is detected during a normal CPU or bus master read request.

See Build configuration item “BLDCFG_ECC_REDIRECTION” on page 200.

AGESA_IDS_NV_DRAM_SCRUB

This control provides the ability to override build parameters used by the memory routines. This control will be evaluated at the entry point AmdInitPost, and used as value of the CfgScrubDramRate parameter. Below are the options used to set the rate of background scrubbing for DRAM.

IDS_DRAMSCRUB_DISABLED IDS_DRAMSCRUB_20_0NS
IDS_DRAMSCRUB_40NS IDS_DRAMSCRUB_80NS
IDS_DRAMSCRUB_160NS IDS_DRAMSCRUB_320NS
IDS_DRAMSCRUB_640NS IDS_DRAMSCRUB_1_28US
IDS_DRAMSCRUB_2_56US IDS_DRAMSCRUB_5_12US
IDS_DRAMSCRUB_10_2US IDS_DRAMSCRUB_20_5US
IDS_DRAMSCRUB_41_0US IDS_DRAMSCRUB_81_9US
IDS_DRAMSCRUB_163_8US IDS_DRAMSCRUB_327_7US
IDS_DRAMSCRUB_655_4US IDS_DRAMSCRUB_1_31MS
IDS_DRAMSCRUB_2_62MS IDS_DRAMSCRUB_5_24MS
IDS_DRAMSCRUB_10_49MS IDS_DRAMSCRUB_20_97MS
IDS_DRAMSCRUB_42_0MS IDS_DRAMSCRUB_84_0MS

See Build configuration item “BLDCFG_SCRUB_DRAM_RATE” on page 206.
**AGESA_IDS_NV_DCACHE_SCRUB**

This control provides the ability to override build parameters used by the memory routines. This control will be evaluated at the entry point AmdInitPost, and used as the value for the CfgScrubDcRate parameter. This option is used to set the rate of background scrubbing for the DCache.

- **IDS_DCACHESCRUB_DISABLED**
- **IDS_DCACHESCRUB_40NS**
- **IDS_DCACHESCRUB_80NS**
- **IDS_DCACHESCRUB_160NS**
- **IDS_DCACHESCRUB_320NS**
- **IDS_DCACHESCRUB_640NS**
- **IDS_DCACHESCRUB_1_28US**
- **IDS_DCACHESCRUB_2_56US**
- **IDS_DCACHESCRUB_5_12US**
- **IDS_DCACHESCRUB_10_2US**
- **IDS_DCACHESCRUB_20_5US**
- **IDS_DCACHESCRUB_41_0US**
- **IDS_DCACHESCRUB_81_9US**
- **IDS_DCACHESCRUB_163_8US**
- **IDS_DCACHESCRUB_327_7US**
- **IDS_DCACHESCRUB_655_4US**
- **IDS_DCACHESCRUB_1_31MS**
- **IDS_DCACHESCRUB_2_62MS**
- **IDS_DCACHESCRUB_5_24MS**
- **IDS_DCACHESCRUB_10_49MS**
- **IDS_DCACHESCRUB_20_97MS**
- **IDS_DCACHESCRUB_42_0MS**
- **IDS_DCACHESCRUB_84_0MS**

See Build configuration item “BLDCFG_SCRUB_DC_RATE” on page 207.

**AGESA_IDS_NV_L2_SCRUB**

This control provides the ability to override build parameters used by the memory routines. This control will be evaluated at the entry point AmdInitPost, and used as the value for the CfgScrubL2Rate parameter. This option is used to set the rate of background scrubbing for the L2 cache.

- **IDS_L2SCRUB_DISABLED**
- **IDS_L2SCRUB_40NS**
- **IDS_L2SCRUB_80NS**
- **IDS_L2SCRUB_160NS**
- **IDS_L2SCRUB_320NS**
- **IDS_L2SCRUB_640NS**
- **IDS_L2SCRUB_1_28US**
- **IDS_L2SCRUB_2_56US**
- **IDS_L2SCRUB_5_12US**
- **IDS_L2SCRUB_10_2US**
- **IDS_L2SCRUB_20_5US**
- **IDS_L2SCRUB_41_0US**
- **IDS_L2SCRUB_81_9US**
- **IDS_L2SCRUB_163_8US**
- **IDS_L2SCRUB_327_7US**
- **IDS_L2SCRUB_655_4US**
- **IDS_L2SCRUB_1_31MS**
- **IDS_L2SCRUB_2_62MS**
- **IDS_L2SCRUB_5_24MS**
- **IDS_L2SCRUB_10_49MS**
- **IDS_L2SCRUB_20_97MS**
- **IDS_L2SCRUB_42_0MS**
- **IDS_L2SCRUB_84_0MS**

See Build configuration item “BLDCFG_SCRUB_L2_RATE” on page 207.

**AGESA_IDS_NV_L3_SCRUB**

This control provides the ability to override build parameters used by the memory routines. This control will evaluate before entry point AmdInitPost, and used as default value of CfgScrubL3Rate parameter.

May not be available on all families.
AGESA™--Arch2008

See Build configuration item “BLDCFG_SCRUB_L3_RATE” on page 207.

**AGESA_IDS_NV_ICACHE_SCRUB**

This control provides the ability to override build parameters used by the memory routines. This control will be evaluated at the entry point AmdInitPost, and used as the value for the CfgScrubICRate parameter.

See Build configuration item “BLDCFG_SCRUB_IC_RATE” on page 207.

**AGESA_IDS_NV_SYNC_ON_ECC_ERROR**

This control provides the ability to override ECC_OVERRIDE_STRUCT structure which is used by MemFInitECC routine. This control will evaluate before entry point AmdInitPost, and used as default value of CfgEccSyncFlood parameter.

| IDS.Disabled | Disable this feature. |
| IDS.Enabled | Enables flooding of all links with sync packets on detection of an uncorrectable ECC error. |

See Build configuration item “BLDCFG_ECC_REDIRECTION” on page 200.

**AGESA_IDS_NV_ECC_SYMBOL_SIZE**

This control provides the ability to override local variable "size" used by memory routines. This control will be evaluated at the entry point AmdInitPost.

| IDS.ECCSYMBOLSIZE_X4 | x4 symbol size and code used |
| IDS.ECCSYMBOLSIZE_X8 | x8 symbol size and code used |

See Build configuration item “BLDCFG_ECC_SYMBOL_SIZE” on page 208.

**AGESA_IDS_NV_DRAM_BURST_LENGTH32**

This specifies the burst length of DRAM accesses and, as a result, the number of data bytes exchanged in each access.

| IDS.DRAMBURSTLENGTH32_64BYTE | 64 byte mode |
| IDS.DRAMBURSTLENGTH32_32BYTE | 32 byte mode |
| IDS.DRAMBURSTLENGTH32_AUTO | Disable any override. Do no user selection and let the BIOS perform its normal functions. |

See Build configuration item “BLDCFG_USE_BURST_MODE” on page 206.

**AGESA_IDS_NV_ALL_MEMCLKS**

This control provides the ability to override local variable "MemoryAllClocks" used by the memory routines. This control will be evaluated at the entry point AmdInitPost.

| IDS.Disabled | Disable this feature |
| IDS.Enabled | Enables this feature |
See Build configuration item “BLDCFG_MEMORY_ALL_CLOCKS_ON” on page 199.

AGESA_IDS_NV_MEMORY_POWER_DOWN_MODE

- IDS_PWRDNMODE_CHANNEL Channel CKE control mode.
- IDS_PWRDNMODE_CS Chip select CKE control mode.
- IDS_PWRDNMODE_AUTO Disable any override. Do no user selection and let the BIOS perform its normal functions.

See Build configuration item “BLDCFG_MEMORY_POWER_DOWN” on page 204.

19.2.2 HDT Tracing controls

The controls in this section are enabled by the IDSOPT_TRACING_ENABLED build option switch.

The support code for the control is added to the build when the corresponding build option switches are set for TRUE. In addition, many debug features also have a run-time control to activate the feature.

During the bring-up and debug test period for a platform, the platform developer will want to have the HDT debug services available and built into the executable image, but not necessarily always active, since that would cause extra time in the boot sequence. The following IDS controls are provided to allow the platform developer to select which sections of HDT analysis code are active for the boot sequence.

AGESA_IDS_NV_HDTOUT

This is an IDS control through which the platform developer can turn the tracing capability on or off. The value of this control is boolean and must be TRUE for the tracing macro function to be executed.

19.2.3 Performance Analysis Controls

The controls in this section are enabled by the IDSOPT_PERF_ANALYSIS build option switch.

19.3 Build Switch Hierarchy

This section shows the relationship of the build switches to the macros and controls they enable.
ASSERT

IDS_ERROR_TRAP_ENABLED
  IDS_ERROR_TRAP
IDS_OPTION_HOOK
IDS_SKIP_HOOK

IDSOPT_CONTROL_ENABLED
  AGESA_IDS_NV_UCODE
  AGESA_IDS_NV_TARGET_PSTATE
  AGESA_IDS_NV_POSTPSTATE
  AGESA_IDS_NV_CORE_LEVEL
  AGESA_IDS_NV_SCRUB_REDIRICATION
  AGESA_IDS_NV_DRAM_SCRUB
  AGESA_IDS_NV_DCACHE_SCRUB
  AGESA_IDS_NV_L2_SCRUB
  AGESA_IDS_NV_L3_SCRUB
  AGESA_IDS_NV_ICACHE_SCRUB
  AGESA_IDS_NV_SYNC_ON_ECC_ERROR
  AGESA_IDS_NV_ECC_SYMBOL_SIZE
  AGESA_IDS_NV_DRAM_BURST_LENGTH32
  AGESA_IDS_NV_ALL_MEMCLKS
  AGESA_IDS_NV_MEMORY_POWER_DOWN_MODE

IDSOPT_TRACING_ENABLED
  IDS_HDT_CONSOLE
  IDS_HDT_CONSOLE_INIT
  IDS_HDT_CONSOLE_EXIT
  CONSOLE

  IDSOPT_TRACE_USER_OPTIONS

IDSOPT_PERF_ANALYSIS
  IDS_HDT_CONSOLE
  IDS_PERF_TIMESTAMP
  IDS_PERF_ANALYSE

IDSOPT_HEAP_CHECKING
  Heap_Check()

IDSOPT_IDT_EXCEPTION_TRAP
  IDS_EXCEPTION_TRAP
Chapter 20  IDS Porting

The OptionsIds.h file is the file that controls which of the Integrated Debug Services will be included into the build. This file must be located in the build tip directory, the same location as the <plat>Options.c file. If the OptionsIds.h file does not exist in that directory, all IDS features will be disabled.

20.1  Check List

Points to remember:

- Create the OptionsIds.h file in the platform tip build directory. AMD recommends the use of a sub-directory named ‘AGESA’ to contain these files and the build output files.
- Edit and modify the option selections to meet the needs of the specific platform.
- Set the environment variable ‘AGESA_OptsDir’ to the path of the AGESA subdirectory of the platform tip build directory.
- Check to make sure the call-out “AgesaGetIdsData” on page 168 has been implemented in the host environment.
- Optionally, #define IDS_DEBUG_PORT to redirect AGESA_TESTPOINT output from the default IO port.

20.2  Example

Example OptionsIds.h file:

```c
/**
 * IDS Option File
 *
 * This file is used to switch on/off IDS features.
 *
 */
#ifndef _OPTION_IDS_H_
#define _OPTION_IDS_H_

#define IDSOPT_IDS_ENABLED FALSE
#define IDSOPT_ERROR_TRAP_ENABLED FALSE
#define IDSOPT_ASSERT_ENABLED FALSE
#define IDSOPT_CONTROL_ENABLED FALSE
#define IDSOPT_HEAP_CHECKING FALSE
#define IDSOPT_TRACING_ENABLED FALSE
#define IDSOPT_PERF_ANALYSIS FALSE
#endif
```
You may cut and paste from this example to create the platform tip copy of the OptionsIds.h file.

### 20.3 Debugging Using IDS

It is highly recommended that you set the following for initial integration and development:

```c
#define IDSOPT_IDS_ENABLED TRUE
#define IDSOPT_ERROR_TRAP_ENABLED TRUE
#define IDSOPT_ASSERT_ENABLED TRUE
```

Enabling ASSERT will provide limit and sanity checking of many platform BIOS inputs, as well as AGESA™ internal error checks. Enabling IDS_ERROR_TRAP provides for debugging system error events. In some cases, these errors are really caused by incorrect wrapper implementation. Both macros provide for halting near to the point the error is actually detected and help to ensure issues don’t go unnoticed.

When halting due to an ASSERT or IDS_ERROR_TRAP, the stop code will be displayed on the debug port. The stop code consists of two pieces of information: the file code and the line number. The file code is four hex digits and uniquely identifies the file containing the ASSERT or IDS_ERROR_TRAP. The file Include\Filecode.h contains the file code for each file. The line number is the remaining four hex digits and provides the line number in that file. For example, 0210 identifies line two hundred ten as the source line. Each ASSERT or IDS_ERROR_TRAP has adjacent comments in the source code describing the error and any wrapper issues known to be associated with the error.

The implementation provides a rotating display of the error code on the port 80h POST display card. The rotation is used to make it easier to view the error on both a 16-bit as well as a 32-bit display card. Additional support is available when running simulation.

In addition, AGESA_TESTPOINT output provides a useful progress indicator. Testpoints are defined in Ids.h, and are displayed on the IO port indicated by IDS_DEBUG_PORT. It is highly recommended that IDS_DEBUG_PORT be defined to a value that permits inspection, if the default port does not provide that. IDS_DEBUG_PORT only affects AGESA_TESTPOINT output, not other IDS debug output.

To help clarify AGESA IDS as the source of the testpoint, there are two controls to set the size and a pre-fix for the testpoint value:

- `IDS_DEBUG_PORT_SIZE_IN_BYTES` - sets the size of the IO cycle write for the testpoint. Options are:
  - 1 - Byte writes. The Prefix must be defined as 0x00.
  - 2 - Word writes. The Prefix may be one byte in size.
  - 4 - (default) DWord writes. The PreFix may be 3 bytes long.

- `IDS_DEBUG_TP_PERFIX` - Sets the value of a prefix set of bytes to be used in the upper bytes of the IO write to identify the source of the code.
0x00 - default for port size of 1, byte writes
0xA0 - default for port size of 2, word writes
0xA9E5A0 - default for port size of 4, dword writes.
Chapter 21  HDT Console

This category of IDS Services allow the AMD Hardware Debug Tool (HDT) to interact with the AGESA™ software as it is performing its operation. Information tracing the progress of an algorithm can be displayed on the HDT monitor, providing data for analyzing the correctness and effectiveness of the algorithm or identifying platform hardware problem.

Refer to the file, AMDTools\HDTOUT\Readme.txt, in your release package for latest and most detailed information.

21.1  Starting an HDT Console debug session

The following components must be located and installed:

**Hardware Requirements:**
- HDT interface device. AMD provides several generations of devices for interfacing a host PC to the target test system. The presently in use devices are: Possum, Purple Possum or Wombat.
- USB cable (A <-> B)
- Motherboard of the test target must have the HDT connection header built onto the board
- Test target system
- Host PC

**Software Requirements:**
- HDT v7.5 or later
- Perl v5.10 or later (ActivePerl is recommended)
- BIOS with HDT Console feature enabled. To enable a BIOS with HDT Console features:
  - Ensure $(AGESA_OptsDir)\OptionsIds.h exists.
  - IDSOPT_IDS_ENABLED must be TRUE.
  - IDSOPT_TRACING_ENABLED must be TRUE.

On the host PC, open a command prompt window (‘DOS box’); set the path to the location of the desired script; then run the perl program with the desired script, e.g.

C:> perl hdtout2008.pl

When a BIOS with HDT Console features is loaded and executed, it will boot normally except that the HDT script can display the data on the console and also recorded to a text file on C:\ drive.
21.2 Available Scripts

AMD provides scripts in the `AMDTools` sub-directory of the release package. These are the scripts available and the features they provide:

- **hdtout2008.pl** - The main purpose for this script is to control, collect and display algorithm trace data.

- **perfout.pl** - This script collects time stamp data from the test target and then analyses the data to produce some statistical time measurements.
Section VI - Appendices
Appendix A  Family Specific Details

This section contains interface details that vary by the processor family. Some features, such as thermal controls, vary greatly as the capabilities evolve in newer family processors. API differences could not be avoided. Those details that vary by processor family are marked in the main text with a reference to this section.

As mentioned earlier, the AGESA code files (e.g. agesa.h) should be referenced for the fine details about the interface.

If a specific family is not mentioned in this section, then it does not have family specific details or is covered by a previous version of this specification.

A.1  Family 15h Models 30h-3Fh

The Family 15h, Model 3xh APUs are x86-64 architecture and will use the full set of procedures defined in this API specification.

A.1.1  Call Entries & parameters

AmdInitEarly()

AdvancedPerformanceProfile

This is the same parameter as described “AdvancedPerformanceProfile” on page 264.
A.2 Family 15h Models 60h-6Fh

The Family 15h, Model 6xh APUs are x86-64 architecture and will use the full set of procedures defined in this API specification. In addition, they will also have the following extensions.

A.2.1 Call Entries & parameters

AmdInitEarly()

AdvancedPerformanceProfile

These settings provide for performance tuning to optimize for specific workloads. For general performance use the recommended settings.

typedef struct {
    IN HARDWARE_PREFETCH_MODE HardwarePrefetchMode;
    IN SOFTWARE_PREFETCH_MODE SoftwarePrefetchMode;
    IN DRAM_PREFETCH_MODE DramPrefetchMode;
} ADVANCED_PERFORMANCE_PROFILE;

HardwarePrefetchMode

This feature provides advanced tuning of the hardware prefetcher. This value is initially declared by the build configuration element “BLDCFG_PERFORMANCE_HARDWARE_PREFETCHER” on page 268. The value is presented here for possible host environment modification.

SoftwarePrefetchMode

This feature provides advanced tuning of software prefetches. This value is initially declared by the build configuration element “BLDCFG_PERFORMANCE_SOFTWARE_PREFETCHES” on page 269. The value is presented here for possible host environment modification.

DramPrefetchMode

This feature provides advanced tuning of the DRAM prefetcher. This value is initially declared by the build configuration element “BLDCFG_PERFORMANCE_DRAM_PREFETCHER” on page 269. The value is presented here for possible host environment modification.

MemoryPowerPolicy

This feature provides an indication of desired power policy used in the memory components. This value is initially declared by the build configuration element “BLDCFG_MEMORY_POWER_POLICY_MODE” on page 268. The value is presented here for possible host environment modification.

ThermCtlLimit

This item sets the target thermal limit to be imposed by the system management unit. This value is initially declared by the build configuration
element “BLDCFG_THERMCTL_LIMIT” on page 271. The value is presented here for possible host environment modification.

Resolution

This item specifies the highest expected display resolution to be supported. It is used to allocate an appropriately sized UMA buffer.

This value is initially declared by the build configuration element “BLDCFG_RESOLUTION” on page 270. The value is presented here for possible host environment modification.

BatteryBoostTune

This item adjusts the allowed amount of boost activity while the unit is being powered from a battery. This value is initially declared by the build configuration element “BLDCFG_BATTERY_BOOST_TUNE” on page 272. The value is presented here for possible host environment modification.

PkgPwrLimitAC

This item sets the upper limit on package power to be used for when the unit is powered by an AC source. This value is initially declared by the build configuration element “BLDCFG_PPT_LIMIT_AC” on page 271. The value is presented here for possible host environment modification.

PkgPwrLimitDC

This item sets the upper limit on package power to be used for when the unit is powered by an DC (battery) source. This value is initially declared by the build configuration element “BLDCFG_PPT_LIMIT_DC” on page 271. The value is presented here for possible host environment modification.

PlatStapmConfig

This item sets the target thermal limit to be imposed by the system management unit. This value is initially declared by the build configuration
typedef struct {
  IN UNIT32 CfgStapmScalar;
  IN UINT32 CfgStapmBoost;
  IN UINT32 CfgStapmTimeConstant;
} PLATFORM_STAPM_CONFIGURATION;

CfgStapmScalar

This value is initially declared by the build configuration element “BLDCFG_STAPM_SCALAR” on page 272. The value is presented here for possible host environment modification.
CfgStapmBoost

This value is initially declared by the build configuration element “BLDCFG_STAPM_BOOST” on page 272. The value is presented here for possible host environment modification.

CfgStapmTimeConstant

This value is initially declared by the build configuration element “BLDCFG_STAPM_TIME_CONSTANT” on page 272. The value is presented here for possible host environment modification.

AzaliaCodecVerbTable

This item points to the vendor specific CODEC verb tables. This value is initially declared by the build configuration element “BLDCFG_CODEC_VERB_TABLE” on page 273. The value is presented here for possible host environment modification.

GnbAzI2sBusSelect

This item specifies where the High Definition Audio CODEC is attached to the system and how the Audio controller should communicate. This value is initially declared by the build configuration element “BLDCFG_GNB_AZ_I2SBUS_SELECT” on page 274. The value is presented here for possible host environment modification.

GnbAzI2sBusPinConfig

This item informs the software about the capabilities of the I2S CODEC. This value is initially declared by the build configuration element “BLDCFG_GNB_AZ_I2SBUS_PIN_CONFIG” on page 274. The value is presented here for possible host environment modification.

AzaliaSsid

This item allows user specify the (analog) HD Audio Controller Subsystem Vendor ID and Subsystem ID. This value is initially declared by the build configuration element “BLDCFG_GNB_AZ_SSID” on page 274. The value is presented here for possible host environment modification.

AmdInitPost()

EnableBankSwapOnly

This value is initially declared by the build configuration element “BLDCFG_MEMORY_ENABLE_BANK_SWAP_ONLY” on page 268. The value is presented here for possible host environment modification.

UmaVersion
This value is initially declared by the build configuration element “BLDCFG_UMA_VERSION” on page 269. The value is presented here for possible host environment modification.

**DimmTypeDdbr4Capable**

This value is initially declared by the build configuration element “BLDCFG_DIMM_TYPE_DDR4_CAPABLE” on page 270. The value is presented here for possible host environment modification.

**DimmTypeDdbr3Capable**

This value is initially declared by the build configuration element “BLDCFG_DIMM_TYPE_DDR3_CAPABLE” on page 270. The value is presented here for possible host environment modification.

**CustomVddioSupport**

CustomVddioSupport helps to customize the VDDIO voltage for DRAM. If this is set to AGESA_DEFAULTS then AGESA will determine the DRAM voltage based upon SPD Data.

**AmdInitEnv()**

**EDPv1_4VSMode**

This item selects the training method to be used on the eDP ports.

This value is initially declared by the build configuration element “BLDCFG_EDP_V1_4_VS_MODE” on page 274. The value is presented here for possible host environment modification.

**ExtHDMIReDrvSlvAddr**

This item specifies the I2C bus address of the HDMI conditioning transceiver chip. This parameter is a numeric value from 0 - 255, with 0 meaning that the software does not need to set configuration values in the chip. Default is 0 (zero).

This value is initially declared by the build configuration element “BLDCFG_EXT_HDMI_RE_DRIVE_SLAVE_ADDR” on page 275. The value is presented here for possible host environment modification.

**ExtHDMIReDrvRegNum**

This item indicates the number of registers that need to be set in the HDMI conditioning transceiver chip. This parameter is a numeric value from 0 - N, with a value of 0 indicating that the chip does not need to be configured by software. The default is 0 (zero).
This value is initially declared by the build configuration element “BLDCFG_EXT_HDMI_RE_DRIVE_REG_NUM” on page 275. The value is presented here for possible host environment modification.

*ExtHDMIRegSetting*

This item is a pointer to a data table containing the configuration settings for the HDMI conditioning transceiver chip. The default is null, meaning there is no table implemented and the chip does not need software configuration.

This value is initially declared by the build configuration element “BLDCFG_EXT_HDMI_RE_DRIVE_REG_INFO” on page 275. The value is presented here for possible host environment modification.

### A.2.2 Configuration elements

#### A.2.2.1 Memory Elements

**BLDCFG_MEMORY_POWER_POLICY_MODE**

This value provides for advanced performance tuning by controlling the power saving features.

- **Performance** - (Default) Maximize performance; disables all power saving features.
- **BatteryLife** - Maximize battery life; some features may cause response latency.
- **Auto** - A balanced approach; save power without causing most latencies.

**BLDCFG_MEMORY_ENABLE_BANK_SWAP_ONLY**

This is an advanced performance setting. It specifies if the system should use DRAM BankSwapOnly mode. The AMD recommended setting is indicated by the default setting. Changes to this setting must be based on individual platform testing.

- **TRUE** = enable
- **FALSE** = disable (default)

Example:

```
#define BLDCFG_MEMORY_ENABLE_BANK_SWAP_ONLY TRUE
```

**BLDCFG_PERFORMANCE_HARDWARE_PREFETCHER**

This value provides for advanced performance tuning by controlling the hardware prefetcher setting. Use the recommended setting for best general performance, but this item can allow for optimizing specific workloads. The settings below are ordered from all enabled to all disabled and a specific disable setting implies all disable settings above it in the list as well. For example, disabling the L1 prefetcher implies that hardware prefetcher training on software prefetches is also disabled.
HARDWARE_PREFETCHER_AUTO - Use the recommended setting for the processor. In most cases, the recommended setting is enabled.
DISABLE_HW_PREFETCHER_TRAINING_ON_SOFTWARE_PREFETCHES - Use the recommended setting for the hardware prefetcher, but disable training on software prefetches.
DISABLE_L1_PREFETCHER - Use the recommended settings for the hardware prefetcher, but disable L1 prefetching and above.
DISABLE_L2_STRIDE_PREFETCHER - Use the recommended settings for the hardware prefetcher, but disable the L2 stride prefetcher and above.
DISABLE_HARDWARE_PREFETCH - Disable hardware prefetching.
DISABLE_L1_PREFETCHER_AND_HW_PREFETCHER_TRAINING_ON_SOFTWARE_PREFETCHES (deprecated) - This setting is deprecated; it has the same effect as DISABLE_L1_PREFETCHER.

BLDCFG_PERFORMANCE_SOFTWARE_PREFETCHES
This value provides for advanced performance tuning by controlling the software prefetch instructions. Use the recommended setting for best general performance, but this item can allow for optimizing specific workloads.
SOFTWARE_PREFETCHES_AUTO - Use the recommended setting for the processor. In most cases, the recommended setting is enabled.
DISABLE_SOFTWARE_PREFETCHES - Disable software prefetches (convert software prefetch instructions to NOP).

BLDCFG_PERFORMANCE_DRAM_PREFETCHER
This value provides for advanced performance tuning by controlling the DRAM prefetcher setting. Use the recommended setting for best general performance, but this item can allow for optimizing specific workloads.
DRAM_PREFETCHER_AUTO - Use the recommended setting for the processor. In most cases, the recommended setting is enabled.
DISABLE_DRAM_PREFETCH_FOR_IO - Disable DRAM prefetching for I/O requests only.
DISABLE_DRAM_PREFETCH_FOR_CPU - Disable DRAM prefetching for requests from processor cores only.
DISABLE_DRAM_PREFETCHER - Disable DRAM prefetching.

BLDCFG_UMA_VERSION
This is a new methodology in the selection of the UMA video memory buffer. It works in conjunction with the other UMA controls to allow the user to set the UMA buffer size.
UMA_LEGACY - (Default) The traditional UMA allocation method will be used. The user will specify a size using the controls:
UMA_NON_LEGACY - The size of the UMA buffer will be determined by the table in the BKDG, based on available memory and the expected maximum display resolution. See “BLDCFG_RESOLUTION” on page 270.

**BLDCFG_RESOLUTION**

This control specifies the maximum resolution the platform is capable of supporting. This value will be used to calculate the UMA buffer size.

- DISPLAY_1920x1080_And_Below - (Default) The display resolution is expected to be 1080p or below.
- DISPLAY_2560x1600 - The platform is capable of supporting medium high resolution display devices.
- DISPLAY_3840x2160 - The platform is capable of supporting the high resolution (“4K”) displays.

**BLDCFG_CUSTOM_VDDIO_VOLTAGE**

This control is used when the platform designer wishes to establish a customized VDDIO value for the platform. Options are:

- VOLT1_5 - VDDIO is set to 1.5 Volt
- VOLT1_35 - VDDIO is set to 1.35 Volt
- VOLT1_25 - VDDIO is set to 1.25 Volt
- VOLT_INITIAL - (Default) AGESA determines the voltage setting from the SPDs.

Example:
If platform want to set the DRAM Voltage to 1.25 V, then
#define BLDCFG_CUSTOM_VDDIO_VOLTAGE VOLT1_25

**BLDCFG_DIMM_TYPE_DDR3_CAPABLE**

Specifies if the platform is designed to be capable of supporting DDR3 memories. Options are:

- TRUE (default)
- FALSE

Example:

#define BLDCFG_DIMM_TYPE_DDR3_CAPABLE TRUE

**BLDCFG_DIMM_TYPE_DDR4_CAPABLE**

Specifies if the platform is designed to be capable of supporting DDR3 memories. Options are:

- TRUE (default)
- FALSE

Example:
A.2.2.2 Thermal and Power Control Elements

Thermal control of the system is a very complicated activity. It is highly advised that the values used in this section are set or reviewed by a Thermal Engineer.

\textit{BLDCFG\_THERMCTL\_LIMIT}

This specifies the die temperature limit, on the T\textsubscript{ctl} temperature scale, to which the processor manages activity. The processor controls the activity level that contributes to power consumption, such as P-states and DPM-states, so that the die temperature remains within this limit. It is recommended that this value be set at least 5T\textsubscript{ctl} below the HTC limit.

This control can be used to balance full system thermals by reducing the budget allocated for the APU in favor of external devices, such as an external GPU. Reducing this value is also a way to address chassis skin temperature issues.

0 - (default) Use the factory setting.
1..74 - invalid. Values in this range will be ignored. The factory setting will be used.
75..95 specifies the T\textsubscript{ctl} value at which the cHTC feature is to be invoked.

\textit{BLDCFG\_PPT\_LIMIT\_AC}

This value defines the limit for package power utilization while attached to an AC power source. AMD provides a recommended power budget value for the APU (full package). This control is provided so that the system designer can inform the software of the power budgeted for the APU in this design.

The default value for this parameter is 0; meaning the AMD recommended package limits will be used.

To specify a package power limit, the value is be specified in milli-watts. For example, a power budget of 27.5 watts is represented as:

\begin{verbatim}
#define BLDCFG_PPT_LIMIT_AC 27500
\end{verbatim}

\textit{BLDCFG\_PPT\_LIMIT\_DC}

This value defines the limit for package power utilization while attached to an DC battery source. The IRM specifies a recommended power budget value for the APU (full package). This control is provided so that the system designer can inform the software of the power budgeted for the APU in this design.
The default value for this parameter is 0; meaning the AMD recommended package limits will be used.

To specify a package power limit, the value must be specified in **milli-watts**. For example, a power budget of 12.25 watts is represented as:

```c
#define BLDCFG_PPT_LIMIT_DC 12250
```

**BLDCFG_BATTERY_BOOST_TUNE**

Specifies the power limit enforced by the SMU as part of the Boost algorithm while the unit is being powered from a battery.

This parameter takes a numeric value which represents a percentage of the DC package Power Limit (see “BLDCFG_PPT_LIMIT_DC”).

The default value for this parameter is 0; meaning the AMD recommended value will be used.

For example, a value of 110 will increase the DC power limit by 10% (110% of the DC power limit) during Boost periods.

```c
#define BLDCFG_BATTERY_BOOST_TUNE 110
```

**BLDCFG_STAPM_BOOST**

The STAPM feature will maintain the system skin temperature under a specified thermal target. This control allows the user to select the thermal algorithm.

- **StapmBoostDisabled** — The STAPM feature is turned off.
- **StapmBoostSystemConfig** — (default) The system will use the standard AMD recommended thermal target.
- **StapmBoostEnabled** — Boost will be allowed, and the user will specify other STAPM parameters using the other BLDCFG controls in this section.

**BLDCFG_STAPM_SCALAR**

This parameter takes a value from 50 to 200, representing the percent of the STAPM Skin Temperature to actually target for operation.

Default is 100 (100%) of the specified target skin temperature.

For example, a value of 115 will increase the target skin temperature by 15%.

```c
#define BLDCFG_STAPM_SCALAR 115
```

**BLDCFG_STAPM_TIME_CONSTANT**
This parameter takes a value from 50 to 500, representing the time period that STAPM Boost can be active, specified in milli-seconds.

The default value is 0; meaning the system standard time value will be used.

For example, a time period of 500 milli-seconds is represented as:

```
#define BLDCFG_STAPM_TIME_CONSTANT 500
```

### BLDCFG_SYSTEM_CONFIGURATION

For each family, AMD has predefined group settings for the thermal related BLDCFGS controls. The user may choose a system ‘Pre-set’ as defined, or they may modify it by using an explicit BLDCFG control.

This parameter is a numeric value from 1 to N, with ‘N’ being defined in the family IRM. Default value is 0, meaning the AMD recommended default will be used.

Caution: the pre-sets for this family may not match the Pre-sets for another family.

### A.2.2.3 HD Audio Elements

#### BLDCFG_CODEC_VERB_TABLE

Audio devices use a encoder/decoder chip (CODEC) to process audio signals. The manufacturers of these chips use a ‘codec verb table’ to configure the chip for operation. This table of values is obtained from the CODEC manufacturer and included into the BIOS image. This control allows the user to specify the identifier used for the verb table. To accommodate flexibility, multiple CODEC tables can be provided and the Azalia support code will match the chip present in the system with it appropriate table. The default is an unassigned pointer (null), which will result in no operational audio device.

Example:

```
UINT32 AzaliaCodecMfgrATable[] =
{
  0x00172051, 0x001721C7, 0x00172222, 0x00172310,
  .......
  0xffffffff  // End marker
};
#define MFGR_A_CODEC_ID                          0x12345678ul
CONST CODEC_VERB_TABLE_LIST OemCodecTableList[] =
{
  { (UINT32) MFGR_A_CODEC_ID, (UINT64)&AzaliaCodecMfgrATable[0]},
  { (UINT32) 0xFFFFfffffful, (UINT64)0xFFFFfffffful}// End marker
};
#define BLDCFG_CODEC_VERB_TABLE                  &OemCodecTableList
```
**BLDCFG_GNB_AZ_I2SBUS_SELECT**

This item specifies where the High Definition Audio CODEC is attached to the system and how the Audio controller should communicate.

Permitted values are:
- GnbAcpAzalia - (Default) The Codec is attached on the Azalia bus.
- GnbAcpI2sBus - The Codec is attached on the I2S bus.

Example:
```c
#define CFG_GNB_AZ_I2SBUS_SELECT GnbAcpAzalia
```

**BLDCFG_GNB_AZ_I2SBUS_PIN_CONFIG**

This value identifies the characteristics, or capabilities, of the I2S CODEC device used in the platform design.

- GnbAcp4Tx4RxBluetooth - (Default) (4 Tx, 4 Rx, and Bluetooth)
- GnbAcp2Tx4RxBluetooth (2 Tx, 4 Rx, and Bluetooth)
- GnbAcp6Tx4RxBluetooth (6 Tx, 4 Rx, and Bluetooth)

Example:
```c
#define CFG_GNB_AZ_I2SBUS_PIN_CONFIG GnbAcp4Tx4RxBluetooth
```

**BLDCFG_GNB_AZ_SSID**

The GNB_AZ device is targeted for analog audio output (a 3.5mm speaker/headphone jack). This Azalia HD Audio device can be assigned a PCIe ID for controlling which driver is loaded to manage the device. The default value is 0 (zero), which will leave the device in its power-up setting.

Example:
```c
#define BLDCFG_GNB_AZ_SSID 0x157A1022ul
```

### A.2.2.4 Graphics and PCIe® Elements

**BLDCFG_EDP_V1_4_VS_MODE**

The Enhanced Display Port (eDP) has the ability to handle signal lines that have several voltage characteristics. This item indicates which should be used. The selection must match with the selected display panel requirements.

- EDP_VS_LEGACY_MODE - (Default) Legacy Mode, backward compatible to the v1.3 of the eDP spec or earlier.
- EDP_VS_LOW_VDIFF_MODE - Low Vdiff Training Mode
- EDP_VS_HIGH_VDIFF_MODE - High Vdiff Training Mode
- EDP_VS_STRETCH_MODE - Stretched DP training mode
- EDP_VS_SINGLE_VDIFF_MODE - Single Vdiff Training Mode
EDP_VS_VARIABLE_PREM_MODE - Single Vdiff Training with Variable Transition Vdiff

A.2.2.4.1 High Speed HDMI Controls

In order to support higher HDMI speeds (such as HDMI 2.0), platform designs need to use an interface chip for signal conditioning on the HDMI port. The design may support transceiver chips from many manufacturers between the APU and HDMI connector for signal conditioning. The motherboard designer must inform the software about the designer’s choice and pass information about the chip to the software for use in configuring the chip.

The specific chip choice is indicated by the platform designer in the PCIE DDI descriptors flags byte explained in “Flags” on page 352. The following items provide data to describe the chosen device.

**BLDCFG_EXT_HDMI_RE_DRIVE_SLAVE_ADDR**

This item specifies the bus address used to communicate to the HDMI conditioning device.

- 0 - (Default) means that the software does not need to set configuration values in the device.
- 1-255 - the I2C bus address of the HDMI conditioning transceiver chip.

**BLDCFG_EXT_HDMI_RE_DRIVE_REG_NUM**

This item indicates the number of registers that need to be set in the HDMI conditioning transceiver chip.

- 0 - (Default) indicates the chip does not need to be configured by software.
- N - decimal number of register to set. This must match the size of the Reg Info table.

**BLDCFG_EXT_HDMI_RE_DRIVE_REG_INFO**

This item is a pointer to a data table containing the configuration settings for the HDMI conditioning transceiver chip. Please refer to the AGESA.H file for more details about the structure.

The default is null, meaning there is no table implemented and the chip does not need software configuration.
A.3 Family 16h, Models 30h - 3Fh

The controls described here are used only by the Family 16h, Model 3xh APUs. These controls are replaced by a newer generation of controls for the other families listed in this version of the Specification.

A.3.1 Call Entries & parameters

AmdInitEarly()

HtcTemperatureLimit

This item customizes support for thermal control. This value is initially declared by the build configuration element “BLDCFG_HTC_TEMPERATURE_LIMIT” on page 277. The value is presented here for possible host environment modification.

LhtcTemperatureLimit

This item customizes support for thermal control. This value is initially declared by the build configuration element “BLDCFG_LHTC_TEMPERATURE_LIMIT” on page 277. The value is presented here for possible host environment modification.

AdvancedPerformanceProfile

This is the same parameter as described “AdvancedPerformanceProfile” on page 264.

AmdInitLate()

DockedTdpHeadroom

Motherboard designs that follow the AMD recommendations for mobile units will be able to take advantage of the extra heat dissipation capability of the dock. This control informs the thermal control software that the design conforms to the recommendations.

This value is initially declared by the build configuration element “BLDCFG_DOCKED_TDP_HEADROOM” on page 278. The value is presented here for possible host environment modification.

A.3.2 Configuration elements

A.3.2.1 Thermal and Power Control Elements

BLDCFG_BATTERY_BOOST_EN
Specifies if the Boost feature should be allowed while operating on battery power.

TRUE — (default) processor Boost states will be used.
FALSE — Save power by disabling Boost states while on battery power.

**BLDCFG_HTC_TEMPERATURE_LIMIT**

This control specifies the temperature at which the processor’s hardware thermal control (HTC) feature is activated. The HTC feature reduces the power consumption and performance of the processor when this temperature limit is reached to prevent further heating. The HTC feature has a Global (‘whole chip’) component and also a Local (‘cores only’) component.

This control (HTCG Limit) is the ‘Global’ component which includes all of the sub-systems present on the processor.

If set, (non-zero) then the Local HTC temperature value must also be set, see “BLDCFG_LHTC_TEMPERATURE_LIMIT” on page 277. The temperature limit is specified in tenth of degrees centigrade increments (0.1). Values below 520 (52.0°C) are ignored. Values above the factory default setting for the processor are ignored. See the processor’s Thermal Design Guide for details.

0 - Use the factory setting. (default).
1.. 519 - invalid. Values in this range will be ignored. The factory setting will be used.
520..HTCG - (52.0 to (HTCG/10)oC) specifies the temperature at which the HTC feature is to be invoked.

**BLDCFG_LHTC_TEMPERATURE_LIMIT**

This control applies only when the HTCG limit is set manually (is non-zero). See “BLDCFG_HTC_TEMPERATURE_LIMIT” on page 277.

This control specifies the temperature at which the processor’s hardware thermal control (HTC) feature is activated. The HTC feature reduces the power consumption and performance of the processor when this temperature limit is reached to prevent further heating. The HTC feature has a Global (‘whole chip’) component and also a Local (‘cores only’) component.

This control (HTC1 Limit) is the ‘Local’ component which includes only the compute unit cores present on the processor. This control allows a more fine-tuned handling of the thermal state.

This value is specified in tenth of degrees centigrade increments (0.1) and is recommended to be 3 to 5°C below the value for HTCG limit. Values above the HTC1 factory default setting for the processor are ignored. See the processor’s Thermal Design Guide for details.
0 - Use the factory setting. (default).
1..519 - invalid. values in this range will be ignored. The default setting will be used.
520..HTC1 - (52.0 to (HTC1/10)°C) specifies the temperature at which the HTC feature is to be invoked.

**BLDCFG\_DOCKED\_TDP\_HEADROOM**

Specifies if there is additional heat dissipation available when the system is docked.

TRUE — (default) The motherboard complies with the AMD recommendations for mobile units. There is extra heat dissipation capability in the dock.

FALSE — There is no extra heat dissipation available.

Note: This feature applies to the APUs using the TurboDock feature. Future APUs may deprecate this control to support new features, see the “Elements for DcTDP\_V2.0” on page 278.

### A.3.2.1.1 Elements for DcTDP\_V2.0

The algorithms used for power and thermal management continues to evolve. The Mullins APU expands the dynamic TDP controls and adds a new capability called Skin Temperature Adaptive Power Management (STAPM). Older APUs that share the same socket may also need to use the “BLDCFG\_DOCKED\_TDP\_HEADROOM” control to support their features.

The DcTDP\_V2.0 feature defines a ‘four box’ set of configurable control values. The current management parameters being enforced are selected by the indices of the box.

<table>
<thead>
<tr>
<th>Docked</th>
<th>AC</th>
<th>DC</th>
</tr>
</thead>
<tbody>
<tr>
<td>TDP</td>
<td>TDP = 9 watts</td>
<td>TDP = 9 watts</td>
</tr>
<tr>
<td>STAPM enabled</td>
<td>STAPM enabled = False</td>
<td>STAPM enabled = False</td>
</tr>
<tr>
<td>STAPM power</td>
<td>STAPM power = (n/a)</td>
<td>STAPM power = (n/a)</td>
</tr>
<tr>
<td>TSP</td>
<td>TSP = (n/a)</td>
<td>TSP = (n/a)</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>UnDocked</th>
<th>AC</th>
<th>DC</th>
</tr>
</thead>
<tbody>
<tr>
<td>TDP</td>
<td>TDP = (n/a)</td>
<td>TDP = (n/a)</td>
</tr>
<tr>
<td>STAPM enabled</td>
<td>STAPM enabled = True</td>
<td>STAPM enabled = True</td>
</tr>
<tr>
<td>STAPM power</td>
<td>STAPM power = 9 watts</td>
<td>STAPM power = 9 watts</td>
</tr>
<tr>
<td>TSP</td>
<td>TSP = 5 watts</td>
<td>TSP = 5 watts</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th></th>
<th>AC</th>
<th>DC</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>TDP = (n/a)</td>
<td>TDP = (n/a)</td>
</tr>
<tr>
<td></td>
<td>STAPM enabled = True</td>
<td>STAPM enabled = True</td>
</tr>
<tr>
<td></td>
<td>STAPM power = 9 watts</td>
<td>STAPM power = 9 watts</td>
</tr>
<tr>
<td></td>
<td>TSP = 5 watts</td>
<td>TSP = 5 watts</td>
</tr>
</tbody>
</table>

* The numbers used in this example are illustrative of a predicted configuration, but each OEM should determine the values appropriate for their platform.
For more information about the thermal control features and algorithms, please refer to the AMD specifications for the specific APU.

`BLDCFG_TDP_AC_DOCKED`
`BLDCFG_TDP_DC_DOCKED`
`BLDCFG_TDP_AC_UNDOCKED`
`BLDCFG_TDP_DC_UNDOCKED`

Specifies the TDP the systems should target when the unit is operating in the indicated box.

This is a numeric value representing the absolute TDP, in milliwatts. For example, a target TDP of 4.5 watts is represented as:

```
#define BLDCFG_TDP_DC_UNDOCKED 4500
```

The default value is zero (0), meaning the unit will use the pre-set values for the part.

`BLDCFG_TSP_AC_DOCKED`
`BLDCFG_TSP_DC_DOCKED`
`BLDCFG_TSP_AC_UNDOCKED`
`BLDCFG_TSP_DC_UNDOCKED`

Specifies the Thermally Significant Power (TSP) the systems should target when the unit is operating in the indicated box. The TSP is the recommended target power level for designing skin temperature limited fanless platforms.

This parameter is used only when STAPM is enabled. For more information on STAPM and TSP refer to the Thermal Design for Fanless Tablets. This is a numeric value representing the absolute TSP, in milliwatts. For example, a target TSP of 4.5 watts is represented as:

```
#define BLDCFG_TSP_DC_UNDOCKED 4500
```

The default value is zero (0), meaning the unit will use the pre-set values for the part.

`BLDCFG_STAPM_EN_AC_DOCKED`
`BLDCFG_STAPM_EN_DC_DOCKED`
`BLDCFG_STAPM_EN_AC_UNDOCKED`
`BLDCFG_STAPM_EN_DC_UNDOCKED`

Select whether or not the STAPM process should be active when the unit is operating in the indicated box. When the STAPM feature is active, the unit will follow the TSP for guidance on actions. When the STAPM feature is disabled, the unit will follow the TDP for guidance on actions.
This is a boolean value.
TRUE - Enable the STAPM process in this box (default).
FALSE - Disable STAPM for this box.

BLDCFG_STAPM_POWER_AC_DOCKED
BLDCFG_STAPM_POWER_DC_DOCKED
BLDCFG_STAPM_POWER_AC_UNDOCKED
BLDCFG_STAPM_POWER_DC_UNDOCKED

This parameter specifies the maximum power that the APU is allowed to consume as long as the skin temperature of the system stays within the specified limits. This parameter is used only when STAPM is enabled. For STAPM-supported systems, the thermal solution should be designed to STAPM Power levels at maximum die temperature (Tdie max).

This is a numeric value representing the absolute power, in milliwatts. For example, a target power of 9 watts is represented as:

```
#define BLDCFG_STAPM_POWER_DC_UNDOCKED 9000
```

A value of 0 (default) means that pre-set values for the part will be used.

BLDCFG_NUM_GFX_CORES_ENABLED

Used to specify how many graphic compute units are to be enabled on the APU. This control allows designers to reduce the number of active compute units for thermal/power reasons.

This is a number between 0 and <N> (the maximum available compute units). The default value of (-1) indicates no limit, use all available compute units.

A.3.2.2 Graphics and PCIe® Elements

BLDCFG_LVDS_MISC_VSYNC_ACTIVE_LOW

This specifies a miscellaneous control for LVDS.
TRUE - The VSYNC signal is active low.
FALSE - The VSYNC signal is active high (default).

BLDCFG_LVDS_MISC_HSYNC_ACTIVE_LOW

This specifies a miscellaneous control for LVDS.
TRUE - The HSYNC signal is active low.
FALSE - The HSYNC signal is active high (default).
Appendix B Tools

B.1 BINUTIL2

Command Line


Description

This tool is used to transform the relocatable execution program file into a binary image. The process changes all of the relocatable address references into fixed address references.

Parameters

/INFILE

List of files to merge into the output image.

/OUTFILE

Name to file to create/replace which contains the merges modules.

[options]:

/IMAGEBASE:[Address] - Image Base address (Example /IMAGEBASE:0xffff0000)

/IMAGETYPE:[Type] - ImageType string B1/B2 (Example /IMAGEBASE:B1)

/VERSION:[Version] - Binary Image Version string (Example /VERSION:1.2.3)

/CREATORID:[Creatorid] - Creator ID string (Example /CREATORID:AMD)


Usage Examples

$(AGESA_ROOT)AMDTools\binutil2 /INFILE:$(OutDir)Agesa_B2_Target.dll
/OUTFILE:$(OutDir)agesa.b2 /IMAGETYPE:B2 /IMAGEBASE:$(AGESA_B2_ADDRESS)
/BDIFILE:$(OutDir)Agesa_B2.bdi
Appendix C  Logged Error Messages

Refer to the internal documentation for the latest and most detailed information (“Internal Documentation” on page 26) on specific logged events.

General form of numeric errors:

Class: AGESA_WARNING
SubClass: 0x00000000
0x00000000, 0x00000000, 0x00000000, 0x00000000 ...

A, B, C, D

Class—This matches the AGESA™ software return code reported from the entry procedure.

Sub-Class—This indicates the group of code files from which the error is being reported and the specific sub-class error. This value has the following bit fields:

AppId:8 — (MSB) Application that generated the event
EventId:8 — Nature of Event; dependent on the application
AppFunction:8 — Indicates the function where the event occurred
SubReason:8 — (LSB) Reason code for the Event; dependent on the application.

A, B, C, D—Sub-class data. This is data that better explains the error and/or its cause. The meaning of this data is specific to the sub-class. Please see the references below for details.

C.1  AGESA_SUCCESS Class

Sub-Class: Memory

<table>
<thead>
<tr>
<th>Sub-Class Fields</th>
<th>Sub-Class Data Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>ID</td>
<td>Event</td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
</tr>
<tr>
<td></td>
<td>MEM_EVENT_CAPSULE_IN_EFFECT</td>
</tr>
<tr>
<td>0x04</td>
<td>0x02</td>
</tr>
<tr>
<td></td>
<td>MEM_EVENT_CONTEXT_RESTORE_IN_EFFECT</td>
</tr>
</tbody>
</table>
## Sub-Class: Processor

### Sub-Class Fields | Sub-Class Data Values
<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x01</td>
<td>0x01</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
</tbody>
</table>

**CPU_ERROR_HEAP_IS_ALREADY_INITIALIZED** - Heap has previously been initialized

### Sub-Class Fields | Sub-Class Data Values
<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x02</td>
<td>0x01</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
</tbody>
</table>

**CPU_ERROR_HEAP_IS_FULL** - Heap allocation for specified buffer handle failed as heap is full

### Sub-Class Fields | Sub-Class Data Values
<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x03</td>
<td>0x01</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
</tbody>
</table>

**CPU_ERROR_HEAP_BUFFER_HANDLE_IS_ALREADY_USED** - Allocation incomplete as buffer has previously been allocated

### Sub-Class Fields | Sub-Class Data Values
<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x01</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
</tbody>
</table>

**CPU_ERROR_HEAP_BUFFER_HANDLE_IS_NOT_PRESENT** - Unable to locate buffer handle or deallocate heap as buffer handle cannot be located

### Sub-Class Fields | Sub-Class Data Values
<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x00</td>
<td>0x01</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
</tbody>
</table>

**CPU_ERROR_HEAP_BUFFER_IS_NOT_PRESENT** - Unable to locate pointer to the heap buffer
### C.3 AGESA_ALERT Class

**Sub-Class: Memory**

<table>
<thead>
<tr>
<th>Sub-Class Fields</th>
<th>Sub-Class Data Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>ID</td>
<td>Event</td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
</tr>
</tbody>
</table>

 MEM_ALERT_USER_TMG_MODE_OVERRULED The timing mode selected by the user via a BLDCFG_item could not be used for the present configuration and has been overruled.

| ID   | Event | Fcn | Sub | A       | B      | C        | D                   |
| 0x04 | 0x01  | 0x01 | 0x00 | Socket  | DCT    | Channel  | 0x00000000          |

 MEM_ERROR_ORG_MISMATCH_DIMM

| ID   | Event | Fcn | Sub | A       | B      | C        | D                   |
| 0x04 | 0x01  | 0x02 | 0x00 | Socket  | DCT    | Channel  | 0x00000000          |

 MEM_ERROR_BK_INT_DIS - Bank interleaving disable for internal issue

**Sub-Class: Processor**

<table>
<thead>
<tr>
<th>Sub-Class Fields</th>
<th>Sub-Class Data Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>ID</td>
<td>Event</td>
</tr>
<tr>
<td>0x08</td>
<td>0x00</td>
</tr>
</tbody>
</table>

 CPU_EVENT_BIST_ERROR - BIST error is reported on the specified socket and core.

### C.4 AGESA_WARNING Class

**Sub-Class: Memory**

<table>
<thead>
<tr>
<th>Sub-Class Fields</th>
<th>Sub-Class Data Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>ID</td>
<td>Event</td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
</tr>
</tbody>
</table>

 MEM_WARNING_UNSUPPORTED_QRDIMM - QR DIMMs detected but not supported

| ID   | Event | Fcn | Sub | A       | B      | C        | D                   |
| 0x04 | 0x02  | 0x16 | 0x00 | Socket  | DCT    | Channel  | 0x00000000          |

 MEM_WARNING_UNSUPPORTED_UDIMM - Unbuffered DIMMs detected but not supported

| ID   | Event | Fcn | Sub | A       | B      | C        | D                   |
| 0x04 | 0x03  | 0x16 | 0x01 | Socket  | DCT    | Channel  | 0x00000000          |

 MEM_WARNING_UNSUPPORTED_SODIMM - SO-DIMMs detected but not supported
<table>
<thead>
<tr>
<th>Address</th>
<th>Code</th>
<th>Command</th>
<th>DCT</th>
<th>Channel</th>
<th>Info</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x04 0x04</td>
<td>0x16</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_UNSUPPORTED_X4DIMM - x4 DIMMs detected but not supported</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x04</td>
<td>0x17</td>
<td>0x02</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_ERROR_ECC_DIS</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x05</td>
<td>0x16</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_UNSUPPORTED_RDIMM - Registered DIMMs detected but not supported</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x06</td>
<td>0x16</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_UNSUPPORTED_LRDIMM - Load Reduced DIMMs detected but not supported</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x19</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_NO_SPDTRC_FOUND</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x17</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
<tr>
<td>MEM_WARNING_EMP_NOT_SUPPORTED - Processor is not capable for EMP</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x02</td>
<td>0x17</td>
<td>0x01</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
<tr>
<td>MEM_WARNING_EMP_CONFLICT - EMP cannot be enabled if channel interleaving, bank interleaving, or bank swizzle is enabled.</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x03</td>
<td>0x17</td>
<td>0x02</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
<tr>
<td>MEM_WARNING_EMP_NOT_ENABLED - Memory size is not power of two.</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x18</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_PERFORMANCE_ENABLED_BATTERY_LIFE_PREFERRED</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x17</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
<tr>
<td>MEM_WARNING_SPD_MODDLY_OUT_OF_RANGE</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x20</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_NODE_INTERLEAVING_NOT_ENABLED</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x21</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_CHANNEL_INTERLEAVING_NOT_ENABLED</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x22</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_BANK_INTERLEAVING_NOT_ENABLED</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x23</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_VOLTAGE_1_35_NOT_SUPPORTED</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x24</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
<tr>
<td>MEM_WARNING_INITIAL_DDR3VOLT_NONZERO</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x25</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
<tr>
<td>MEM_WARNING_NO_COMMONLY_SUPPORTED_VDDIO</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x04 0x01</td>
<td>0x26</td>
<td>0x00</td>
<td>Socket</td>
<td>DCT</td>
<td>Channel</td>
</tr>
<tr>
<td>MEM_WARNING_NO_COMMONLY_SUPPORTED_VDDIO</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### MEM_WARNING_MBIST_REQUIRED_FUNCTION_NOT_SUPPORTED

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x04</td>
<td>0x01</td>
<td>0x27</td>
<td>0x00</td>
<td>Socket 0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td></td>
</tr>
</tbody>
</table>

### MEM_WARNING_MBIST_INTERNAL_ERROR

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x04</td>
<td>0x01</td>
<td>0x28</td>
<td>0x00</td>
<td>Socket Channel Chipselect Subtest</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### MEM_WARNING_MBIST_DEFAULT_TEST_FAIL

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x04</td>
<td>0x01</td>
<td>0x29</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
</tbody>
</table>

### MEM_WARNING_AMP_SUPPORT_DETECTED_BUT_NOT_ENABLED

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x04</td>
<td>0x02</td>
<td>0x29</td>
<td>0x00</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
</tbody>
</table>

### MEM_WARNING_AMP_SELECTED_BUT_NOT_ENABLED

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
</table>

### Sub-Class: Processor

#### Sub-Class Fields

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>Field</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x00</td>
<td>0x21</td>
<td>0xRR</td>
<td>Data A</td>
<td>Data B</td>
</tr>
</tbody>
</table>

**CPU_EVENT_EXECUTION_CACHE_ALLOCATION_ERROR** - Execution cache allocation warning, Execution cache allocation error.

*RR — Allocation rule number that has been violated*

- 0x01 AGESA_CACHE_SIZE_REDUCED
- 0x02 AGESA_CACHE_REGIONS_ACROSS_1MB
- 0x03 AGESA_CACHE_REGIONS_ACROSS_4GB

*Data A — cache region index in parameter set that violated the rule*

*Data B — cache region start address*

*Data C — cache region size*

### CPU_WARNING_ADJUSTED_LEVELING_MODE

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>Field</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x00</td>
<td>0x22</td>
<td>0x00</td>
<td>Requested</td>
<td>Actual Level</td>
</tr>
</tbody>
</table>

**CPU_WARNING_ADJUSTED_LEVELING_MODE**

**CPU_EVENT_PM_PSTATE_OVERCURRENT**

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>Field</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x00</td>
<td>0x04</td>
<td>0x00</td>
<td>Socket Pstate</td>
<td>0x00000000</td>
</tr>
</tbody>
</table>

**CPU_EVENT_UNKNOWN_PROCESSOR_REVISION**

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>Field</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x05</td>
<td>0x01</td>
<td>0x00</td>
<td>Socket Raw CPUID</td>
<td>0x00000000</td>
</tr>
</tbody>
</table>
Sub-Class: AMD.Enable_STACK

<table>
<thead>
<tr>
<th>Sub-Class Fields</th>
<th>Sub-Class Data Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>ID</td>
<td>Event</td>
</tr>
<tr>
<td>0x08</td>
<td>0x02</td>
</tr>
</tbody>
</table>

CPU.EVENT_STACK_REENTRY - The stack has already been enabled and this is a redundant invocation of AMD_ENABLE_STACK. There is no event logged and no data values. The event sub-class is returned along with the status code.

C.5 AGESA_ERROR Class

Sub-Class: Memory

<table>
<thead>
<tr>
<th>Sub-Class Fields</th>
<th>Sub-Class Data Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>ID</td>
<td>Event</td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
</tr>
<tr>
<td>0x04</td>
<td>0x02</td>
</tr>
<tr>
<td>0x04</td>
<td>0x03</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
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<td>0x04</td>
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</tr>
<tr>
<td>0x04</td>
<td>0x06</td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
</tr>
</tbody>
</table>

MEM_ERROR_NO_DQS_POS_RD_WINDOW — No DQS Position window for RD DQS

MEM_ERROR_SMALL_DQS_POS_RD_WINDOW — Small DQS Position window for RD DQS

MEM_ERROR_NO_DQS_POS_WR_WINDOW

MEM_ERROR_SMALL_DQS_POS_WR_WINDOW

MEM_ERROR_DIMM_SPARING_NOT_ENABLED — DIMM sparing has not been enabled for an internal issues

MEM_ERROR_RCVR_EN_VALUE_TOO_LARGE — Receive Enable value is too large

MEM_ERROR_RCVR_EN_NO_PASSING_WINDOW

MEM_ERROR_DRAM_ENABLED_TIME_OUT
<table>
<thead>
<tr>
<th>Socket</th>
<th>DCT</th>
<th>Channel</th>
<th>Error Message</th>
<th>Error Code</th>
<th>Channel</th>
<th>Error Code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x04</td>
<td>0x01</td>
<td>0x07</td>
<td>MEM_ERROR_DCT_ACCESS_DONE_TIME_OUT</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td></td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
<td>0x08</td>
<td>MEM_ERROR_SEND_CTRL_WORD_TIME_OUT</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td></td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
<td>0x09</td>
<td>MEM_ERROR_PREF_DRAM_TRAIN_MODE_TIME_OUT</td>
<td>0x00000000</td>
<td>0x00000000</td>
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</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
<td>0x0A</td>
<td>MEM_ERROR_ENTER_SELF_REF_TIME_OUT</td>
<td>0x00000000</td>
<td>0x00000000</td>
<td></td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
<td>0x0B</td>
<td>MEM_ERROR_FREQ_CHG_IN_PROG_TIME_OUT</td>
<td>0x00000000</td>
<td>0x00000000</td>
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<tr>
<td>0x04</td>
<td>0x02</td>
<td>0x0A</td>
<td>MEM_ERROR_EXIT_SELF_REF_TIME_OUT</td>
<td>0x00000000</td>
<td>0x00000000</td>
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</tr>
<tr>
<td>0x04</td>
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<td>0x0C</td>
<td>MEM_ERROR_SEND_MRS_CMD_TIME_OUT</td>
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<tr>
<td>0x04</td>
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<td>0x0D</td>
<td>MEM_ERROR_SEND_ZQ_CMD_TIME_OUT</td>
<td>0x00000000</td>
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<td>0x0E</td>
<td>MEM_ERROR_DCT_EXTRA_ACCESS_DONE_TIME_OUT</td>
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<td>0x00000000</td>
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<tr>
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<td>0x01</td>
<td>0x0F</td>
<td>MEM_ERROR_MEM_CLR_BUSY_TIME_OUT</td>
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<td>0x00000000</td>
<td></td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
<td>0x10</td>
<td>MEM_ERROR_RCVR_EN_NO_PASSING_WINDOW_EQUAL_LIMIT</td>
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</tr>
<tr>
<td>ERRNO</td>
<td>ERROR_CODE</td>
<td>ERROR_MESSAGE</td>
<td>VALUE 1</td>
<td>VALUE 2</td>
<td>VALUE 3</td>
<td>VALUE 4</td>
</tr>
<tr>
<td>--------</td>
<td>-------------</td>
<td>----------------</td>
<td>----------</td>
<td>----------</td>
<td>----------</td>
<td>----------</td>
</tr>
<tr>
<td>0x04 0x01 0x12 0x00</td>
<td>Socket DCT Channel</td>
<td>MEM_ERROR_RCVR_EN_VALUE_TOO_LARGE_LIMIT_LESS_ONE</td>
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<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
<tr>
<td>0x04 0x01 0x13 0x00</td>
<td>Socket DCT Channel</td>
<td>MEM_ERROR_CHECKSUM_NV_SPDCHK_RESTR_ERROR</td>
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<td>0x00000000</td>
<td>0x00000000</td>
<td>0x00000000</td>
</tr>
<tr>
<td>0x04 0x01 0x15 0x00 0x00000000 0x00000000 0x00000000 0x00000000</td>
<td>MEM_ERROR_NO_CHIPSELECT</td>
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<tr>
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<td>Socket 0x00000000 0x00000000</td>
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<tr>
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<td>0x00000000 0x00000000 0x00000000 0x00000000</td>
<td>MEM_ERROR_HEAP_ALLOCATE_FOR_DATAEYE</td>
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<td></td>
<td></td>
<td></td>
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<tr>
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<td>Socket Channel Chipselect Subtest</td>
<td>MEM_ERROR_HEAP_ALLOCATE_FOR_DATAEYE</td>
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<tr>
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<td>0x00000000 0x00000000 0x00000000 0x00000000</td>
<td>MEM_ERROR_MBIST_TEST_FAIL</td>
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<td>MEM_ERROR_NBPSTATE_TRANSACTION_TIME_OUT</td>
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<tr>
<td>Incorrect Phy master channel setting.</td>
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<td>0x00000000 0x00000000 0x00000000 0x00000000</td>
<td>MEM_ERROR_NO_2D_WRDAT_WINDOW</td>
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<tr>
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<td>0x00000000 0x00000000 0x00000000 0x00000000</td>
<td>MEM_ERROR_NO_2D_WRDAT_HEIGHT</td>
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<td></td>
<td></td>
<td></td>
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<tr>
<td>0x04 0x0F 0x04 0x00</td>
<td>Node DCT Channel 0x00000000</td>
<td>MEM_ERROR_2D_WRDAT_ERROR</td>
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<tr>
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<td>0x00000000 0x00000000 0x00000000 0x00000000</td>
<td>MEM_ERROR_INVALID_2D_WRDAT_VALUE</td>
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<tr>
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<td>Node DCT Channel 0x00000000</td>
<td>MEM_ERROR_2D_WRDAT_VREF_MARGIN_ERROR</td>
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<tr>
<td>0x04 0x12 0x04 0x00</td>
<td>Node DCT Channel 0x00000000</td>
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### MEM_ERROR_PMU_TRAINING

<table>
<thead>
<tr>
<th>Sub-Class Fields</th>
<th>Sub-Class Data Values</th>
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</thead>
<tbody>
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<td>Event</td>
</tr>
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<td>0x10</td>
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### MEM_ERROR_HEAP_ALLOCATE_FOR_PMU_SRAM_MSG_BLOCK

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<th>Sub-Class Data Values</th>
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<tbody>
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<td>Event</td>
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### MEM_ERROR_HEAP_DEALLOCATE_FOR_PMU_SRAM_MSG_BLOCK

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### MEM_ERROR_HEAP_LOCATE_FOR_PMU_SRAM_MSG_BLOCK

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## Sub-Class: Processor

### Sub-Class Fields | Sub-Class Data Values

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<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
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</thead>
<tbody>
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</table>

CPU_ERROR_BRANDID_HEAP_NOT_AVAILABLE - No heap is allocated for BrandId structure

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<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
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<tbody>
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CPU_ERROR_MICRO_CODE_PATCH_IS_NOT_LOADED- Unable to load micro code patch

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<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
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<tbody>
<tr>
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<td>0x04</td>
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<td>0x00000000</td>
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</table>

CPU_ERROR_PSTATE_HEAP_NOT_AVAILABLE - No heap is allocated for the Pstate structure

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<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x03</td>
<td>0x04</td>
<td>0x00</td>
<td>Socket</td>
<td>Index</td>
<td>0x00000000</td>
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</table>

CPU_ERROR_PM_NB_PSTATE_MISMATCH- NB P-state indicated by Index was disabled due to mismatch between processors.

<table>
<thead>
<tr>
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<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
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<tbody>
<tr>
<td>0x08</td>
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<td>0x21</td>
<td>0xRR</td>
<td>Data A</td>
<td>Data B</td>
<td>Data C</td>
<td>0x00000000</td>
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CPU_EVENT_EXECUTION_CACHE_ALLOCATION_ERROR - Execution cache allocation warning, Execution cache allocation error.

RR — Allocation rule number that has been violated
0x04 AGESA_REGION_NOTAligned_ON_BOUNDARY
0x05 AGESA_START_ADDRESS_LESS_D0000
0x06 AGESA_THREE_CACHE_REGIONS_ABOVE_1MB
0x07 AGESA_DEALLOCATE_CACHE_REGIONS

Data A — cache region index in parameter set that violated the rule
Data B — cache region start address
Data C — cache region size

<table>
<thead>
<tr>
<th>ID</th>
<th>Event</th>
<th>Fcn</th>
<th>Sub</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
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<tbody>
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### CPU_EVENT_SCS_INITIALIZATION_ERROR

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<th>0x00000000</th>
<th>0x00000000</th>
<th>0x00000000</th>
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</table>

**CPU_EVENT_SCS_INITIALIZATION_ERROR** - Heap entry missing

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**CPU_EVENT_SCS_INITIALIZATION_ERROR** - Buffer Empty

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**CPU_EVENT_SCS_INITIALIZATION_ERROR** - Weights Mismatch

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**CPU_EVENT_BTC_INITIALIZATION_ERROR** - there was an error during setting the Branch Trace Control (BTC) VID adjustment.

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<th>0x04</th>
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<th>Input Limit</th>
<th>PState Freq</th>
<th>original/new</th>
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**CPU_ERROR_PM_ALL_PSTATE_OVER_FREQUENCY_LIMIT** - all P-states are over the input frequency limit. The minimum P-state frequency will be used.

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<th>0x04</th>
<th>0x00</th>
<th>Input Limit</th>
<th>PState Freq</th>
<th>Boost Pstate#</th>
<th>SW Pstate</th>
<th>original/new</th>
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**CPU_EVENT_PM_PSTATE_FREQUENCY_LIMIT** - successful

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### Sub-Class: GNB

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<th>Sub-Class Data Values</th>
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</thead>
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**GNB_EVENT_INVALID_CONFIGURATION** — Invalid user input for configuration.

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**GNB_EVENT_INVALID_PCIE_TOPOLOGY_CONFIGURATION** — Invalid user input for configuration.

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**GNB_EVENT_INVALID_PCIE_PORT_CONFIGURATION** — Invalid user input for configuration.

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**GNB_EVENT_INVALID_DDI_LINK_CONFIGURATION** — Invalid user input for configuration.

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<th>0x00000000</th>
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**GNB_EVENT_INVALID_LINK_WIDTH_CONFIGURATION** — Invalid user input for configuration.
Appendix C Logged Error Messages

AGESA™--Arch2008

44065  Rev. 3.02  March 2015

AGESA™--Arch2008

C.6 AGESA_CRITICAL Class

Sub-Class: Memory

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<thead>
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<td>MEM_ERROR_UNSUPPORTED_DIMM_CONFIG</td>
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C.7 AGESA_FATAL Class

Sub-Class: Memory

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<td>Event</td>
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<tr>
<td>0x04</td>
<td>0x01</td>
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<tr>
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<td>MEM_ERROR_MINIMUM_MODE — Running in minimum mode.</td>
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<td>0x01</td>
</tr>
</tbody>
</table>
MEM_ERROR_MODULE_TYPE_MISMATCH_DIMM — DIMM modules are miss-matched.

0x04 0x01 0x1C 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_NO_DIMM_FOUND_ON_SYSTEM — No DIMMs have been found.

0x04 0x01 0x1D 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_MISMATCH_DIMM_CLOCKS — DIMM clocks miss-matched.

0x04 0x01 0x1E 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_NO_CYC_TIME — No cycle time found.

0x04 0x01 0x1F 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_ALLOCATE_DYN_STORING_OF_TRAINED_TIMINGS

0x04 0x02 0x1F 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_ALLOCATE_FOR_DCT_STRUCT_AND_CH_DEF_STRUCT

0x04 0x03 0x1F 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_ALLOCATE_FOR_REMOTE_TRAINING_ENV

0x04 0x04 0x1F 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_ALLOCATE_FOR_SPD

0x04 0x05 0x1F 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_ALLOCATE_FOR_RECEIVED_DATA

0x04 0x06 0x1F 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_ALLOCATE_FOR_S3_SPECIAL_CASE_REGISTERS

0x04 0x07 0x1F 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_ALLOCATE_FOR_TRAINING_DATA

0x04 0x02 0x23 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_ALLOCATE_FOR_IDENTIFY_DIMM_MEM_NB_BLOCK

0x04 0x0B 0x1F 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_ALLOCATE_FOR_2D

0x04 0x0C 0x1F 0x00 0x00000000 0x00000000 0x00000000 0x00000000

MEM_ERROR_HEAP_DEALLOCATE_FOR_2D

Sub-Class: Processor

<table>
<thead>
<tr>
<th>Sub-Class Fields</th>
<th>Sub-Class Data Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>ID</td>
<td>Event</td>
</tr>
<tr>
<td>0x08</td>
<td>0x01</td>
</tr>
</tbody>
</table>

CPU_EVENT_PM_ALL_PSTATES_OVERCURRENT - All PStates exceeded the motherboard current limit on specified socket
Sub-Class: AMD_ENABLE_STACK

<table>
<thead>
<tr>
<th>Sub-Class Fields</th>
<th>Sub-Class Data Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>ID</td>
<td>Event</td>
</tr>
<tr>
<td>0x08</td>
<td>0x01</td>
</tr>
<tr>
<td>0x03</td>
<td>0x05</td>
</tr>
</tbody>
</table>

- **CPU_EVENT_UNKNOWN_PROCESSOR_FAMILY** - Stack cannot be enabled due to unknown processor family. There is no event logged and no data values. The sub-class is returned along with the status code.

- **CPU_EVENT_CORE_NOT_IDENTIFIED** - Stack cannot be enabled due to core numbering issue, such being unable to determine compute unit primary status. There is no event logged and no data values. The sub-class is returned along with the status code.
Appendix D  Memory Details

Refer to the internal documentation for the latest and most detailed information ("Internal Documentation" on page 26).

D.1  Modifying or Correcting SPD values

The memory code uses the initializer function to load the SPD data for all of the memory DIMMs in the system prior to the entry for the main memory configuration process. Once the initializer completes, control is returned to the host environment. At this point in time, modifications or corrections can be made to the SPD data that will be used by the main configuration process. Be careful to maintain a valid checksum for the DIMM data.

D.2  Specialized Platform Files

The AGESA™ software attempts to automatically identify timing parameters. However, variations in the motherboard design are unpredictable. The AGESA™ software includes small procedures that contain platform-specific settings that may need to be modified or replaced for certain motherboards. The AMD Reference Design Kit (ARDK) motherboards follow the AMD platform design guidelines and the default platform description procedures included in the AGESA™ software use timing values that match these design guidelines. Motherboards that do not conform to the AMD design guidelines may need to supply replacement procedures.

The AGESA™ memory software segregates procedures for memory timing by each type of memory (Registered or Unbuffered) and technology (DDR2 or DDR3). These are accessed through an array of procedure pointers contained in a MEM_DATA_STRUCT structure element:

```c
AGESA_STATUS (*GetPlatformCfg[]) (  
    MEM_DATA_STRUCT *MemData,  
    UINT8 SocketID,  
    CH_DEF_STRUCT *CurrentChannel;
```

The host environment must replace the default procedure pointers with pointers to their private procedures that conform to the following definition.
MemAGetPsCfgRHy2
MemAGetPsCfgRHy3

Internal routines to obtain platform-specific address and command settings for DIMM configurations.

**Prototype**

```c
AGESA_STATUS
MemAGetPsCfgRHy3 (  
    IN OUT MEM_DATA_STRUCT *MemData,
    IN    UINT8       SocketID,
    IN OUT CH_DEF_STRUCT *CurrentChannel);
```

**Parameters**

- **MemData**
  Pointer to a data structure containing the memory information.

- **SocketId**
  The socket number for the memory presently being configured.

- **CurrentChannel**
  The memory channel number for the memory presently being configured.

**Related Definitions**

- **MEM_DATA_STRUCT**
- **CH_DEF_STRUCT**

  These are the same data structures used by the main memory routine. See “AmdInitPost” on page 115 for structure details.

**Description**

This procedure is called from the AGESA™ software main code to determine platform-specific memory timing values. The host environment may choose to replace this function with their own version to adjust timing parameters specific to the board. This procedure, or its replacement, has the entire content of the MEM_DATA_STRUCT available for reference input. At a minimum, the procedure needs to set or adjust the following timing elements in that structure:

- **DCTData->SlowMode**
  Indicates if Slow Access mode is supported (also known as 1T or 2T timing mode)

- **DCTData->OdcCtl**
  Output driver control value or “drive strength”

- **DCTData->AddrTmg**
  Address/data timing values
Dependencies

The platform must conform to the AMD Platform Design Guide and approximate the AMD reference design board for the default functions to perform properly. If the platform deviates from the reference platform characteristics, then the host environment must tailor this function to the specific needs of the platform and replace the function pointer in the parameter block before making the call to the main memory function.

Status Codes Returned

AGESA_SUCCESS The function has completed successfully.
AGESA_ERROR
D.3 Advanced DQS Training

Note: “BLDCFG_DQS_TRAINING_CONTROL” on page 205 — False means that the platform has stored values previously and intends to use them. If the stored values are not present (or not valid) then active training will be used.

D.4 On-Line Spares

This is a mechanism in which a DIMM of memory is reserved for use as a “spare.” When ECC errors reach a threshold level in a single DIMM, the active DIMM is swapped out of use and the “spare” DIMM is swapped into use in its place. This swap is done by the hardware and is near instantaneous. Further details can be found in the BIOS and Kernel Developers Guide (BKDG).

To activate the feature, refer to the build option “BLDOPT_REMOVE_ONLINE_SPARE_SUPPORT” on page 183, and the build configuration element “BLDCFG_ONLINE_SPARE” on page 199.

D.5 Platform Specific Override

The Platform Specific Override Interface provides additional, expert level, customizations to the AGESA™ Memory code.

The Platform Specific Override customizations are made using the default table located in the platform options C file. Each platform options file contains a default override table called DefaultPlatformMemoryConfiguration. This table may be modified or extended to customize for your platform. The table may also be replaced by updating the parameter with the pointer to the replacement table when calling AmdInitPost, see “PlatformMemoryConfiguration” on page 121.

Customizations are made in the table using a robust set of macros. These are presented below in three groups: basic macros, conditional macros, and table macros. Any memory settings which are not customized using the macros will be initialized using recommended settings.

D.5.1 Expert Overrides

The following macros provide expert platform specific customizations.
**MOTHER_BOARD_LAYERS**

**Prototype**

\[
\text{MOTHER BOARD LAYERS (Layers)}
\]

**Parameters**

\[
\text{Layers}
\]

Customize the number of board layers for the system.

- LAYERS_4 - The system has 4 board layers (default).
- LAYERS_6 - The system has 6 board layers.

**Description**

This override allows correct customization of memory settings which vary based on the number of board layers. Address, Command, and Drive Strength memory settings may be affected.
MEMCLK_DIS_MAP

Prototype

MEMCLK_DIS_MAP (SocketID, ChannelID, Bit0Map, Bit1Map, Bit2Map, Bit3Map,
 Bit4Map, Bit5Map, Bit6Map, Bit7Map)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

  SOCKET0  SOCKET5
  SOCKET1  SOCKET6
  SOCKET2  SOCKET7
  SOCKET3  ANY_SOCKET
  SOCKET4

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

  CHA  CHD
  CHB  ANY_CHANNEL
  CHC

These values may be combined as follows: CHA + CHC

Bit[7:0]Map

Indicating the memory clock pins connect to which memory chip-selects / ranks.

Description

The memory clock pins are identified based on BKDG definition of MEM_CLK_DIS bitmap. Disabling unused MemClk may save power.

For example, BKDG definition of MEM_CLK_DIS bitmap is like below:

<table>
<thead>
<tr>
<th>Bit</th>
<th>pin name</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>M[B,A]_CLK_H/L[0]</td>
</tr>
<tr>
<td>1</td>
<td>M[B,A]_CLK_H/L[1]</td>
</tr>
<tr>
<td>2</td>
<td>M[B,A]_CLK_H/L[2]</td>
</tr>
<tr>
<td>3</td>
<td>M[B,A]_CLK_H/L[3]</td>
</tr>
<tr>
<td>4</td>
<td>M[B,A]_CLK_H/L[4]</td>
</tr>
<tr>
<td>5</td>
<td>M[B,A]_CLK_H/L[5]</td>
</tr>
<tr>
<td>6</td>
<td>M[B,A]_CLK_H/L[6]</td>
</tr>
<tr>
<td>7</td>
<td>M[B,A]_CLK_H/L[7]</td>
</tr>
</tbody>
</table>
And platform has the following routing:

CS0  $M_{[B,A]}_\text{CLK}_H/L[4]$
CS1  $M_{[B,A]}_\text{CLK}_H/L[2]$
CS2  $M_{[B,A]}_\text{CLK}_H/L[3]$
CS3  $M_{[B,A]}_\text{CLK}_H/L[5]$

Then platform can specify the following macro:

MEMCLK_DIS_MAP(ANY_SOCKET, ANY_CHANNEL, 0x00, 0x00, 0x02, 0x04, 0x01, 0x08, 0x00, 0x00)
ON_DIMM_THERMAL_CONTROL

Prototype

ON_DIMM_THERMAL_CONTROL (SocketID, ChannelID, EnableDisable)

Parameters

SocketID

A mask indicating the physical processor socket or sockets. Possible values are:

- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

EnableDisable

Indicate whether to enable on DIMM thermal sensor support.

- ENABLE - Enable the feature on DIMMs for the channel specified.
- DISABLE - Disable the feature on DIMMs for the channel specified.

Description

Support for on DIMM thermal sensors can be overridden.
CKE_TRI_MAP

Prototype

CKE_TRI_MAP (SocketID, ChannelID, Bit0Map, Bit1Map, Bit2Map, Bit3Map)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

Bit[3:0]Map

Indicating CKE signals connect to which memory chip-selects/ranks.

Description

The CKE pins are identified based on BKDG definition of CKETri bitmap. Tri-state of unused CKE may save power.
ODT_TRI_MAP

Prototype

ODT_TRI_MAP (SocketID, ChannelID, Bit0Map, Bit1Map, Bit2Map, Bit3Map)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

Bit[3:0]Map

Indicating ODT signals connect to which memory chip-selects/ranks.

Description

The ODT pins are identified based on BKDG definition of ODTTri bitmap. Tri-state of unused ODT pins may save power.
CS_TRI_MAP

Prototype

CS_TRI_MAP (SocketID, ChannelID, Bit0Map, Bit1Map, Bit2Map, Bit3Map, Bit4Map, Bit5Map, Bit6Map, Bit7Map)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:
- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:
- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

Bit[7:0]Map

Indicating chip selects signals connect to which memory chip-selects/ranks.

Description

The chip select pins are identified based on BKDG definition of ChipSelTri bitmap. Tri-state of unused chip selects signals may save power.
NUMBER_OF_DIMMS_SUPPORTED

Prototype

NUMBER_OF_DIMMS_SUPPORTED (SocketID, ChannelID, NumberOfDimmSlotsPerChannel)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

- CHA
- CHB
- CHC

These values may be combined as follows: CHA + CHC

NumberOfDimmSlotsPerChannel

Specifies the number of DIMM slots per channel.

Description

This macro usually exists in the platform options file to specify the number of DIMM slots per channel in socket/channel basis. On a platform with soldered down DRAM only, SODIMM only, or soldered-down DRAM plus SODIMM, this macro will be used to specify total number of DIMMs supported on a channel, including slotted and soldered down DIMMs.
NUMBER_OF_SOLDERED_DOWN_DIMMS_SUPPORTED

Prototype

NUMBER_OF_SOLDERED_DOWN_DIMMS_SUPPORTED (SocketID, ChannelID, NumberOfSolderedDownDimmsPerChannel)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:
- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:
- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

NumberOfSolderedDownDimmsPerChannel

Specifies the number of soldered down DIMMs per channel.

Description

This macro is used to specify the number of soldered-down DIMMs per channel in socket/channel basis. This macro is similar to SOLDIERED_DOWN_SODIMM_TYPE macro, however, it explicitly tells AGESA how many soldered-down DIMMs are on the board. It is recommended that this macro be used instead of SOLDIERED_DOWN_SODIMM_TYPE macro when the board design is soldered-down DRAM(s) only or solder-down DRAM(s) plus SODIMM(s) configuration.
NUMBER_OF_CHIP_SELECTS_SUPPORTED

Prototype

NUMBER_OF_CHIP_SELECTS_SUPPORTED (SocketID, ChannelID, NumberOfChipSelectsPerChannel)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

NumberOfChipSelectsPerChannel

Specifies the number of chip selects per channel.

Description

This macro is used to specify the number of chip selects per channel in socket/channel basis.
NUMBER_OF_CHANNELS_SUPPORTED

Prototype

NUMBER_OF_CHANNELS_SUPPORTED (SocketID, NumberOfChannelsPerSocket)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

NumberOfChannelsPerSocket

Specifies the number of channels per socket.

Description

This macro is used to specify the numbers of channels on socket SocketID.
OVERRIDE_DDR_BUS_SPEED

Prototype

OVERRIDE_DDR_BUS_SPEED (SocketID, ChannelID, TimingMode, BusSpeed)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

TimingMode

Indicating which timing mode that applies the desired bus speed. Possible values are: TIMING_MODE_LIMITED, TIMING_MODE_SPECIFIC

BusSpeed

Frequencies to apply change. Possible values are:

- DDR667_FREQUENCY
- DDR800_FREQUENCY
- DDR1066_FREQUENCY
- DDR1333_FREQUENCY
- DDR1600_FREQUENCY
- DDR1866_FREQUENCY
- DDR2100_FREQUENCY
- DDR2133_FREQUENCY
- DDR2400_FREQUENCY

Description

This macro is used to limit/force the memory speed of channel ChannelID on socket SocketID.
DRAM_TECHNOLOGY

Prototype

DRAM_TECHNOLOGY (SocketID, MemTechType)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:
- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

MemTechType

Indicating the DRAM technology. Possible values are:
- DDR3_TECHNOLOGY
- DDR2_TECHNOLOGY

Description

This macro specifies DRAM technology type of socket SocketID.
WRITE_LEVELING_SEED

Prototype

WRITE_LEVELING_SEED (SocketID, ChannelID, DimmID, Byte0Seed, Byte1Seed, Byte2Seed, Byte3Seed, Byte4Seed, Byte5Seed, Byte6Seed, Byte7Seed, ByteEccSeed)

Parameters

SocketID

A mask indicating the physical processor socket or sockets. Possible values are:

SOCKET0  SOCKET5
SOCKET1  SOCKET6
SOCKET2  SOCKET7
SOCKET3  ANY_SOCKET
SOCKET4

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

CHA  CHD
CHB  ANY_CHANNEL
CHC

These values may be combined as follows: CHA + CHC

DimmID

A mask indicates the physical channel. Possible values are:

DIMM0  DIMM3
DIMM1  ALL_DIMMS
DIMM2

These values may be combined as follows: DIMM0 + DIMM1

Byte[7:0]Seed/ByteEccSeed

8 bits seed values for each byte lanes.

Description

This macro specifies the write leveling seed values for a specific DIMM on a channel of a socket. The default behavior when this macro is not populated: Defined by BKDG.
HW_RXEN_SEED

Prototype

HW_RXEN_SEED (SocketID, ChannelID, DimmID, Byte0Seed, Byte1Seed, Byte2Seed, Byte3Seed, Byte4Seed, Byte5Seed, Byte6Seed, Byte7Seed, ByteEccSeed)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

DimmID

A mask indicates the physical channel. Possible values are:

- DIMM0
- DIMM1
- DIMM2
- DIMM3
- ALL_DIMMS

These values may be combined as follows: DIMM0 + DIMM1

Byte[7:0]Seed/ByteEccSeed

8 bits seed values for each byte lanes.

Description

This macro specifies the HW RXEN training seed values for a specific DIMM on a channel of a socket. The default behavior when this macro is not populated: Defined by BKDG.
NO_LRDIMM_CS67_ROUTING

Prototype

NO_LRDIMM_CS67_ROUTING (SocketID, ChannelID)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

Description

When this macro is stated, it tells AGESA that there is no CS6 and CS7 routing for LRDIMM.

The default behavior when this macro is not populated: AGESA supports CS6 and CS7 routing for LRDIMM.
SOLEDERED_DOWN_SODIMM_TYPE

Prototype

SOLEDERED_DOWN_SODIMM_TYPE (SocketID, ChannelID)

Parameters

SocketID

Mask indicating the physical processor socket or sockets. Possible values are:

<table>
<thead>
<tr>
<th>SocketID</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>SOCKET0</td>
<td>SOCKET5</td>
</tr>
<tr>
<td>SOCKET1</td>
<td>SOCKET6</td>
</tr>
<tr>
<td>SOCKET2</td>
<td>SOCKET7</td>
</tr>
<tr>
<td>SOCKET3</td>
<td>ANY_SOCKET</td>
</tr>
<tr>
<td>SOCKET4</td>
<td></td>
</tr>
</tbody>
</table>

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelID

A mask indicates the physical channel. Possible values are:

<table>
<thead>
<tr>
<th>ChannelID</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>CHA</td>
<td>CHD</td>
</tr>
<tr>
<td>CHB</td>
<td>ANY_CHANNEL</td>
</tr>
<tr>
<td>CHC</td>
<td></td>
</tr>
</tbody>
</table>

These values may be combined as follows: CHA + CHC

Description

When this macro is stated, it tells AGESA that current platform is soldered down SO-DIMM configuration. The default behavior when this macro is not populated: AGESA assumes that no soldered down SO-DIMMs supported.
**MIN_RD_WR_DATAEYE_WIDTH**

**Prototype**

MIN_RD_WR_DATAEYE_WIDTH (SocketID, ChannelID, MinRdDataeyeWidth, MinWrDataeyeWidth)

**Parameters**

*SocketID*

Mask indicating the physical processor socket or sockets. Possible values are:
- SOCKET0
- SOCKET1
- SOCKET2
- SOCKET3
- SOCKET4
- SOCKET5
- SOCKET6
- SOCKET7
- ANY_SOCKET

These values may be combined as follows: SOCKET0 + SOCKET2

*ChannelID*

A mask indicates the physical channel. Possible values are:
- CHA
- CHB
- CHC
- CHD
- ANY_CHANNEL

These values may be combined as follows: CHA + CHC

*MinRdDataeyeWidth*

A 8 bits value for minimum read data eye width.

*MinWrDataeyeWidth*

A 8 bits value for minimum write data eye width.

**Description**

This macro specifies minimum read and write date eye width for a channel of a socket. The default behavior when this macro is not populated: AGESA minimum width for DQS RD/QR training is 3 delay steps wide.
CPU_FAMILY_TO_OVERRIDE

Prototype

CPU_FAMILY_TO_OVERRIDE (CpuFamilyRevision)

Parameters

CpuFamilyRevision

A 32 bit CPUID value that indicates the CPU family and revision.

Description

This macro is a special macro, it allows customers stating CPU family specific platform memory overriding macros.

The platform memory overriding macros follow this macro will be treated as CPU family specific macros. For those platform memory overriding macros not follow this macro will be treated as global macros, that means, they are applied to all CPU families except for the CPU family that CPU_FAMILY_TO_OVERRIDE macro specifies.

Example:

// Global PSO for the CPU families which no exclusive PSO stated below
ODT_TRI_MAP(ANY_SOCKET, ANY_CHANNEL, 0x11, 0x22, 0x33, 0x44),

// Exclusive PSO macro for CPU family (0x00600F10)
CPU_FAMILY_TO_OVERRIDE (0x00600F10),
ODT_TRI_MAP(ANY_SOCKET, ANY_CHANNEL, 0x99, 0x88, 0x77, 0x66),

// Exclusive PSO macro for CPU family (0x00500F20)
CPU_FAMILY_TO_OVERRIDE (0x00500F20),
ODT_TRI_MAP(ANY_SOCKET, ANY_CHANNEL, 0x68, 0x79, 0x8A, 0x9B),

Dependencies

Not all of platform memory override macros are CPU family dependent, NUMBER_OF_DIMMS_SUPPORTED macro, for example, it is related to boards design.

Currently, the available platform memory override macros can be supported in CPU family/revision basis are:

MEMCLK_DIS_MAP, CKE_TRI_MAP,
ODT_TRI_MAP, CS_TRI_MAP,
OVERRIDE_DDR_BUS_SPEED, WRITE_LEVELING_SEED,
HW_RXEN_SEED, MIN_RD_WR_DATAEYE_WIDTH
D.5.2 Conditional Overrides

The following macros provide conditional expert platform specific customizations, primarily for processor families for which table driven overrides are not available.

The following parameters can currently be overridden by this interface:

- "Dram ODT
- "Memory Address Timing
- "Dram Drive Strength
- "Slew Rate
- "DDR Frequency as a function of DIMM voltage

These overrides may be made conditional on the platform characteristics below, by preceding the configuration action macro with conditionals macros. A configuration action macro closes all conditionals preceding it.

- "Processor Socket
- "Memory Channel
- "Dimm Number
- "Frequency
- "Dimm population
- "Spd Contents

The macros below are divided into macros for specifying the conditions and macros for indicating the configuration actions.

D.5.2.1 Condition and Test Macros
CONDITION_AND

Prototype

CONDITION_AND

Parameters

<none>

Description

This macro opens a condition block. The conditions that follow will be logically ANDed together when evaluating whether to apply the associated actions. Multiple CONDITION_AND macros can be used in succession for a particular group of ACTION items. In this case, there is an implied OR of the separate CONDITION_AND blocks.
COND_LOC

Prototype

COND_LOC (SocketMsk, ChannelMsk, DimmMsk)

Parameters

SocketMsk

Mask indicating the physical processor socket or sockets. Possible values are:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SOCKET0</td>
<td>SOCKET5</td>
</tr>
<tr>
<td>SOCKET1</td>
<td>SOCKET6</td>
</tr>
<tr>
<td>SOCKET2</td>
<td>SOCKET7</td>
</tr>
<tr>
<td>SOCKET3</td>
<td>ANY_SOCKET</td>
</tr>
<tr>
<td>SOCKET4</td>
<td></td>
</tr>
</tbody>
</table>

These values may be combined as follows: SOCKET0 + SOCKET2

ChannelMsk

A mask indicates the physical channel. Possible values are:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CHA</td>
<td>CHD</td>
</tr>
<tr>
<td>CHB</td>
<td>ANY_CHANNEL</td>
</tr>
<tr>
<td>CHC</td>
<td></td>
</tr>
</tbody>
</table>

These values may be combined as follows: CHA + CHC

DimmMsk

A mask of the DIMMS to with the condition applies. Possible values are:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>DIMM0</td>
<td>DIMM3</td>
</tr>
<tr>
<td>DIMM1</td>
<td>ALL_DIMM</td>
</tr>
<tr>
<td>DIMM2</td>
<td></td>
</tr>
</tbody>
</table>

These values may be combined as follows: DIMM0 + DIMM3

Description

This specifies the Socket/Channel/Dimm to apply the changes. There can only be one COND_LOC block in each CONDITION_AND block and it must be the first entry in the block. The action entries defined in this block will be ignored unless the criteria in this field is met. However, certain actions may not be performed at the channel or dimm scope, and therefore will not be filtered on this basis. For instance, Address timing is programmed per channel and therefore will be applied as long as the socket and channel match. The Dimm field will be ignored.
COND_SPD

Prototype

COND_SPD (Byte, Mask, Value)

Parameters

Byte
The byte index of the spd value

Mask
The bit mask of the specific spd field

Value
The SPD value to match in this field.

Description

This entry tests a specific SPD value. As many of these as are desired can be grouped together in a CONDITION_AND block.

D.5.2.2 Conditional Action Macros
ACTION_ODT

Prototype

ACTION_ODT (Frequency, Dimms, QrDimms, DramOdt, QR_DramOdt, DramDynOdt)

Parameters

Frequency

Mask of frequencies to apply change. Possible values are:

- DDR400
- DDR533
- DDR667
- DDR800
- DDR1066
- ANY_SPEED

These values can be combined as follows: DDR400 + DDR533 + DDR667

Dimms

Number of DIMMs in the channel. Possible values are:

- NO_DIMM
- ONE_DIMM
- TWO_DIMM
- THREE_DIMM
- FOUR_DIMM
- ANY_DIM
- ANY_NUM

These values can be combined as follows: ONE_DIMM + TWO_DIMM

QrDimms

Number of quad rank DIMMs in the channel. Possible values are same as above.

DramOdt

Dram ODT (Rtt_Nom) as specified in the JEDEC DDR3 specification to be applied.

QR_DramOdt

Dram ODT (Rtt_Nom) as specified in the JEDEC DDR3 specification to be applied to quad rank dims

DramDynOdt

Dram Write ODT (Rtt_Wr) as specified in the JEDEC DDR3 specification to be applied
ACTION_ADDRTMG

Prototype

ACTION_ADDRTMG (Frequency, DimmConfig, AddrTmg)

Parameters

Frequency

Mask of frequencies to apply change. Possible values are:

- DDR400
- DDR533
- DDR667
- DDR800
- DDR1066
- DDR1333
- DDR1600
- DDR1866
- ANY_SPEED

These values can be combined as follows: DDR400 + DDR533 + DDR667

DimmConfig

Mask indicating DIMM configuration. Possible values are:

- ANY_
- SR_DIMM0
- SR_DIMM1
- SR_DIMM2
- SR_DIMM3
- DR_DIMM0
- DR_DIMM1
- DR_DIMM2
- DR_DIMM3
- QR_DIMM0
- QR_DIMM1
- QR_DIMM2
- QR_DIMM3

These values can be combined as follows: QR_DIMM0 + ANY_DIMM1

AddrTmg

32 bit address timing value to apply.
**ACTION_ODCCTRL**

**Prototype**

ACTION_ODCCTRL (Frequency, DimmConfig, OdcCtrl)

**Parameters**

*Frequency*

Mask of frequencies to apply change. Possible values are:

- DDR400
- DDR1333
- DDR533
- DDR1600
- DDR667
- DDR1866
- DDR800
- ANY_SPEED
- DDR1066

These values can be combined as follows: DDR400 + DDR533 + DDR667

*DimmConfig*

Mask indicating DIMM configuration. Possible values are:

- ANY
- DR_DIMM1
- QR_DIMM3
- SR_DIMM0
- DR_DIMM2
- ANY_DIMM0
- SR_DIMM1
- DR_DIMM3
- ANY_DIMM1
- SR_DIMM2
- QR_DIMM0
- ANY_DIMM2
- SR_DIMM3
- QR_DIMM1
- ANY_DIMM3
- DR_DIMM0
- QR_DIMM2

These values can be combined as follows: QR_DIMM0 + ANY_DIMM1

*OdcCtrl*

32 bit output driver compensation control value to apply.
ACTION_SLEWRATE

Prototype

ACTION_SLEWRATE (Frequency, DimmConfig, SlewRate)

Parameters

Frequency

Mask of frequencies to apply change. Possible values are:

- DDR400
- DDR533
- DDR667
- DDR800
- DDR1066
- DDR1333
- DDR1600
- DDR1866
- ANY_SPEED

These values can be combined as follows: DDR400 + DDR533 + DDR667

DimmConfig

Mask indicating DIMM configuration. Possible values are:

- ANY_
- SR_DIMM0
- SR_DIMM1
- SR_DIMM2
- SR_DIMM3
- DR_DIMM0
- DR_DIMM1
- DR_DIMM2
- DR_DIMM3
- QR_DIMM0
- QR_DIMM1
- QR_DIMM2
- QR_DIMM3
- ANY_DIMM0
- ANY_DIMM1
- ANY_DIMM2
- ANY_DIMM3

These values can be combined as follows: QR_DIMM0 + ANY_DIMM1

SlewRate

32 bit slew rate value to apply.
ACTION_SPEEDLIMIT

Prototype

ACTION_SPEEDLIMIT (DimmConfig, Dimms, Speedlimit15, Speedlimit135, SpeedLimit125)

Parameters

DimmConfig

Mask indicating DIMM configuration. Possible values are:

- ANY_DR_DIMM1
- SR_DIMM0
- SR_DIMM1
- SR_DIMM2
- SR_DIMM3
- DR_DIMM0

These values can be combined as follows: QR_DIMM0 + ANY_DIMM1

Dimms

Mask indicating number of DIMMs in the channel. Possible values are:

- NO_DIMM
- ONE_DIMM
- TWO_DIMM

These values can be combined as follows: ONE_DIMM + TWO_DIMM

Speedlimit15/Speedlimit135/Speedlimit125

Frequencies to apply change. Possible values are:

- DDR667_FREQUENCY
- DDR800_FREQUENCY
- DDR1066_FREQUENCY
- DDR1333_FREQUENCY
- DDR1600_FREQUENCY
- DDR1866_FREQUENCY
- DDR2100_FREQUENCY
- DDR2133_FREQUENCY
- DDR2400_FREQUENCY

D.5.3 Table Overrides

The following macros provide table driven expert platform specific customizations. Table driven overrides are the preferred mechanism over conditional macros for most processor families.

Table override macros are divided into configuration macros, which specify the platform criteria, and setting override macros, which provide specific setting overrides.

D.5.3.1 Configuration Macros
**TBLDRV_CONFIG_TO_OVERRIDE**

**Prototype**

\[ \text{TBLDRV_CONFIG_TO_OVERRIDE (DimmPerCH, Frequency, DimmVolt, DimmConfig)} \]

**Parameters**

- **DimmPerCH**
  
  Number of DIMM slots in a channel.

- **Frequency**
  
  Mask of frequencies to apply change. Possible values are:
  
  - DDR400
  - DDR533
  - DDR667
  - DDR800
  - DDR1066
  
  These values can be combined as follows: DDR400 + DDR533 + DDR667

- **DimmVolt**
  
  Mask of voltage to apply change. Possible values are:
  
  - VOLT1_5_
  - VOLT1_35_
  - VOLT1_25_
  - VOLT_ANY_
  
  These values can be combined as follows: VOLT1_5_ + VOLT1_35_

- **DimmConfig**
  
  Mask indicating DIMM configuration. Possible values are:
  
  - ANY_
  - DR_DIMM0
  - SR_DIMM0
  - SR_DIMM1
  - SR_DIMM2
  - SR_DIMM3
  - DR_DIMM0
  - QR_DIMM0
  - ANY_DIMM0
  - ANY_DIMM1
  - ANY_DIMM2
  - ANY_DIMM3
  - DR_DIMM1
  - QR_DIMM1
  
  These values can be combined as follows: QR_DIMM0 + ANY_DIMM1

**Description**

This macro specifies what kind of configuration that applies the override settings. Users are able to state multiple override macros with this configuration macro.

**Example**:

\[ \text{TBLDRV_CONFIG_TO_OVERRIDE (2, DDR1600, VOLT1_5_ + VOLT1_35_, SR_DIMM0 + DR_DIMM1)} \]
TBLDRV_CONFIG_ENTRY_RTTNOM (CS2_ + CS3_, 2),
TBLDRV_CONFIG_ENTRY_RTTWR (CS2_, 2),
TBLDRV_CONFIG_ENTRY_RTTWR (CS3_, 1),
TBLDRV_CONFIG_ENTRY_ADDRTMG (0x003C3C3C),
TBLDRV_CONFIG_ENTRY_ODCCTRL (0x20112222)

Dependencies

The override macros which can be associated with this configuration macro are:

TBLDRV_CONFIG_ENTRY_ODT_RTTNOM,
TBLDRV_CONFIG_ENTRY_ODT_RTTWR,
TBLDRV_CONFIG_ENTRY_ODTPATTERN,
TBLDRV_CONFIG_ENTRY_ADDRTMG,
TBLDRV_CONFIG_ENTRY_ODCCTRL,
TBLDRV_CONFIG_ENTRY_SLOWACCMODE,
TBLDRV_CONFIG_ENTRY_LRDMM_IBT,
TBLDRV_CONFIG_ENTRY_2D_TRAINING
**TBLDRV_SPEEDLIMIT_CONFIG_TO_OVERRIDE**

**Prototype**

\[
\text{TBLDRV\_SPEEDLIMIT\_CONFIG\_TO\_OVERRIDE} \text{ (DimmPerCH, Dimms, NumOfSR, NumOfDR, NumOfQR, NumOfLRDIMM)}
\]

**Parameters**

- **DimmPerCH**
  Number of DIMM slots in a channel.

- **Dimms**
  Number of DIMMs in a channel.

- **NumOfSR**
  Number of Single rank DIMMs in a channel

- **NumOfDR**
  Number of dual rank DIMMs in a channel

- **NumOfQR**
  Number of Quad rank DIMMs in a channel

- **NumOfLRDIMM**
  Number of LR-DIMMs (Load reduce DIMMs) in a channel

**Description**

This configuration macro is only used with memory speed limit override macro, it specifies what kind of configuration that applies the override.

NumOfLRDIMM should be stated as "NA_" in a normal DIMM type platform. NumOfSR, NumOfDR and NumOfQR should be stated as NA_ in a LR-DIMM type platform, vice versa.

Example:

\[
\text{TBLDRV\_SPEEDLIMIT\_CONFIG\_TO\_OVERRIDE} \text{ (2, 2, 0, 0, NA_),}
\text{TBLDRV\_CONFIG\_ENTRY\_SPEEDLIMIT} \text{ (DDR1600\_FREQUENCY,}
\text{ DDR1333\_FREQUENCY,}
\text{ DDR1066\_FREQUENCY)},
\]

**Dependencies**

Only TBLDRV\_CONFIG\_ENTRY\_SPEEDLIMIT override macro can be associated with this configuration macro.
**TBLDRV_RC2IBT_CONFIG_TO_OVERRIDE**

**Prototype**

\[
\text{TBLDRV_RC2IBT_CONFIG_TO_OVERRIDE (DimmPerCH, Frequency, DimmVolt, DimmConfig, NumOfReg)}
\]

**Parameters**

- **DimmPerCH**
  
  Number of DIMM slots in a channel.

- **Frequency**
  
  Mask of frequencies to apply change. Possible values are:
  
  - DDR400
  - DDR533
  - DDR667
  - DDR800
  - DDR1066

  These values can be combined as follows: DDR400 + DDR533 + DDR667

- **DimmVolt**
  
  Mask of voltage to apply change. Possible values are:
  
  - VOLT1_5
  - VOLT1_25
  - VOLT1_35
  - VOLT_ANY

  These values can be combined as follows: VOLT1_5 + VOLT1_35

- **DimmConfig**
  
  Mask indicating DIMM configuration. Possible values are:
  
  - ANY
  - SR_DIMM0
  - SR_DIMM1
  - SR_DIMM2
  - SR_DIMM3
  - DR_DIMM0
  - DR_DIMM1
  - DR_DIMM2

  These values can be combined as follows: QR_DIMM0 + ANY_DIMM1

**Description**

This configuration macro is only used with RC2IBT override macro, it specifies what kind of configuration that applies the override.
Example:

```
TBLDRV_RC2IBT_CONFIG_TO_OVERRIDE (2, DDR1600, VOLT1_5_ +
  VOLT1_35_ , SR_DIMM0 + DR_DIMM1, 2),
  TBLDRV_CONFIG_ENTRY_RC2_IBT (DIMM0, 4),
```

Dependencies

Only TBLDRV_CONFIG_ENTRY_RC2_IBT override macro can be associated with this configuration macro.
D.5.3.2 Override Macros

**TBLDRV_CONFIG_ENTRY_SPEEDLIMIT**

**Prototype**

TBLDRV_CONFIG_ENTRY_SPEEDLIMIT (SpeedLimit1_5, SpeedLimit1_35, SpeedLimit1_25)

**Parameters**

*SpeedLimit1_5*/SpeedLimit1_35*/SpeedLimit1_25*

Frequencies to apply change. Possible values are:

- DDR667_FREQUENCY
- DDR800_FREQUENCY
- DDR1066_FREQUENCY
- DDR1333_FREQUENCY
- DDR1600_FREQUENCY
- DDR1866_FREQUENCY
- DDR2100_FREQUENCY
- DDR2133_FREQUENCY
- DDR2400_FREQUENCY

**Description**

This macro specifies memory speed limit value for VDDIO 1.5V, 1.35V and 1.25 V.

**Dependencies**

This macro must be presented along with

TBLDRV_SPEEDLIMIT_CONFIG_TO_OVERRIDE configuration macro.
TBLDRV_CONFIG_ENTRY_ODT_RTTNOM

Prototype

TBLDRV_CONFIG_ENTRY_ODT_RTTNOM (TgtCS, RttNom)

Parameters

**TgtCS**

Mask indicating which chip selects are applied to RttNom value override. Possible values are:

<table>
<thead>
<tr>
<th>CS0_</th>
<th>CS3_</th>
<th>CS6_</th>
</tr>
</thead>
<tbody>
<tr>
<td>CS1_</td>
<td>CS4_</td>
<td>CS7_</td>
</tr>
<tr>
<td>CS2_</td>
<td>CS5_</td>
<td>CS_ANY</td>
</tr>
</tbody>
</table>

These values can be combined as follows: CS0_ + CS1_

**RttNom**

A 8 bits value indicating the nominal termination value. Possible values are:

<table>
<thead>
<tr>
<th>0</th>
<th>1</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Disabled</td>
<td>60 ohms</td>
<td>120 ohms</td>
</tr>
<tr>
<td>3-40 ohms</td>
<td>4-20 ohms</td>
<td>5-30 ohms</td>
</tr>
</tbody>
</table>

Description

This macro specifies the RttNom value override for specific chip selects.

Dependencies

This macro must be presented along with TBLDRV_CONFIG_TO_OVERRIDE configuration macro. And it is able to grouped together with other general override macros using same configuration macro.
TBLDRV_CONFIG_ENTRY_ODT_RTTWR

Prototype

TBLDRV_CONFIG_ENTRY_ODT_RTTWR (TgtCS, RttWr)

Parameters

TgtCS

Mask indicating which chip selects are applied to RttNom value override. Possible values are:

- CS0
- CS1
- CS2
- CS3
- CS4
- CS5
- CS6
- CS7
- CS_ANY

These values can be combined as follows: CS0 + CS1

RttWr

A 8 bits value indicating the write termination value. Possible values are:

- 0 - Disabled
- 1 - 60 ohms
- 2 - 120 ohms

Description

This macro specifies the RttWr value override for specific chip selects.

Dependencies

This macro must be presented along with TBLDRV_CONFIG_TO_OVERRIDE configuration macro. And it is able to grouped together with other general override macros using same configuration macro.
TBLLDRV_CONFIG_ENTRY_ODTPATTERN

Prototype

TBLLDRV_CONFIG_ENTRY_ODTPATTERN (RdODTCSHigh, RdODTCSLow, WrODTCSHigh, WrODTCSLow)

Parameters

- **RdODTCSHigh**
  A 32 bits value indicating read ODT pattern value for CS[7:4].

- **RdODTCSLow**
  A 32 bits value indicating read ODT pattern value for CS[3:0].

- **WrODTCSHigh**
  A 32 bits value indicating write ODT pattern value for CS[7:4].

- **WrODTCSLow**
  A 32 bits value indicating write ODT pattern value for CS[3:0].

Description

This macro specifies the read/write ODT pattern values to override.

Dependencies

This macro must be presented along with TBLLDRV_CONFIG_TO_OVERRIDE configuration macro. And it is able to grouped together with other general override macros using same configuration macro.
**TBLDRV_CONFIG_ENTRY_ADDRTMG**

**Prototype**

```c
TBLDRV_CONFIG_ENTRY_ADDRTMG (AddrTmg)
```

**Parameters**

- `AddrTmg`
  
  A 32 bits value indicating Address/Command Timing value.

**Description**

This macro specifies the Address/Command Timing value to override.

**Dependencies**

This macro must be presented along with TBLDRV_CONFIG_TO_OVERRIDE configuration macro. And it is able to grouped together with other general override macros using same configuration macro.
**TBLDRV_CONFIG_ENTRY_ODCCTRL**

**Prototype**

```
TBLDRV_CONFIG_ENTRY_ODCCTRL (OdcCtrl)
```

**Parameters**

*OdcCtrl*

A 32 bits value indicating Output Driver Compensation Control (driving strength) value.

**Description**

This macro specifies the Output Driver Compensation Control value to override.

**Dependencies**

This macro must be presented along with TBLDRV_CONFIG_TO_OVERRIDE configuration macro. And it is able to grouped together with other general override macros using same configuration macro.
TBLDRV_CONFIG_ENTRY_SLOWACCMODE

Prototype

TBLDRV_CONFIG_ENTRY_SLOWACCMODE (SlowAccMode)

Parameters

SlowAccMode

A 8 bits value indicating Slow Access Mode value.

Description

This macro specifies the Slow Access Mode value to override.

Dependencies

This macro must be presented along with TBLDRV_CONFIG_TO_OVERRIDE configuration macro. And it is able to grouped together with other general override macros using same configuration macro.
**TBLDRV_CONFIG_ENTRY_RC2_IBT**

**Prototype**

\[ \text{TBLDRV\_CONFIG\_ENTRY\_RC2\_IBT} \left( TgtDimm, \ IBT \right) \]

**Parameters**

- **\( TgtDimm \)**
  
  Mask indicating which DIMMs are applied to RC2 IBT value override. Possible values are:
  
  - DIMM0
  - DIMM1
  - DIMM2
  
  These values can be combined as follows: DIMM0 + DIMM1

- **\( IBT \)**
  
  A 8 bits value indicating IBT value to override

**Description**

This macro specifies the RDIMM IBT value to override.

**Dependencies**

This macro must be presented along with TBLDRV\_RC2IBT\_CONFIG\_TO\_OVERRIDE configuration macro.
**TBLDRV_OVERRIDE_MR0_CL**

**Prototype**

TBLDRV_OVERRIDE_MR0_CL (RegValOfTcl, MR0CL13, MR0CL0)

**Parameters**

*RegValOfTcl*

A 8 bits value indicating the value of Tcl bit field value in memory controller register.

*MR0CL13*

The encoding value of MR0 command CL[3:1] bit field.

*MR0CL0*

The encoding value of MR0 command CL[0] bit field.

**Description**

This macro does NOT need to combine with any configuration macro, it specifies the encoding value of MR0 command CL[3:0] bit field to override corresponding to the value of Tcl bit field in memory controller register. Multiple TBLDRV_OVERRIDE_MR0_CL macros are allowed to put together, they override the encoding value of MR0 command CL[3:0] bit field corresponding to various Tcl value in the register.
**TBLDRV_OVERRIDE_MR0_WR**

**Prototype**

```
TBLDRV_OVERRIDE_MR0_WR (RegValOfTwr, MR0WR)
```

**Parameters**

- **RegValOfTwr**
  
  A 8 bits value indicating the value of Twr bit field value in memory controller register.

- **MR0WR**
  
  The encoding value of MR0 command WR[2:0] bit field.

**Description**

This macro does NOT need to combine with any configuration macro, it specifies the encoding value of MR0 command WR[2:0] bit field to override corresponding to the value of Twr bit field in memory controller register. Multiple TBLDRV_OVERRIDE_MR0_WR macros are allowed to put together, they override the encoding value of MR0 command WR[2:0] bit field corresponding to various Twr value in the register.
TBLDRV_OVERRIDE_RC10_OPSPEED

Prototype

TBLDRV_OVERRIDE_RC10_OPSPEED (Frequency, RC10OPSPEED)

Parameters

Frequency

Mask of frequencies to apply change. Possible values are:

- DDR400
- DDR533
- DDR667
- DDR800
- DDR1066
- DDR1333
- DDR1600
- DDR1866
- ANY_SPEED

These values can be combined as follows: DDR400 + DDR533 + DDR667

RC10OPSPEED

The encoding value of RDIMM control word 10 [Operating Speed] bit field.

Description

This macro does NOT need to combine with any configuration macro and is for RDIMM memory type only, it specifies the encoding value of RDIMM RCW10 command [Operating Speed] bit field to override corresponding to memory frequency. Multiple TBLDRV_OVERRIDE_RC10_OPSPEED macros are allowed to put together, they override the encoding value of RDIMM RCW10 command [Operating Speed] bit field corresponding to various memory frequencies.
**TBLDRV_CONFIG_ENTRY_LRDMM_IBT**

**Prototype**

\[ \text{TBLDRV_CONFIG_ENTRY_LRDMM_IBT (F0RC8, F1RC0, F1RC1, F1RC2)} \]

**Parameters**

- **F0RC8**
  
  A 8 bits value indicating LRDIMM function 0 control word 8 value.

- **F1RC0**
  
  A 8 bits value indicating LRDIMM function 1 control word 0 value.

- **F1RC1**
  
  A 8 bits value indicating LRDIMM function 1 control word 1 value.

- **F1RC2**
  
  A 8 bits value indicating LRDIMM function 0 control word 2 value.

**Description**

This macro specifies LRDIMM IBT values to override.

**Dependencies**

This macro must be presented along with TBLDRV_CONFIG_TO OVERRIDE configuration macro. And it is able to grouped together with other general override macros using same configuration macro.
TBLDRV_CONFIG_ENTRY_2D_TRAINING

Prototype

TBLDRV_CONFIG_ENTRY_2D_TRAINING (Training2dMode)

Parameters

Training2dMode

Indicating the enablement of memory 2D training function.

1 - Enable
2 - Disable

Description

This macro is used to force either enable or disable memory 2D training function.

Dependencies

This macro must be presented along with TBLDRV_CONFIG_TO OVERRIDE configuration macro. And it is able to grouped together with other general override macros using same configuration macro.
**TBLDRV_INVALID_CONFIG**

**Prototype**

```c
TBLDRV_INVALID_CONFIG
```

**Parameters**

```c
<none>
```

**Description**

This macro specifies an invalid configuration. And, the configuration is stated in one of existing configuration macros.

**Dependencies**

This macro must be associated with TBLDRV_CONFIG_TO_OVERRIDE, TBLDRV_SPEEDLIMIT_CONFIG_TO_OVERRIDE or TBLDRV_RC2IBT_CONFIG_TO_OVERRIDE configuration macro.
Appendix E  Graphics Northbridge Details

Refer to the internal documentation for the latest and most detailed information ("Internal Documentation" on page 26).

**E.1  PCIe® Port Descriptor List**

These structures provide customization of the processor’s PCIe® ports. See processor specific documentation for a description of what PCIe® support, if any, exists on that processor.

Customization data is provided by lists of descriptors. The list is terminated by an item which has DESCRIPTOR_TERMINATE_LIST as its Flags value.

```c
typedef struct {
    IN       UINT32               Flags;
    IN       PCIe_ENGINE_DATA     EngineData;
    IN       PCIe_PORT_DATA       Port;
} PCIe_PORT_DESCRIPTOR;
```

**Flags**

DESCRIPTOR_TERMINATE_LIST - This is the last descriptor in the list.

**Engine Data**

See “PCIe® Engine Data” on page 354.

**Port**

Provide customization settings for this PCIe® port.

```c
typedef struct {
    IN       UINT8                   PortPresent;
    IN       UINT8                   ChannelType;
    IN       UINT8                   DeviceNumber;
    IN       UINT8                   FunctionNumber;
    IN       UINT8                   LinkSpeedCapability;
    IN       UINT8                   LinkAspm;
    IN       UINT8                   LinkHotplug;
    IN       UINT8                   ResetId;
    IN       PCIe_PORT_MISC_CONTROL MiscControls;
    IN       APIC_DEVICE_INFO       ApicDeviceInfo;
    IN       PCIe_ENDPOINT_STATUS   EndPointStatus;
    IN       RX_ADAPT_MODE         RxAdaptMode;
} PCIe_PORT_DATA;
```

**PortPresent**

Specifies the port is enabled. This is specified using the PCIe_PORT_ENABLE enum.

PortDisabled - Disabled
PortEnabled - Enabled

**ChannelType**

Specifies the type of channel. This is specified using the PCIE_CHANNEL_TYPE enum.

- ChannelTypeLowLoss - Low Loss
- ChannelTypeHighLoss - High Loss
- ChannelTypeMob0db - Mobile 0dB
- ChannelTypeMob3db - Mobile 3dB
- ChannelTypeExt6db - Extended 6dB
- ChannelTypeExt8db - Extended 8dB

**DeviceNumber**

Specifies the PCI device number for this port.

- 0 - Use native port device number
- N - Use this port device number. See processor specific documentation for details.

**FunctionNumber**

Reserved.

**LinkSpeedCapability**

Specifies the link’s speed and feature capabilities. This is specified using the PCIE_LINK_SPEED_CAP enum.

- PcieGenMaxSupported - The maximum speed and feature set is supported.
- PcieGen1 - Gen 1 speeds and features are supported.
- PcieGen2 - Gen 2 speeds and features are supported.
- PcieGen3 - Gen 3 speeds and features are supported.

**LinkAspm**

Specifies the link’s ASPM control. This is specified using the PCIE_ASPM_TYPE enum.

- AspmDisabled - ASPM is disabled.
- AspmL0s - support for the L0s PCIe link state.
- AspmL1 - support for the L1 PCIe link state.
- AspmL0sL1 - support for both the L0s and L1 PCIe link state.

**LinkHotplug**

Specifies the link’s hot plug support. This is specified using the PCIE_HOTPLUG_TYPE enum.

- HotplugDisabled - Hot plug is disabled.
- HotplugBasic - Basic hot plug is supported.
- HotplugServer - Server hot plug is supported.
HotplugEnhanced - Enhanced hot plug is supported.
HotplugInboard - In board hot plug is supported.

ResetId
Specify the ID which will be passed to the AgesaPcieSlotResetContol callout to reset this port. This generally corresponds to the GPIO which will be used by the host BIOS to control this port’s reset. Ports may share a reset ID, if they are controlled together by the platform.

MiscControls
Miscellaneous other controls for port test and debug.

ApicDeviceInfo
IOAPIC device and interrupt programming information.

EndPointStatus
Provides additional status information about the end point device.

**EndpointDetect** - Indicates that AGESA should attempt to detect endpoint presence

**EndpointNoPresent** - Indicates that there is an alternative way to determine if the endpoint is present or not (such as a GPIO) and that method has indicated that there is no device present. AGESA will not attempt to detect a device in this port

RxAdaptMode
Defines the default configuration for RxAdaptMode used for Gen3 PCIe configuration. This parameter structure generally applies only to Gen3 capable slots and devices.

typedef struct {
    IN UINT8 GroupMap;
    IN UINT8 Swizzle;
    IN UINT8 BridgeInit;
} APIC_DEVICE_INFO;

GroupMap
The four virtual PCIe® interrupts, INTx, may be mapped to a group of four entries in the redirection table.

0 - Use the recommended settings (default). The other members of this structure will be ignored.

1 - Interrupts are mapped to Group 0 which is interrupts 0 through 3 of the redirection table.

2 - Interrupts are mapped to Group 1 which is interrupts 4 through 7 of the redirection table.
3 - Interrupts are mapped to Group 2 which is interrupts 8 through 11 of the redirection table.
4 - Interrupts are mapped to Group 3 which is interrupts 12 through 15 of the redirection table.
5 - Interrupts are mapped to Group 4 which is interrupts 16 through 19 of the redirection table.
6 - Interrupts are mapped to Group 5 which is interrupts 20 through 23 of the redirection table.
7 - Interrupts are mapped to Group 6 which is interrupts 24 through 27 of the redirection table.
8 - Interrupts are mapped to Group 7 which is interrupts 28 through 31 of the redirection table.

Swizzle

Within the interrupt group, the virtual PCIe® interrupts, INTx, may be swizzled.

0 - Use swizzle ABCD (for example, if the group is 1 then INTA is level 0, INTB is level 1, INTC is level 2, and INTD is level 3).
1 - Use swizzle BCDA.
2 - Use swizzle CDAB.
3 - Use swizzle DABC.

BridgeInt

The PCIe® bridge will use this interrupt level for the bridge Message Signalled Interrupt (MSI). Specify an available interrupt level in the redirection table, from 0 to 31.

typedef struct {
  IN BOOLEAN InitOffsetCancellation;
  IN UINT8 DFEControl;
  IN UINT8 LEQControl;
  IN BOOLEAN DynamicOffsetCalibration;
  IN BOOLEAN FOMCalculation;
  IN BOOLEAN PIOffsetCalibration;
} RX_ADAPT_MODE;

See the enum definition in the AGESA.H file for permitted values.

InitOffsetCancellation

Defines whether Initial Offset calibration will be enabled or not.

DFEControl

Defines the configuration of the LEQ Control.

DynamicOffsetCalibration
Defines whether Dynamic Offset Calibration is enabled or not.

*FOMCalculation*

Defines whether FOM Calculation will be enabled or not.

*PIOffsetCalibration*

Defines whether PI Offset Calibration will be enabled or not.

### E.2 DDI Link Descriptor List

These structures provide customization of the processor’s DDI ports. See processor specific documentation for a description of what DDI support, if any, exists on that processor.

Customization data is provided by lists of descriptors. The list is terminated by an item which has DESCRIPTOR_TERMINATE_LIST as its Flags value.

```c
typedef struct {
    IN       UINT32               Flags;
    IN       PCIe_ENGINE_DATA     EngineData;
    IN       PCIe_DDI_DATA        Ddi;
} PCIe_DDI_DESCRIPTOR;
```

**Flags**

DESCRIPTOR_TERMINATE_LIST - This is the last descriptor in the list.

**Engine Data**

See “PCIe® Engine Data” on page 354.

**Ddi**

Provide customization settings for this Ddi port.

```c
typedef struct  {
    IN UINT8 ConnectorType;
    IN UINT8 AuxIndex;
    IN UINT8 HdpIndex;
    IN CONN_CHANNEL_MAPPING Mapping[2];
    IN UINT8 LanePnInvert;
    IN UINT8 Flags;
} PCIe_DDI_DATA;
```
ConnectorType

Specifies the display connector type. Connector types are provided by the PCIE_CONNECTOR_TYPE enum.

ConnectorTypeDP - DP
ConnectorTypeEDP - eDP
ConnectorTypeSingleLinkDVI - Single Link DVI
ConnectorTypeDualLinkDVI - Dual Link DVI
ConnectorTypeHDMI - HDMI™
ConnectorTypeDpToVga - Travis DP to VGA
ConnectorTypeDpToLvds - Travis DP to LVDS
ConnectorTypeNutmegDpToVga - Nutmeg DP to VGA
ConnectorTypeSingleLinkDviI - Single Link DVI-I
ConnectorTypeCrt - Native CRT
ConnectorTypeLvds - Native LVDS
ConnectorTypeEDPToLvds - common eDP to LVDS
ConnectorTypeEDPToLvdsSwInit - eDP to LVDS, with specific software initialization steps.
ConnectorTypeAutoDetect - Provides automatic detection for EDID display panels when connected via Native LVDS, eDP, or Travis DP to LVDS.

AuxIndex

Specifies the AUX line used. AUX lines are specified using the PCIE_AUX_TYPE enum: AUX1, AUX2, AUX 3, AUX, AUX5, and AUX6.

HdpIndex

Specifies the HDP pin for this port. HDP pins are specified using the PCIE_HDP_TYPE enum: HDP1, HDP2, HDP3, HDP4, HDP5, and HDP6.

Mapping

Specifies the mapping of lanes to connector pins. Mapping [0] defines the mapping for the four lanes beginning at PCIe_ENGINE_DATA.StartLane. Mapping [1] defines the mapping for the four lanes ending at PCIe_ENGINE_DATA.EndLane. Lane mapping values are:

0 - Map to lane 0.
1 - Map to lane 1.
2 - Map to lane 2.
3 - Map to lane 3.

LanePnInvert

Specifies whether to invert the state of P and N for each lane.

0 - Do not invert (default).
1 - Invert P and N on this lane.
Flags

Specifies capability flags for the DDI link. By default, no special capability limits are assumed. Each flag can be used to limit that capability.

DDI_DATA_FLAGS_DP1_1_ONLY - Limit the link to DP 1.1 capable.
EXT_DISPL PATH_CAPS_DP_REPEATER - Apply special settings for certain hardware implementations.
EXT_DISPL PATH_CAPS_DP_FIXED_VS_EN - VBIOS will always output fixed voltage swing during DP link training
EXT_DISPL PATH_CAPS_HDMI20_PI3EQX1204 – See note below
EXT_DISPL PATH_CAPS_HDMI20_TISN65DP159RSBT – See note below

Note: HDMI 2.0 PLL design uses re-timer(TI SN65DP159RSBT)/re-driver (PI3EQX1204) chips between APU and connector for signal conditioning. VBIOS supports two independent solutions, either can be used. These flags indicate the solution (if any) implemented by the platform.

E.3 PCIe® Engine Data

This structure is used for configuring both PCIe® and DDI ports.

```c
typedef struct {
    IN UINT8 EngineType;
    IN UINT16 StartLane;
    IN UINT16 EndLane;
} PCr_Engine_DATA;
```

**EngineType**

Indicates the port type which this customizes.

0 - Ignore this item
1 - PCIe® Port
2 - DDI Port

**StartLane**

The starting Lane ID for this port. Normally, that is the lowest Lane ID, but it can be the highest Lane ID when the lanes are reversed. See processor specific documentation for details.

**EndLane**

The ending Lane ID for this port. Normally that is the highest Lane ID, but it can be the lowest Lane ID when the lanes are reversed. See processor specific documentation for details.
E.4 IOMMU Exclusion Range Descriptor

Platform BIOS may provide IOMMU exclusion ranges for I/O virtualization as follows.

```c
typedef struct {
    IN       UINT16     Bus       :8;
    IN       UINT16     Device    :5;
    IN       UINT16     Function  :3;
} IOMMU_REQUESTOR_ID;

typedef struct {
    IN       UINT32               Flags;
    IN       IOMMU_REQUESTOR_ID   RequestorIdStart;
    IN       IOMMU_REQUESTOR_ID   RequestorIdEnd;
    IN       UINT64               RangeBaseAddress;
    IN       UINT64               RangeLength;
} IOMMU_EXCLUSION_RANGE_DESCRIPTOR;
```

**Flags**

This descriptor may be ignored or may terminate the list.

**RequestorIdStart**

The exclusion range is requested for the inclusive device set beginning with the requestor start ID.

**RequestorIdEnd**

The end of the requestor ID range.

**RangeBaseAddress**

The allocate the exclusion range beginning at this physical address.

**RangeLength**

The length of the exclusion region in bytes.

E.5 ACPI ASL Library

Platform BIOS may include ACPI ASL methods for providing run-time features, for example, PCIe® Speed Power Policy (PSPP) or PCIe® hot plug. The ACPI ASL library provides support for these platform BIOS ACPI ASL methods by providing a library of supporting ASL methods which can be invoked by the platform BIOS ASL code.

Use of the ACPI ASL Library requires that PCIe® MMIO base address and size are configured. See “BLDCFG_PCI_MMIO_BASE” on page 189 and “BLDCFG_PCI_MMIO_SIZE” on page 189.

When using the ACPI ASL Library, the following names should be considered reserved in \\_SB scope: ALIB; ADxx, where xx is 00 - 99; Ayyy, where yyy is 000 - 999.
ACPI ASL Library support is invoked using the ALIB method. This method is in \_SB scope and provides multiple services as indicated by a function code.

\textbf{ALIB (Arg0, Arg1)}

- \textit{Arg0} Provide the desired function code. Valid function codes are specified below.

- \textit{Arg1} A parameter buffer which provides inputs to the method and contains outputs from the method. The inputs and outputs are specific to each function. The buffer is 256 bytes.

These are the supported functions. For each function, the Arg1 buffer parameters are described for input and output.

**Report AC/DC State - Function 1.**

The Platform BIOS should Report AC/DC State to report boot up power source as AC or DC. This function could be performed from \_SB.PCI0._INI or from \_SB._INI, for example.

**Input:**

\textbf{WORD Size}

\textbf{BYTE AC/DC State}

- \textit{Size} The size in bytes, 3.

- \textit{AC/DC State} Indicate the current power source type.
  
  0 - Current state is AC power.
  
  1 - Current state is DC power.

**Output:** None.

**PCIe® Performance Request - Function 2.**

Register a specific performance request for a specific client PCIe® device, or remove the previous request.

**Input:**

\textbf{WORD Size}

\textbf{WORD Client ID}

\textbf{WORD Valid Flags}

\textbf{WORD Flags}

\textbf{BYTE Request Type}

\textbf{BYTE Performance Request}

- \textit{Size}
The size in bytes, 10.

**Client ID**

Provides client device PCI config address, Bus in bits [15:8], Device in bits [7:3], and Function in bits [2:0].

**Valid Flags**

Indicates which bits in Flags are valid. For each bit:

0 - Flag bit is not valid.
1 - Flag bit is valid.

**Flags**

bit 0 - Advertise capabilities.
bit 1 - Wait for completion.
bits [31:2] - Reserved, must be zero.

**Request Type**

Specifies how to interpret the performance level in Performance Request.

1 - PCIe® Link Speed

**Performance Request**

0 - Remove request.
1 - Force low power mode.
2 - Performance level 1 (PCIe® Gen1 speed).
3 - Performance level 2 (PCIe® Gen2 speed).
4 - Performance level 3 (PCIe® Gen3 speed).

**Output:**

<table>
<thead>
<tr>
<th>WORD Size</th>
<th>Byte Return Value</th>
</tr>
</thead>
</table>

**Size**

The size in bytes, 3.

**Return Value**

1 - Request refused.
2 - Request complete.
3 - Request in progress.

**PSPP Start/Stop Management Request - Function 3.**

Start, or stop, PSPP policy management.

**Input:**

| WORD Size |
BYTE Policy

Size

The size in bytes, 3.

Policy

0 - Stop PSPP policy management.
1 - Start PSPP policy management.

Output:

WORD Size
BYTE Status

Size

The size in bytes, 3.

Status

0 - Request completed successfully.
1 - Request unsupported.
5 - Request error, AGESA_ERROR severity.

Set PCIe® Bus Width - Function 4.

Set or reset power gating based on the number of requested PCIe® lanes.

Input:

WORD Size
WORD Client ID
BYTE Lanes

Size

The size in bytes, 5.

Client ID

Provides client device PCI config address, Bus in bits [15:8], Device in bits [7:3], and Function in bits [2:0].

Lanes

Specifies the number of lanes to be active.

Output:

WORD Size
BYTE Lanes

Size

The size in bytes, 3.

Lanes
The number of active lanes. May be more or less than the number requested.

**ALIB Init - Function 5.**

Initialize the ACPI ASL library. Recommend this is called from \_SB.PCI0._INI.

Inputs: None.

Outputs: None.

**PCle® Port Hot Plug Request - Function 6.**

Handle device insert and eject for a specific PCIe® port. This should be called from the SCI handler for the “PRSNT#” signal on the PCIe® port.

Input:

- WORD Size
- WORD Port ID
- BYTE State

**Size**

The size in bytes, 5.

**Port ID**

Provides port device PCI config address, Bus in bits [15:8], Device in bits [7:3], and Function in bits [2:0].

**State**

0 - Handle device eject.
1 - Handle device insert.

Output:

- WORD Size
- BYTE Status
- BYTE Device Status

**Size**

The size in bytes, 4.

**Status**

0 - Request completed successfully.
1 - Request unsupported.
5 - Request error, AGESA_ERROR severity.

**Device Status**

0 - Device not present.
1 - Device present.
Report Dock/Undock State - Function A

The Platform BIOS should Report Dock/Undock State to report attachment to a dock that provides supplemental cooling or thermal capabilities. This function could be performed from \_SB.PCI0._INI or from \_SB._INI, for example. This function is independent of the AC/DC function.

Input:

WORD Size
BYTE Dock/Undock State

*Size* -

The size in bytes.

*Dock/Undock State* -

Indicate the current power source type.

0 - Current state is docked

1 - Current state is not docked

Output: None.

Report Battery Status - Function B

The Platform BIOS should report battery status information for management of power and performance states while operating in DC mode. This information should be reported periodically as the battery status is measured by the system and should be reported independently for each battery in the system.

Input:

WORD Size
BYTE Battery ID
BYTE Power Unit
DWORD Battery Total Capacity
DWORD Battery Remaining Capacity
DWORD Battery Voltage

*Size* -

The size in bytes, 16

*Battery ID* -

The ID of the battery being reported

*Power Unit* -

Indicates the current power source type.

0 – Battery capacity is in mAh

1 – Battery capacity is in mWh
**Battery Total Capacity** -  
Indicates the total capacity of the battery when fully charged, in the units specified by Power Unit. This should match the last reported value by the ACPI BIF object.

**Battery Remaining Capacity** -  
Indicates the remaining capacity of the battery, in the units specified by Power Unit.

**Battery Voltage** -  
Indicates the voltage currently provided by the battery, in mV. For systems reporting the remaining capacity in mAh the voltage is used to calculate the battery capacity in mWh units.

Output: None.

---

**Dynamic Power and Thermal Configuration Interface - Function C**

DPTCi is a feature available on Family15h Model 60h and newer processors. This function provides platform BIOS the capability to dynamically change the operating parameters for a subset of power and thermal management features. This allows the platform BIOS to adjust parameters based on any platform status change rather than limiting it to specific functions (such as AC/DC or docked/undocked). The interface allows for single or multiple parameters to be passed in a single ALIB call.

**Input:**

- **WORD Size**
- **BYTE Parameter ID**
- **DWORD Power or thermal parameter**
  - [  
    **BYTE Parameter ID**
    **DWORD Power or Thermal Parameter**
    …]

**Size**

The size in bytes, $2 + (5 \times \text{number of parameters passed})$

**Parameter ID**

Indicates the type of the parameter passed

- 0 – cTDP Value
- 1 – STAPM Time Constant
- 2 – Skin Control Scalar
- 3 – Thermal Control Limit

---

1. This function is Family Specific
Power or Thermal Parameter

Indicates the new value for the identified parameter

**cTDP Value** - Specifies the new value for configurable TDP. This value is a 32-bit floating point value.

**STAPM Time Constant** - The TimeConstant is a time in seconds. Passing in 200 will indicate the heat up time constant is 200 seconds. This value is a 32-bit floating point value. This value is a 32-bit floating point value.

**Skin Control Scalar** - The limit scalar will come from CBS or BLDCFG and is represented in a % (100 being the default). Passing in 110 to the argument will increase the TSP power limit by 10%. This value is a 32-bit floating point value.

**Thermal Control Limit** - This specifies the die temperature limit, on the Tctl temperature scale, to which the processor manages activity. The processor controls the activity level that contributes to power consumption, such as P-states and DPM-states, such that the die temperature remains within this limit. Reducing this value is a way to address chassis skin temperature issues. It is recommended that this value be set at least 5C below the HTC temperature limit. This value is a 32-bit floating point value. This value is a 32-bit floating point value.

---

**E.5.1 Optional ACPI Callout Method**

The ACPI ASL Library provides for calling an optional ACPI ASL method to control PCIe® slot reset during hot plug. The platform BIOS should implement this method in order to support PCIe® hot plug. To implement the method, define:

```
\_SB.ALIC (Arg0, Arg1)
```

*Arg0*  
The Bus, Device, Function of the slot’s PCI address.  
Function in bits 2:0  
Device in bits 7:3  
Bus in bits 15:8

*Arg1*  
Indicates whether to assert or de-assert reset to the slot.  
0 - Assert reset.  
1 - De-assert reset.
E.5.2 AWAK and APTS Methods

The ACPI ASL library provides methods to assist the _WAK and _PTS ACPI control methods in waking the system or preparing the system to sleep.

AWAK (Arg0)

Arg0

An integer indicating the sleep state from which the system is waking. This should be the same value passed to the _WAK method. The S1 sleep state is represented as 1, S2 as 2, etc.

AWAK is a method which provides processor specific configuration after the system wakes from a sleep state. The host environment should invoke AWAK from its _WAK method. AWAK does not return a value.

APTS (Arg0)

Arg0

An integer indicating the sleep state to which the system is preparing to enter. This should be the same value passed to the _PTS method. The S1 sleep state is represented as 1, S2 as 2, etc.

APTS is a method which provides processor specific configuration as the system prepares to enter a sleep state. The host environment should invoke APTS from its _PTS method. APTS does not return a value.